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Foreword

This final draft European Telecommunication Standard (ETS) has been produced by the Business Telecommunications (BTC) Technical Committee of the European Telecommunications Standards Institute (ETSI), and is now submitted for the Voting phase of the ETSI standards approval procedure.

This final draft ETS resulted from a mandate from the Commission of the European Community (CEC) to provide harmonized standards for the support of the Directive on Open Network Provision (ONP) of leased lines (92/44/EEC).

There are two other standards directly related to this ETS:

- pETS 300 686: "Business Telecommunications (BTC); 34 Mbit/s and 140 Mbit/s digital leased lines (D34U, D34S, D140U and D140S); Network interface presentation";
- ETS 300 688: "Business Telecommunications (BTC); 140 Mbit/s digital leased lines (D140U and D140S); Connection characteristics".

Proposed transposition dates	
Date of latest announcement of this ETS (doa):	3 months after ETSI publication
Date of latest publication of new National Standard or endorsement of this ETS (dop/e):	6 months after doa
Date of withdrawal of any conflicting National Standard (dow):	6 months after doa

This ETS is based on information from ITU-T Recommendations and ETSI publications and the relevant documents are quoted where appropriate.

Introduction

The Council Directive on the application of ONP to leased lines (92/44/EEC) concerns the harmonisation of conditions for open and efficient access to, and use of, the leased lines provided over public telecommunications networks, and the availability throughout the European Union of a minimum set of leased lines with harmonized technical characteristics.

The 140 Mbit/s unstructured and structured leased lines are not part of the minimum set of leased lines under the leased line Directive, however these standards are being written with the intention that where 140 Mbit/s leased lines are offered, they will be in accordance with these harmonized standards.

Two classes of standard will be used for the interfaces of terminal equipment designed for connection to the ONP leased lines. European Telecommunication Standards (ETSS), which are voluntary, give the full technical specifications for these interfaces, whereas Technical Basis for Regulations (TBRs) give the essential requirements under the Second Phase Directive (91/263/EEC) for attachment to the leased lines. The TBR (TBR 25) will be a subset of the corresponding ETS. This standard, which is an ETS, belongs to the first category.

ETS 300 166 and ITU-T Recommendation G.703 are used as the basis for the terminal equipment interface.

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1 Scope

This ETS specifies the full mechanical and electrical characteristics, the necessary functional characteristics and the corresponding conformance tests for a terminal equipment interface for:

- connection to the network termination points of 139 264 kbit/s digital unstructured leased lines (D140U); and
- connection to the network termination points of 139 264 kbit/s digital structured leased lines (D140S) which support an unstructured 138 240 kbit/s information transfer rate.

These leased lines are defined in ETS 300 686 and ETS 300 688.

This ETS is not written for regulatory purposes.

This ETS is written only to ensure that the interface of the terminal equipment is compatible with the 140 Mbit/s digital unstructured or structured leased lines. This ETS is applicable to all interfaces designed for connection to the leased line, however in the cases of apparatus that carries a particular service, of complex apparatus and of apparatus in private networks, other ETSs may apply in addition to this ETS.

Customer premises wiring and installation between the terminal equipment and the NTP are outside the scope of this ETS.

2 Normative references

This ETS incorporates by dated or undated reference, provisions from other publications. These normative references are cited at the appropriate places in the text and the publications are listed hereafter. For dated references, subsequent amendments to, or revisions of any of these publications apply to this ETS only when incorporated into it by amendment or revision. For undated references the latest edition of the publication referred to applies.

- [1] EN 60950 (1992): "Safety of information technology equipment including electrical business equipment".
- [2] IEC 169-8:1978: "Radio frequency connectors; Part 8: R.F coaxial connectors with inner diameters of outer conductor 6,5 mm (0,256 in) with bayonet lock - Characteristic impedance 50 ohms (Type BNC)".
- [3] IEC 169-13 (1976): "Radio frequency connectors; Part 13: R.F. coaxial connectors with inner diameter of outer conductor 5,6 mm (0,22 in) - Characteristic impedance 75 ohms (Type 1,6/5,6) - Characteristic impedance 50 ohms (Type 1,8/5,6) with similar mating dimensions".
- [4] ISO/IEC 10173 (1991): "Information technology - Integrated Services Digital Network (ISDN) primary access connector at reference points S and T".
- [5] ITU-T Recommendation G.703 (1991): "Physical/electrical characteristics of hierarchical digital interfaces".
- [6] ITU-T Recommendation O.151 (1992): "Error performance measuring equipment for digital systems at the primary rate and above".
- [7] ITU-T Recommendation O.171 (1992): "Timing jitter measuring equipment for digital systems".

NOTE: This ETS also contains a number of informative references which have been included to indicate the sources from which various material has been derived, hence they do not have an associated normative reference number. Details of these publications are given in annex E. In some cases the same publication may have been referenced in both a normative and an informative manner.

3 Definitions and abbreviations

For the purposes of this ETS, the following definitions apply:

3.1 Definitions

frame: A repetitive set of consecutive bits in which the position of each bit can be identified by reference to a frame alignment signal.

frame alignment signal: The distinctive signal inserted in every frame always occupying the same relative position within the frame and used to establish and maintain frame alignment.

leased lines: The telecommunications facilities provided by a public telecommunications network that provide defined transmission characteristics between network termination points and that do not include switching functions that the user can control, (e.g. on-demand switching).

Network Termination Point (NTP): All physical connections and their technical access specifications which form part of the public telecommunications network and are necessary for access to and efficient communication through that public network.

PRBS(2²³-1): A Pseudo Random Bit Sequence (PRBS) (as defined in subclause 2.2 of ITU-T Recommendation O.151 [6]).

Safety Extra-Low Voltage (SELV) circuit: A secondary circuit which is so designed and protected that under normal and single fault conditions, the voltage between any two accessible parts and, for class 1 equipment, between any accessible part and the equipment protective earthing terminal does not exceed a safe value (subclause 1.2.8.5 of EN 60950 [1]).

terminal equipment: Equipment intended to be connected to the public telecommunications network, i.e.:

- to be connected directly to the termination of a public telecommunication network; or
- to interwork with a public telecommunications network being connected directly or indirectly to the termination of a public telecommunications network,

in order to send, process, or receive information.

3.2 Abbreviations

For the purposes of this ETS, the following abbreviations apply:

AIS	Alarm indication Signal
ASCII	American Standard Code for Information Interchange
ATM	Asynchronous Transfer Mode
BIP-8	Bit Interleaved Parity (9 bit)
BNC	Bayonet Nut Connector
CMI	Coded Mark Inversion
CRC-7	Cyclic Redundancy Check (9 bit)
D140S	140 Mbit/s digital structured leased line
D140U	140 Mbit/s digital unstructured leased line
EM	Error Monitoring
EMC	ElectroMagnetic Compatibility
ETS-RT	ETS Requirements Table
FA1	Frame Alignment byte 1
FA2	Frame Alignment byte 2
GC	General purpose Communications channel
LOF	Loss Of Frame
LOS	Loss Of Signal
LSB	Least Significant Bit
MA	Maintenance and Adaptation
MSB	Most Significant Bit
NR	Network operator byte

NTP	Network Termination Point
ONP	Open Network Provision
ppm	parts per million
PRBS	Pseudo Random Bit Sequence
RDI	Remote Defect Indication
REI	Remote Error Indication
RX	RX is a signal input (at either the terminal equipment or the test equipment, see figure 1)
SDH	Synchronous Digital Hierarchy
SELV	Safety Extra-Low Voltage
TM	Timing Marker
TR	TRail trace
TTI	Trail Trace Identifier
TU	Tributary Unit
TUG	Tributary Unit Group
TX	TX is a signal output (at either the terminal equipment or the test equipment, see figure 1)
UI	Unit Interval

4 Requirements

The D140U 139 264 kbit/s unstructured leased line provides a bi-directional point-to-point digital leased line for the support of an unstructured 139 264 kbit/s information transfer rate. Any structuring of the data is the responsibility of the user.

The D140S 139 264 kbit/s structured leased line provides a bi-directional point-to-point digital leased line for the support of an unstructured 138 240 kbit/s information transfer rate. Any structuring of the data within the transparent 138 240 kbit/s part of the frame is the responsibility of the user.

For both D140U and D140S the provision of timing is the responsibility of the user; however, in certain installations the leased line provider may be able to offer a leased line that is synchronised to the network.

4.1 Mechanical characteristics

The terminal equipment shall provide at least one of the methods of connection given in subclauses 4.1.1 and 4.1.2.

NOTE 1: When connecting the terminal equipment to the NTP, any difference in ground potential between the two equipments may produce a voltage across the signal ground connection and may cause damage. See DEN/EE-02004 for details of earthing requirements within the customer's premises.

NOTE 2: The transmit pair is the output from the terminal equipment interface. The receive pair is the input to the terminal equipment interface, as shown in figure 1. Where the terms "output" and "input" are used without qualification in this ETS, they refer to the terminal equipment interface.

NOTE 3: Normal practice is for the outer conductors of the input and output connectors to be connected via a dc path to the signal ground and thence to ground. This connection is to reduce EMC emissions. If there is a difference in ground potential between the terminal equipment and the NTP, this arrangement may result in high currents in the outer conductors and cause damage.

To prevent this problem, dc isolation may be introduced between the terminal equipment and the NTP, for example by introducing dc isolation between the outer conductor and the signal ground in the terminal equipment. Careful attention should be given to the requirements of standards on installation earthing practice.

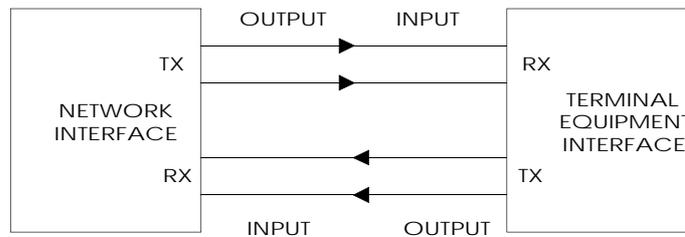


Figure 1

4.1.1 Sockets

Requirement: The terminal equipment interface shall provide two coaxial 75 Ω sockets, one each for transmit and receive; these sockets being either:

- a) 75 Ω sockets (type 1,6/5,6) complying with IEC 169-13 [3]; or
- b) 75 Ω BNC sockets complying with the general requirements of IEC 169-8 [2] with the mating dimensions specified in annex B of ISO/IEC 10173 [4].

The outer conductor of the coaxial pair shall be connected to signal ground both at the input port and at the output port.

Test: There shall be a visual inspection that the sockets are of the correct type.

4.1.2 Plugs

Requirement: The terminal equipment interface shall provide two coaxial 75 Ω plugs at the end of a cord (or cords), one each for transmit and receive; these plugs being either:

- a) 75 Ω plugs (type 1,6/5,6) complying with IEC 169-13 [3]; or
- b) 75 Ω BNC plugs complying with the general requirements of IEC 169-8 [2] with the mating dimensions specified in annex B of ISO/IEC 10173 [4].

The outer conductor of the coaxial pair shall be connected to signal ground both at the input port and at the output port.

NOTE: There is no requirement on the method of connection of the cord (or cords) to the terminal equipment.

Test: There shall be a visual inspection that the plugs are of the correct type.

4.2 Electrical characteristics

4.2.1 Output port

4.2.1.1 Signal coding

Requirement: The signal transmitted at the output port shall comply with the Coded Mark Inversion (CMI) encoding rules (see annex B).

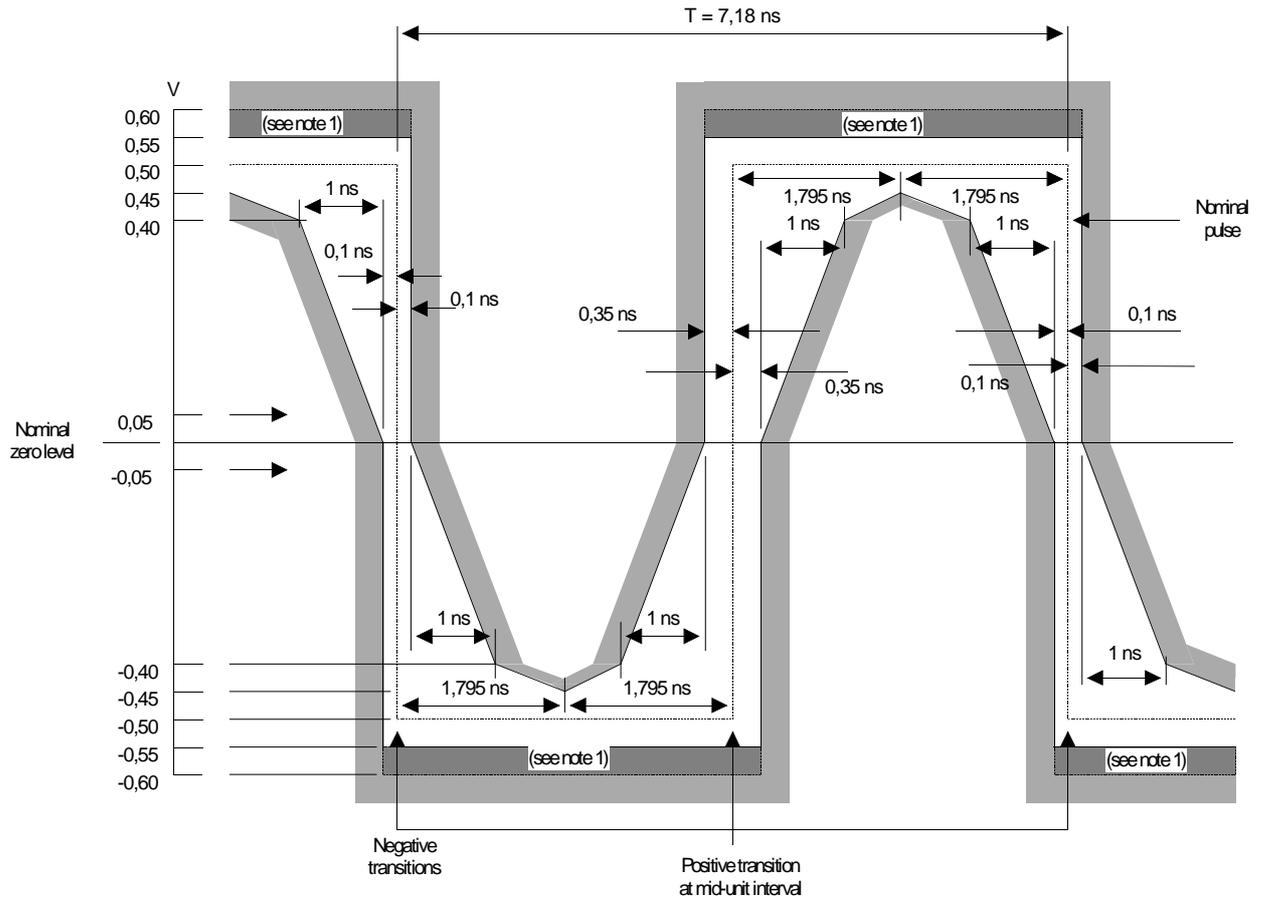
Test: The test shall be conducted according to subclause A.2.1.

4.2.1.2 Waveform shape

Requirement: The pulse at the output port shall comply with the requirements given in figures 2 and 3 and table 1; based on ITU-T Recommendation G.703.

Table 1: Waveform shape at output port

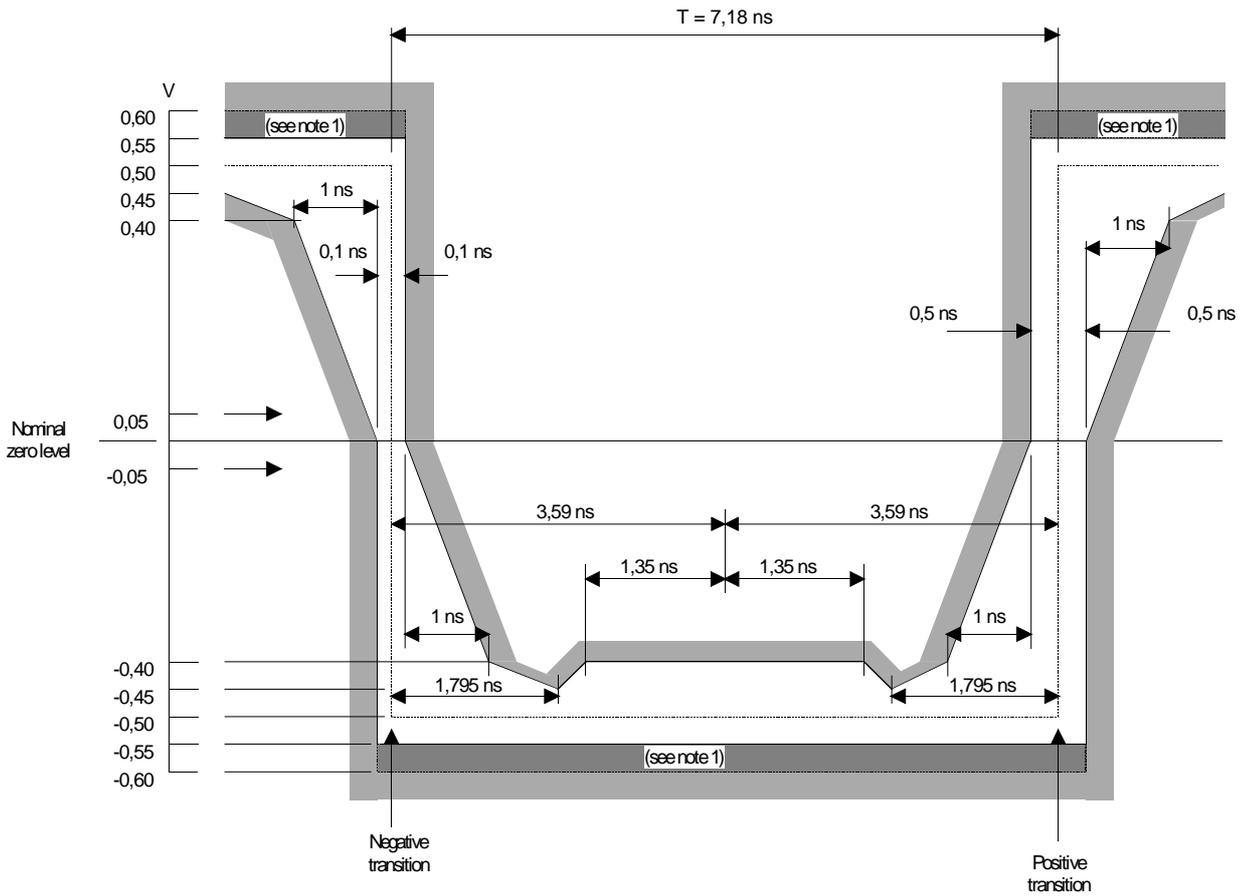
Pulse shape	Nominally rectangular and conforming with the masks shown in figures 2 and 3.
Test load impedance	75 Ω non-reactive
Peak to peak voltage	1,0 \pm 0,1 V
Rise time between 10 % and 90 % amplitudes of the measured steady state amplitude	\leq 2 ns
Transition timing tolerance (referred to the mean value of the 50 % amplitude points of the negative transition)	Negative transitions: \pm 0,1 ns Positive transitions at unit interval boundaries: \pm 0,5 ns Positive transitions at mid-interval: \pm 0,35 ns



NOTE 1: The maximum "steady state" amplitude shall not exceed the 0,55 V limit. Overshoots and other transients are permitted to fall into the dotted area, bounded by the amplitude levels 0,55 V and 0,60 V, provided they do not exceed the steady state level by more than 0,05 V.

NOTE 2: The rise time and decay time shall be measured between -0,4 V and 0,4 V and shall not exceed 2 ns.

Figure 2: Mask of a pulse corresponding to a binary 0



- NOTE 1: The maximum "steady state" amplitude shall not exceed the 0,55 V limit. Overshoots and other transients are permitted to fall into the dotted area, bounded by the amplitude levels 0,55 V and 0,60 V, provided they do not exceed the steady state level by more than 0,05 V.
- NOTE 2: The inverse pulse shall have the same characteristics, noting that the timing tolerance at the level of the negative and positive transitions are $\pm 0,1$ ns and $\pm 0,5$ ns respectively.
- NOTE 3: The rise time and decay time shall be measured between -0,4 V and 0,4 V and shall not exceed 2 ns.

Figure 3: Mask of a pulse corresponding to a binary 1

Test: The test shall be conducted according to subclause A.2.2.

4.2.1.3 Output timing

The terminal equipment may derive its timing from:

- a) an internal source (e.g. an internal clock);
- b) an external reference signal input;
- c) the received signal at the input port.

Requirement: For each of the timing arrangements intended for use, the bit rate at the output port shall be within the limits of 139 264 kbit/s \pm 15 parts per million (ppm), when any relevant external signal, including the received signal at the input port, is within its stated tolerance.

NOTE: The tolerance of \pm 15 ppm relates to the transmission capability of the leased line. Tighter limits may be needed to ensure satisfactory end to end interworking with the distant terminal equipment.

Test: The test shall be conducted according to subclause A.2.3.

4.2.1.4 Output return loss

Requirement: The output return loss at the terminal equipment interface, with respect to 75 Ω , shall be greater than or equal to the values given in table 2, which is taken from subclause 9.2 of ITU-T Recommendation G.703.

Table 2: Output port minimum return loss

Frequency range	Return loss
7 MHz to 210 MHz	15 dB

Test: The test shall be conducted according to subclause A.2.6.

4.2.1.5 Output jitter

Requirement: The peak-to-peak output jitter shall not exceed the limits of table 3 when measured with a bandpass filter with linear cut-off with the defined cut-off frequencies. At frequencies below the lower 3 dB point, the attenuation of the high pass filter shall rise with a value greater than, or equal to, 20 dB per decade. At frequencies above the upper 3 dB point, the attenuation of the low pass filtration shall rise with a value greater than, or equal to, 60 dB per decade.

For the purpose of testing, any signal input from which the output timing is derived shall be provided with the maximum tolerable input jitter, and with the maximum tolerable input frequency deviation, as specified by the manufacturer.

Where the output timing of the terminal equipment is taken from the leased line, the input to the terminal equipment shall be provided with components of sinusoidal jitter at points on the curve of figure 4 and table 5.

Table 3: Maximum output jitter

Measurement filter bandwidth		Output jitter
Lower cut-off (high pass)	Upper cut-off (low pass)	Unit Interval (UI) peak- to-peak (maximum)
200 Hz	3 500 kHz	0,4
10 kHz	3 500 kHz	0,075

Test: The test shall be conducted according to subclause A.2.7.

4.2.1.6 Output frame structure

The requirement of this subclause applies to terminal equipment for connection to the D140S leased line. For terminal equipments for connection to the D140U leased line, there is no requirement on the structure of the output bit stream.

Requirement: For terminal equipments for connection to the D140S leased line, the bit stream transmitted at the output of the terminal equipment shall be structured as defined in annex C.

Bit 1 of byte Maintenance and Adaptation (MA), a Remote Defect Indication (RDI), shall be set to "1" within 250 μ s of the detection of loss of received frame alignment (see subclause 4.2.2.7), and set to "0" within 250 μ s on gaining frame alignment".

Test: The test shall be conducted according to subclause A.2.8 and A.2.9.

4.2.2 Input port

4.2.2.1 Signal coding

Requirement: The input port shall decode without error CMI encoded signals in accordance with CMI encoding rules (see annex B).

Test: The test shall be conducted according to subclause A.2.4.

4.2.2.2 Input return loss

Requirement: The input return loss with respect to 75 Ω at the interface shall be greater than or equal to the values given in table 4, which is taken from subclause 9.3 of ITU-T Recommendation G.703.

Table 4: Input port minimum return loss

Frequency range	Return loss
7 MHz to 210 MHz	15 dB

Test: The test shall be conducted according to subclause A.2.5.

4.2.2.3 Input loss tolerance

Requirement: The input port shall decode without errors a 139 264 kbit/s signal as defined in subclauses 4.2.1.1 and 4.2.1.2 above but modified by a cable or artificial cable with the following characteristics:

- a) attenuation that follows a \sqrt{f} law with values throughout the range 0 dB to 12 dB at 70 MHz; and
- b) characteristic impedance of 75 Ω with a tolerance of $\pm 20\%$ over the frequency range from 7 MHz to 210 MHz.

Test: The test shall be conducted according to subclause A.2.4.

4.2.2.4 Input jitter tolerance

Requirement: The terminal equipment shall tolerate at its input port the maximum input jitter as shown in figure 4 and table 5 (taken from ITU-T Recommendation G.823).

NOTE: Terminal equipment with more than one input will normally need to be designed with a wander buffer of at least 18 microseconds, however, to accommodate the wander that may be produced by Synchronous Digital Hierarchy (SDH) networks, up to 40 microseconds may be needed.

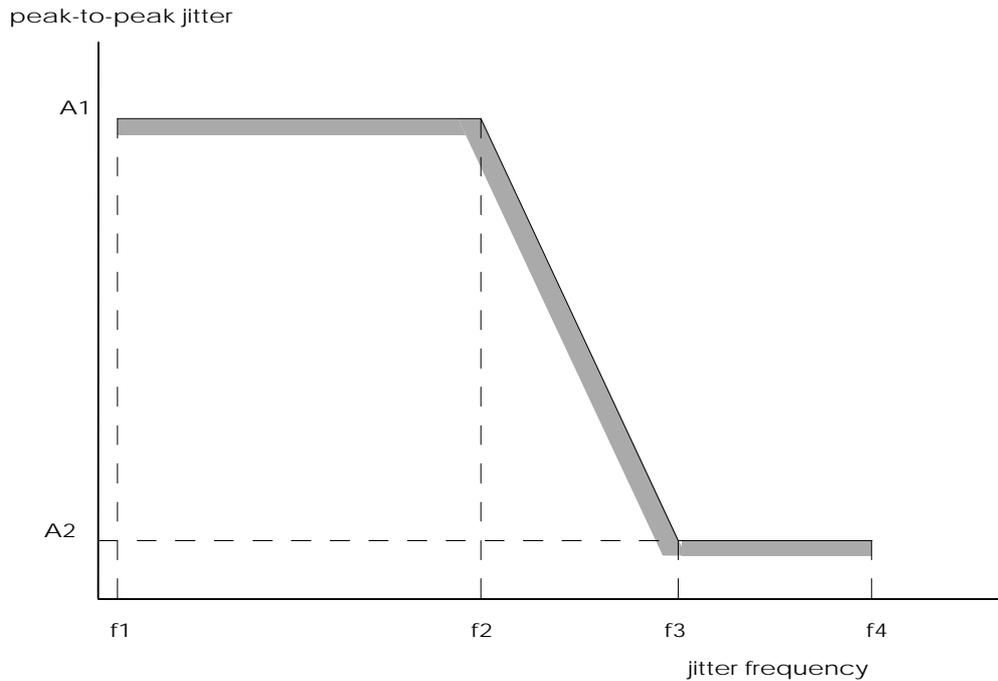


Figure 4: Input jitter tolerance

Table 5: Input jitter tolerance

Peak-to-peak amplitude (UI)		Frequency			
A1	A2	f1	f2	f3	f4
1,5	0,075	200 Hz	500 Hz	10 kHz	3 500 kHz

Test: The test shall be conducted according to subclause A.2.7.

4.2.2.5 Input clock tolerance

Requirement: The terminal equipment shall decode without error CMI encoded signals, as defined in annex B, for all bit rates within the limits of 139 264 kbit/s \pm 15 ppm.

Test: The test shall be conducted according to subclause A.2.7.

4.2.2.6 Input frame structure

The requirement of this subclause applies to terminal equipment for connection to the D140S leased line. For terminal equipments for connection to the D140U leased line, there is no requirement on the structure of the input bit stream.

Requirement: The input port shall accept an input bit stream with a frame structure as defined in annex C. The terminal equipment shall be capable of achieving frame alignment, as detailed in subclause 4.2.2.7, in order to separate the user data from the frame information.

Test: The test shall be conducted according to subclause A.2.4.

4.2.2.7 Frame alignment procedure

The requirement of this subclause applies to terminal equipment for connection to the D140S leased line. For terminal equipments for connection to the D140U leased line, there is no requirement on the frame alignment procedure.

Requirement: The terminal equipment shall perform a frame alignment procedure on the 139 264 kbit/s signal in order to gain or to recover frame alignment. To obtain frame alignment, the terminal equipment shall search for the FA1 and FA2 bytes contained within the received bit stream. Frame alignment shall be continuously checked with the presumed frame start position for the correct frame alignment.

Frame alignment shall be considered to have been obtained, or recovered, when three consecutive non-errored frame alignment signals (FA1 and FA2) have been found.

Frame alignment shall be considered to have been lost when either:

- a) four consecutive frame alignment signals (FA1 and FA2) are detected in error (i.e. ≥ 1 error in each FA1 and FA2); or
- b) 986 or more frames with one or more BIP-8 violations are detected in a block of 1 000 frames.

When frame alignment is achieved, even bit parity (BIP-8) shall be computed by the terminal equipment for each bit n of every byte of the preceding frame and compared with bit n of the EM byte recovered from the current frame. A difference between the computed BIP-8 and the EM value shall be taken as evidence of one or more errors in the previous frame.

Should a research for frame alignment be initiated for any reason, then the new search for frame alignment should start 1 bit displaced forward from the position of the last indication of frame alignment.

NOTE: The above is recommended in order to avoid repeated alignment on to a simulation of the framing location.

Test: The test shall be conducted according to subclause A.2.9.

4.3 Safety

Requirement: The terminal equipment interface shall comply with the requirements for accessible parts of an SELV circuit.

Test: The test shall be conducted according to EN 60950 [1].

4.4 Overvoltage protection

There are no overvoltage protection requirements under this ETS.

NOTE 1: Requirements for overvoltage protection requirements on a 75Ω interface are under study. Requirements may be added to this ETS when appropriate specifications become available.

NOTE 2: If the cables between the NTP and the terminal equipment leave the building, additional protection may be required as detailed in draft IEC 801-5, with a test level of 4,0 kV, applying failure criteria A from clause 7 of ITU-T Recommendation K.20.

4.5 ElectroMagnetic Compatibility (EMC)

There are no EMC requirements under this ETS.

NOTE: General EMC requirements are imposed under the EMC Directive (89/336/EEC). Requirements for conducted emissions and immunity to continuous conducted signals will be added to this ETS when appropriate specifications become available if these requirements are not imposed under the EMC Directive.

Annex A (normative): Test methods

A.1 General

This annex describes the test principles to determine the compliance of a terminal equipment against the requirements of this ETS.

It is outside the scope of this annex to identify the specific details of the implementation of the tests.

A terminal equipment may be designed for through-connecting and may fulfil the electrical requirements only if through-connected. In these cases the requirements of this ETS are valid and the tests shall be carried out with the through-connection terminated as specified by the manufacturer.

Details of test equipment accuracy and the specification tolerance of the test devices are not included in all cases. Where such details are provided they shall be complied with, but the way they are expressed shall not constrain the method of implementing the test.

NOTE: Attention is drawn to the issue of measurement uncertainty which may be addressed in future documents. Not all the required test results make allowance for spurious events during testing (e.g. errors due to EMC effects), which may make it necessary to repeat a test.

The test configurations given do not imply a specific realisation of test equipment or test arrangement, or the use of specific test devices for conformance testing. However, any test configuration used shall provide those test conditions specified under "interface state", "stimulus" and "monitor" for each individual test.

The test equipment shall be a device, or a group of devices, that is capable of generating a stimulus signal conforming to this ETS and capable of monitoring the signal received from the interface.

A.1.1 Additional information to support the test

The following facilities shall be provided by the terminal equipment interface under test:

- a) an ability to configure the terminal equipment such that it provides a transparent loopback of the data contained within the payload at the input to the output; and
 - b) an ability to transmit a given bit pattern, e.g. PRBS(2²³-1), within the payload;
- or
- c) where a or b cannot be provided, an alternative means of performing the test.

NOTE: Where the terminal equipment is for connection to the D140S leased line, the REI bit may be used as an alternative to a transparent loopback in order to determine if data at the input has been correctly received.

A.1.2 Equipment connection

The tests shall be applied at the sockets or plugs defined in subclauses 4.1.1 and 4.1.2. Connecting cable between the sockets and test equipment shall be kept to a minimum, except where cable is specified as part of the test.

Where plugs are provided at the end of a cord as defined in subclause 4.1.2, the tests specified in subclauses A.2.2, A.2.5 and A.2.6 may be performed at the point of connection of the cord to the terminal equipment, since the requirements are based on ITU-T Recommendation G.703 which makes no allowance for any plug and cord.

A.2 Test methods

One test may cover more than one requirement. The scope of each test is defined under the heading "purpose".

A.2.1 Signal coding at the output port

Purpose: To verify that the signal coding at the terminal equipment output port complies with the CMI coding rules as required by subclause 4.2.1.1.

Test configuration: Figure A.1.

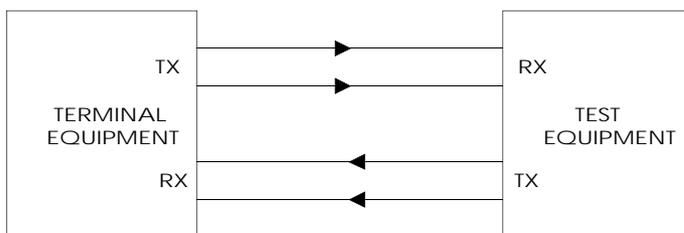


Figure A.1: Signal coding at output port

Interface state: Powered.

Stimulus: The terminal equipment shall transmit a pseudo random bit stream, e.g. PRBS($2^{23}-1$). For terminal equipment which can generate a structured signal in accordance with annex C the PRBS may be transmitted in the payload section of the frame. For terminal equipment which cannot generate such a structured signal, the PRBS should be transmitted in the whole bit stream.

Monitor: The output bit stream for a test period of sufficient time to allow transmission of 100 occurrences of the above patterns plus the latency period of the error detection mechanism.

Results: There shall be no errors in the CMI encoding.

A.2.2 Waveform shape at the output port

Purpose: To verify conformance of the output waveform shape with the requirements of subclause 4.2.1.2.

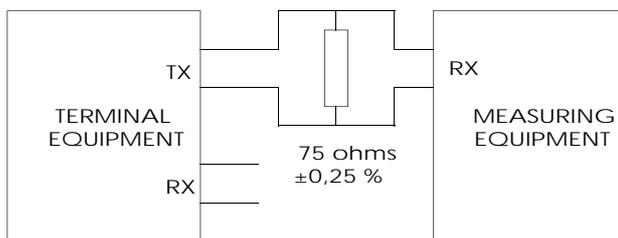


Figure A.2: Waveform shape at output port

Test configuration: Figure A.2.

Interface state: Powered.

Stimulus: Undefined.

Monitor: Marks and spaces transmitted from the terminal equipment, measuring the amplitude and pulse shapes corresponding to binary 0 and binary 1. A bandwidth of 1 GHz or greater shall be used to ensure the capture of over or undershoot of the pulse.

The overall measurement accuracy shall be better than 30 mV. For all measurements using these masks, the signal shall be ac coupled, using a capacitor of not less than 0,01 μ F, to the input of the oscilloscope (or other equipment) used for the measurement. The nominal zero for both masks shall be aligned with the oscilloscope trace with no input signal. With the signal then applied, the vertical position of the trace can then be adjusted with the objective of meeting the limits of the masks. Any such adjustment shall be the same for both masks and shall not exceed $\pm 0,05$ V. This shall be checked by removing the input signal again and ensuring that the trace lies within $\pm 0,05$ V of the nominal zero level of the masks.

The masks allow for high frequency jitter caused by intersymbol interference in the output stage, but not for jitter present in the timing signal associated with the source of the interface signal.

When using an oscilloscope technique to determine pulse compliance with the mask, it is important that successive traces of the pulses overlay in order to suppress the effects of low frequency jitter. This can be accomplished by several techniques, e.g.:

- a) triggering the oscilloscope on the measured waveform, or
- b) providing both the oscilloscope and the pulse output circuits with the same clock signal.

Results: Each pulse in a coded pulse sequence shall meet the limits of the relevant mask given in figures 2 and 3, irrespective of the state of the preceding or succeeding pulses, with both pulse masks fixed in the same relation to a common timing reference, i.e. with their normal start and finish edges coincident.

The rise and decay time shall be measured between -0,4 V and 0,4 V and shall not exceed 2 ns.

A.2.3 Output timing

Purpose: To measure the output timing as defined in subclause 4.2.1.3.

Test Configuration: Figure A.3.

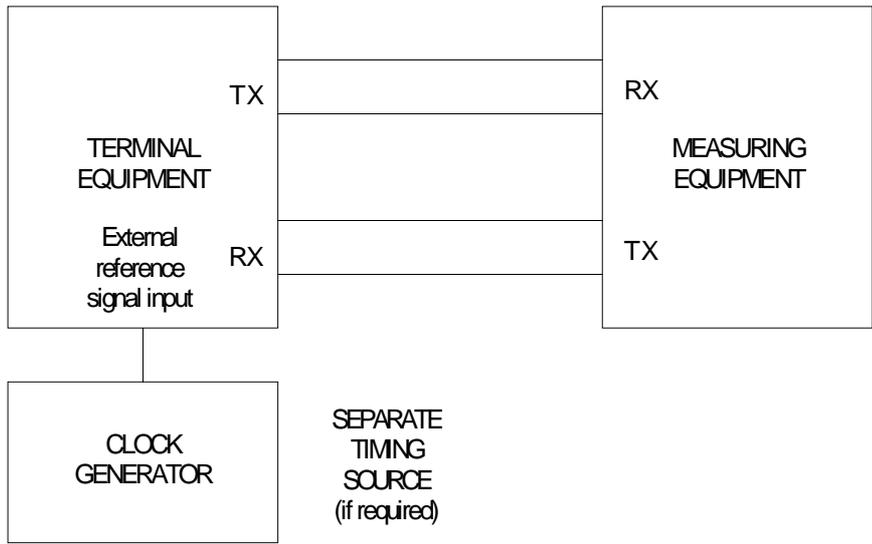


Figure A.3: Output timing

Interface state: Powered.

Stimulus: The terminal equipment shall be configured to provide output timing from each of its intended timing arrangements. Any external reference signal input, including the input port, from which timing can be derived, shall be provided with timing at the bit rate limits as specified by the terminal equipment manufacturer.

Monitor: The bit rate of the signal decoded from output port of the terminal equipment.

Results: The bit rate shall be within the limits given in subclause 4.2.1.3.

A.2.4 Input signal coding and loss tolerance

Purpose: To verify the input port signal coding (subclause 4.2.2.1) both without cable (i.e. 0 dB attenuation loss) and with a cable attenuation of 12 dB (subclause 4.2.2.3).

Test configuration: Figure A.4.

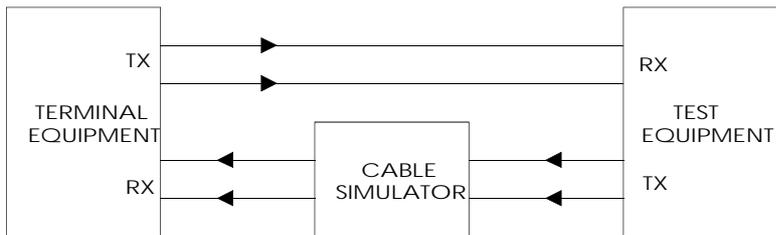


Figure A.4: Input coding and loss tolerance

The cable simulator shall have an attenuation of 12 dB measured at 70 MHz and an attenuation characteristic that follows a \sqrt{f} law over the frequency range 7 MHz to 210 MHz.

The conformance of the interface shall be verified in the following test conditions:

- a) without cable simulator; and
- b) with cable simulator.

Interface state: Powered, with received data looped back to the output port.

Stimulus: The output signal of the test equipment shall be CMI encoded and conform to a pulse shape as defined in figures 19 and 20 of ITU-T Recommendation G.703 [5], which are reproduced in figures 2 and 3 of this ETS. For terminal equipment which can generate a structured signal in accordance with annex C, the bit stream shall be structured into frames according to annex C. The binary content of the data contained in the payload of the frame shall be a PRBS($2^{23}-1$). For terminal equipment which cannot generate such a structured signal, the PRBS should be transmitted in the whole bit stream. The bit rate shall be within the limits $139\,264\text{ kbit/s} \pm 15\text{ ppm}$.

Monitor: Data at the output port of the terminal equipment.

Results: There shall be no bit errors for at least one minute.

A.2.5 Input return loss

Purpose: To verify the return loss of the input port of the terminal equipment complies with the requirement of subclause 4.2.2.2.

Test configuration: Figure A.5.

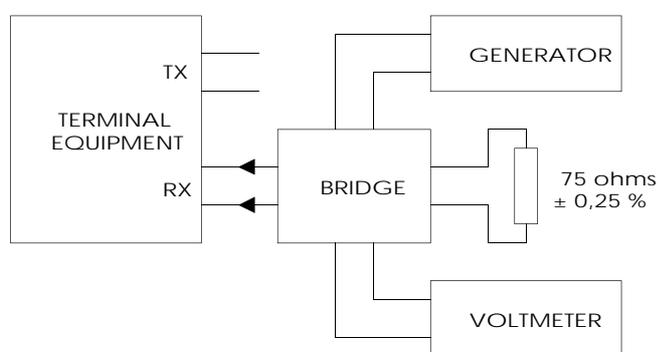


Figure A.5: Return loss at input port

Interface state: Powered.

Stimulus: Sinusoidal signal of 1 V peak applied to the input of the terminal equipment with a frequency variable between the limits 7 MHz to 210 MHz.

Monitor: Voltage measured across the bridge, representing a terminating resistor of $75\ \Omega$ using a selective voltmeter with a bandwidth of less than 10 kHz.

Results: The measured return loss shall be greater than or equal to the values specified in subclause 4.2.2.2.

NOTE 1: The characteristics of the generator and of the voltmeter may be different depending on the implementation of the bridge, however the total error of the test set-up should be less than 0,5 dB in the range between 10 dB and 20 dB. When connected to a $75\ \Omega \pm 0,25\ %$ resistor, the measured return loss of the bridge should be 20 dB higher than the limits specified for the interface.

NOTE 2: Where the generator and voltmeter are implemented by means of a network analyser, a measurement bandwidth of 100 Hz and a sweep time of 10 s is recommended.

A.2.6 Output return loss

Purpose: To verify the return loss of the output port of the terminal equipment complies with the requirement of subclause 4.2.1.4.

Test configuration: Figure A.6.

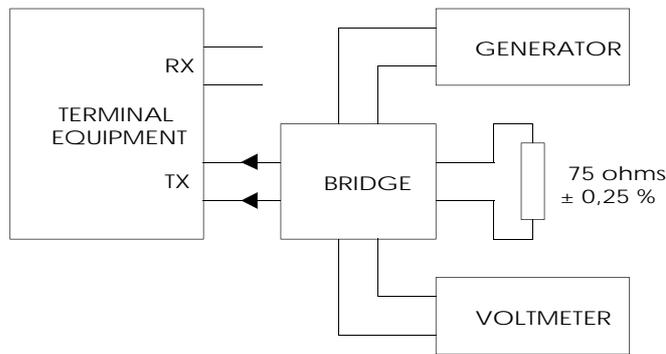


Figure A.6: Return loss at output port

- Interface state:** Powered.
- Stimulus:** Sinusoidal signal of 1 V peak applied to the output of the terminal equipment interface with a frequency variable between the limits of 7 MHz and 210 MHz.
- The output return loss shall be measured under dynamic conditions with a PRBS($2^{23}-1$) transmitted at the output. For a terminal equipment which can generate a structured signal in accordance with this ETS, the PRBS may be transmitted in the payload section of the frame. For a terminal equipment which cannot generate such a structured signal, the PRBS should be transmitted in the whole bit stream.
- Monitor:** Voltage measured across the bridge, representing a terminating resistor of 75 Ω using a selective voltmeter with a bandwidth of less than 10 kHz.
- Results:** The measured return loss shall be greater than or equal to the values specified in subclause 4.2.1.4.

NOTE 1: The characteristics of the generator and of the voltmeter may be different depending on the implementation of the bridge however the total error of the test set-up should be less than 0,5 dB in the range between 10 dB and 20 dB. When connected to a 75 Ω \pm 0,25 % resistor the measured return loss of the bridge should be 20 dB higher than the limits specified for the interface.

NOTE 2: Where the generator and voltmeter are implemented by means of a network analyser, a measurement bandwidth of 100 Hz and a sweep time of 10 s is recommended to restrict the influence of the output signal on the test result.

A.2.7 Input and output jitter

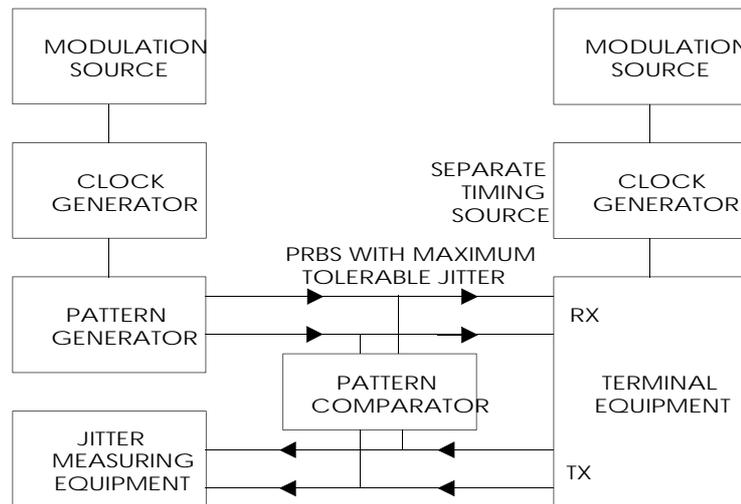
Purpose: To measure tolerance to input jitter (subclause 4.2.2.4), maximum output jitter (subclause 4.2.1.5) and operation over the specified input timing range (subclause 4.2.2.5).

NOTE: Further information on the measurement of jitter can be found in CCITT Supplement number 3.8, Fascicle IV.4 (1988).

Test Configuration: Figure A.7.

The terminal equipment shall be tested in each of the following configurations (where these modes of operation are supported):

- a) output timing referenced to the internal clock; and
- b) output timing referenced to any external clock source from which timing can be derived (including derivation from the input signal).



NOTE: The modulation source may be included in the clock generator and/or the pattern generator, or it may be provided separately.

Figure A.7: Jitter measurement

Interface state: Powered, with received data looped back to the output port.

Stimulus: The output signal of the test equipment shall be CMI encoded and conform to a pulse shape as defined in figures 19 and 20 of ITU-T Recommendation G.703 [5], which are reproduced in figures 2 and 3 of this ETS. For terminal equipment which can accept a structured signal in accordance with annex C, the bit stream shall be structured into frames according to annex C. The binary content of the data contained in the payload of the frame shall be a PRBS($2^{23}-1$). For terminal equipment which cannot accept such a structured signal, the PRBS should be transmitted in the whole bit stream.

Measurements shall be made with both the input signals at the digital rate limits of $139\,264\text{ kbit/s} \pm 15\text{ ppm}$ and between these limits, sufficient to verify jitter compliance over the specified frequency range. As a minimum the test shall be performed at the upper and lower limits and at the nominal rate.

The modulation source for the terminal equipment input bit stream shall generate individual components of sinusoidal jitter at points on the applicable curve of figure 3 and table 5 or figure 4 and table 4 of this ETS.

The modulation source for the external timing (if needed) shall be independent from that for the input signal and shall generate the maximum tolerable jitter, and maximum frequency deviation, as specified by the manufacturer of the terminal equipment.

It may be necessary to synchronise the two clock generators to avoid a high occurrence of slips.

Monitor:

- a) The signal transmitted by the terminal equipment; and
- b) the jitter extracted from this signal using equipment complying with ITU-T Recommendation O.171 [7].

Results:

- a) There shall be no bit errors reported by the test equipment within the period of the test; and
- b) the peak-to-peak jitter shall comply with the requirements of subclause 4.2.1.5.

A.2.8 Frame structure

Purpose: To verify compliance with the requirements for terminal equipment output structure defined in subclause 4.2.1.6. The test verifies the presence of the frame alignment signals (FA1 and FA2), the BIP-8, trail trace, MA byte (RDI, REI, payload type, payload dep and TM) and the general purpose communications channel.

Test configuration: Figure A.8.

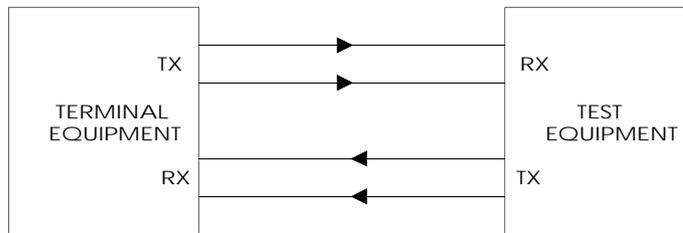


Figure A.8: Structure

Interface state: Powered.

Stimulus: The following CMI encoded stimuli shall be applied to the input of the terminal equipment at a bit rate within the limits of 139 264 kbit/s \pm 15 ppm:

- a) a bit stream structured in accordance with annex C;
- b) a bit stream structured in accordance with annex C, with bit errors introduced in the payload following calculation of the BIP-8;
- c) a continuous all one signal (AIS);
- d) no signal (input disconnected);
- e) a continuous PRBS($2^{23}-1$) with no frame structure.

Monitor: The bit stream at the output of the terminal equipment.

Results: The output bit stream shall comprise frames of octets commencing with the two octets FA1 and FA2 as defined in annex C.

- a) The BIP-8 contained in the EM byte shall correspond to the previous frame in accordance with the requirements of annex C; RDI = 0; REI = 0; the trail trace byte, payload type, payload dependent bits and TM shall be as declared by the terminal equipment manufacturer;
- b) REI shall be set to 1 for a period of 1 frame, for each frame received where the BIP-8 does not correspond with the data;
- c) RDI = 1;
- d) RDI = 1;
- e) RDI = 1.

A.2.9 Frame alignment procedure

Purpose: To verify the compliance with the requirements for frame alignment procedure (see subclause 4.2.2.7). The test verifies the detection of loss of frame and regaining of frame and the associated setting of the RDI (see subclause 4.2.1.6).

Test configuration: See figure A.9.

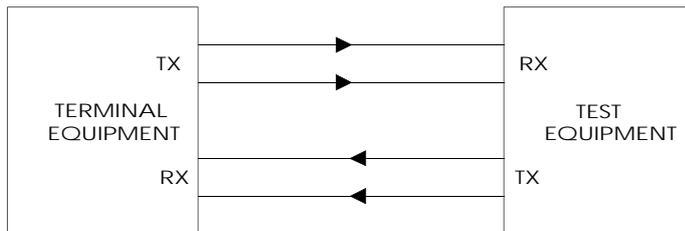


Figure A.9: Frame alignment

Interface state: Powered.

Stimulus: The following CMI encoded signal shall be applied to the input of the terminal equipment at a bit rate within the limits of 139 264 kbit/s ± 15 ppm. The bit stream shall be structured in accordance with annex C but with the following modification of the frame alignment word and the EM byte.

Table A.1: Frame alignment procedure

Stimulus	Result	Comment
...F F F F F F ...	RDI=0	correct FAS
...F F F F /F /F /F F F F ...	RDI=0	3 incorrect FAS
...F F F F N*(/F /F /F /F F F)	RDI=1	4 incorrect FAS
/F /F /F /F F F F	RDI=0	
/F F F /F	RDI=0	
F F F F ...	RDI=0	
...985 BIP-8 errors in 1 000 frames	RDI=0	
...986 BIP-8 errors in 1 000 frames	RDI=1	
F F F F...	RDI=0	
/F /F /F /F ...	RDI=1	New FAS should be searched with 1 bit offset.
Simulated FA1, FA2 and correct BIP-8 in the payload.	RDI=0	
After locking of simulated frame consecutive F and EM, 986 incorrect BIP-8 in the payload	RDI=1	
F F F F	RDI=0	
NOTE:	F = correct frame alignment signal /F = incorrect frame alignment signal N* = repeat continuously N times (where N is an integer)	

Monitor: The RDI signal at the output port

Result: The setting of the RDI shall conform to column 2 of table A.1.

Annex B (normative): Definition of CMI code

B.1 General

This annex specifies the CMI code. The contents of this annex are based on subclause 9.1 of ITU-T Recommendation G.703.

B.2 Definition

CMI is a 2-level non-return-to-zero code in which binary 0 is coded so that both amplitude levels, A_1 and A_2 , are attained consecutively, each for half a unit time interval $T/2$.

Binary 1 is coded by either of the amplitude levels A_1 or A_2 , for one full unit time interval (T), in such a way that the level alternates for successive binary 1s.

An example is given in figure B.1.

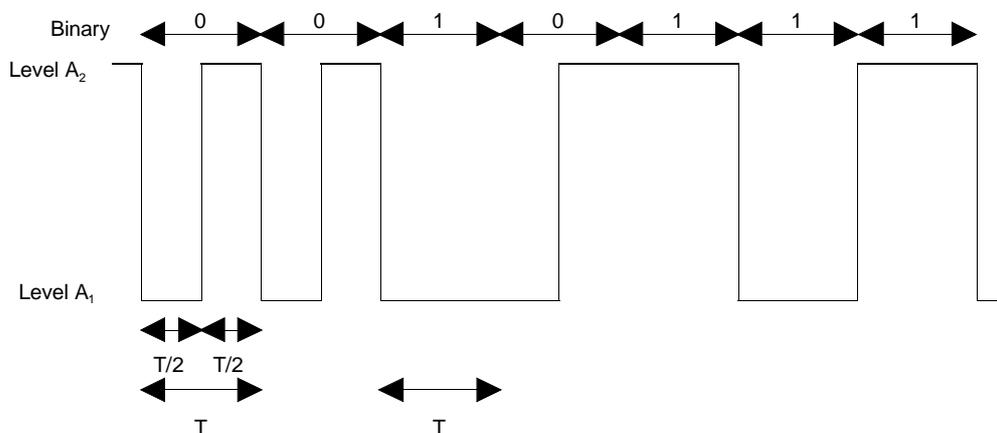


Figure B.1: Example of CMI coded binary signal

Annex C (normative): Definition of frame structure

C.1 Frame structure at 139 364 kbit/s

The basic frame structure at 139 264 kbit/s for the D140S leased line shall comprise 16 octets of generic path overhead and 2 160 octets of payload capacity; this is defined in figures C.1 and C.2. The order of transmission of information in figure C.1 is first from left to right and then top to bottom. Within each byte the most significant bit is transmitted first. The most significant bit (bit 1) is illustrated at the left of figure C.2.

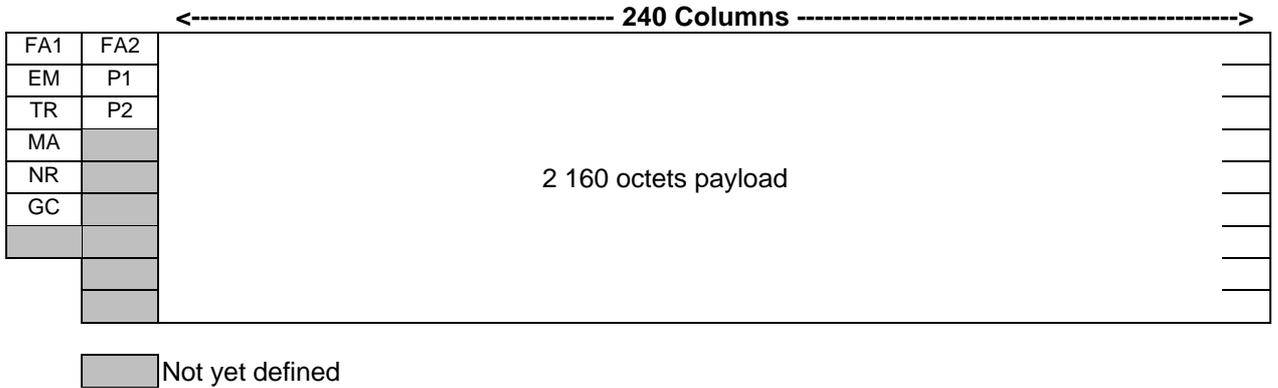


Figure C.1: Frame structure at 139 264 kbit/s

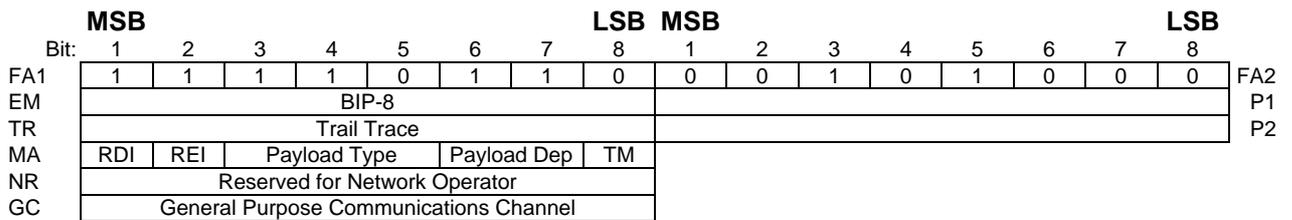


Figure C.2: Path overhead at 139 264 kbit/s

MSB Most Significant Bit.

LSB Least Significant Bit.

FA1 Frame alignment byte (1).

FA2 Frame alignment byte (2).

EM Error Monitoring, Bit Interleaved Parity - 8 (BIP-8). One byte is allocated for path error monitoring. This function shall be a BIP-8 code using even parity. The path BIP-8 is calculated over all bits of the previous 125 µs frame. The computed BIP-8 is placed in the EM byte of the current 125 µs frame.

TR TRail trace. This byte is used to transmit repetitively a trail access point identifier so that a trail receiving terminal can verify its continued connection to the intended transmitter. See subclause C.1.1.

MA Maintenance and Adaptation Byte:

Bit 1 RDI Remote Defect Indication: this bit is set to "1" under the following conditions:

- a) invalid input signal or loss of signal (LOS);
- b) loss of frame alignment (LOF) see note 1; or
- c) alarm indication signal (AIS);

and is otherwise set to "0".

NOTE 1: RDI may also be set in the event of a trail trace mismatch.

Bit 2 REI Remote Error Indication: this bit is set to "1" and sent back to the remote path termination if one or more errors were detected by the BIP-8, and is otherwise set to "0".

Bits 3 - 5 Payload type: these bits are set as shown in table C.1.

Table C.1: Payload type

Code	Signal
000	Unequipped
001	Equipped, non-specific
010	ATM
011	20 x TUG-2
100	2 x TUG-3 and 5 x TUG-2

Bits 6 - 7 Payload dependent: e.g. Tributary Unit (TU) multiframe indicator.

NOTE 2: Further information on the multiplexing of SDH elements within the payload and the use of the payload dependent bits is given in ETS 300 337.

Bit 8 TM Timing marker: this bit is set to "0" to indicate that the timing source is traceable to a primary reference clock and is otherwise set to "1".

NR Network operator byte. This byte is undefined for terminal equipments.

NOTE 3: This byte is allocated for maintenance purposes specific to individual network operators. Its transparency from NTP to NTP is not guaranteed.

GC General purpose Communications channel (e.g. to provide data/voice channel connection for maintenance purposes). The specific use of this byte is undefined.

NOTE 4: This byte is allocated for the specific use of the terminal equipment user. Its transparency from NTP to NTP is guaranteed.

NOTE 5: The specific use of this byte is under study within other ETSI technical committees.

P1/2 Automatic protection switching. Bytes P1 and P2 are not used in leased line applications and are undefined for terminal equipments.

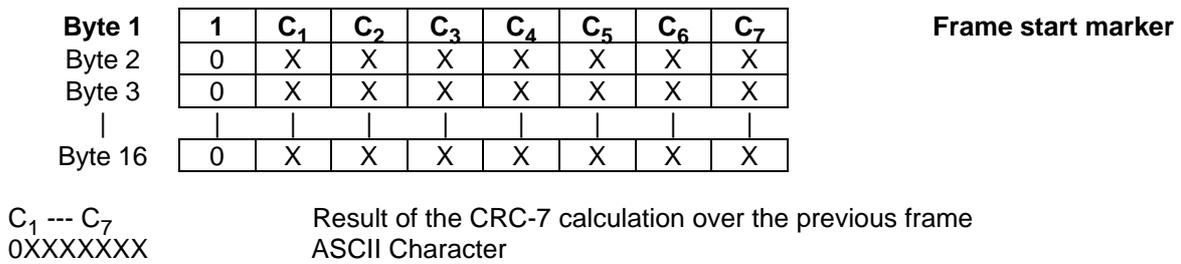
C.1.1 Trail access point identifier format

The trail access point identifier shall use the 16-byte numbering format described below.

The first byte of the string is a frame start marker and includes the result of a Cyclic Redundancy Check (CRC-7) calculation over the previous frame. The following 15 bytes are used for the transport of 15 American Standard Code for Information Interchange (ASCII) characters supplied by the leased line provider for each leased line. This code will be different in each direction of transmission.

NOTE: The ASCII code is specified in ITU-T Recommendation T.50.

The 16-byte frame is defined in figure C.3.

**Figure C.3: 16-byte frame**

The description of the CRC-7 calculation is given below.

C.1.1.1 CRC-7 calculation - multiplication and division process

A particular CRC-7 word is the remainder after multiplication by x^7 and then division (modulo 2) by the generator polynomial $x^7 + x^3 + 1$, of the polynomial representation of the previous Trail Trace Identifier (TTI) multiframe.

When representing the contents of the block as a polynomial, the first bit in the block (i.e. byte 1 bit 1) shall be taken as being the MSB. Similarly, C₁ is defined to be the MSB of the remainder and C₇ to be the LSB of the remainder.

C.1.1.2 CRC-7 calculation - encoding procedure

Contrary to e.g. CRC-4 procedure in a 2 048 kbit/s signal, the CRC-7 word is static because the data is static (the TTI represents the source address). This means that the CRC-7 checksum can be calculated a priori over the TTI multiframe. For consistency with existing recommendations, the CRC-7 shall be calculated over the previous multiframe. In theory this means that the 16-byte string that is loaded in a device for repetition transmission should have the checksum as the last byte, although in practice it does not really matter, because the TTI is static.

The encoding procedure is as follows:

- the CRC-9 bits in the TTI are replaced by binary 0 s;
- the TTI is then acted upon by the multiplication/division process referred to above;
- the remainder resulting from the multiplication/division process is inserted into the CRC-7 location.

The CRC-9 bits generated do not affect the result of the multiplication/division process because, as indicated in a) above, the CRC-9 bit positions are initially set to 0 during the multiplication/division process.

C.1.1.3 CRC-7 calculation - decoding procedure

The decoding procedure is as follows:

- a received TTI is acted upon by the multiplication/division process referred to above after having its CRC-9 bits extracted and replaced by binary 0 s;
- the remainder resulting from the multiplication/division process is then compared on a bit-by-bit basis with the CRC-9 bits received;
- if the remainder calculated in the decoder exactly corresponds to the CRC-9 bits received, it is assumed that the checked TTI is error free.

Annex D (normative): ETS Requirements Table (ETS-RT)

Notwithstanding the provisions of the copyright clause related to the text of this ETS, ETSI grants that users of this ETS may freely reproduce the ETS-RT proforma in this annex so that it can be used for its intended purposes and may further publish the completed ETS-RT.

Table D.1: ETS conditions table for attachment requirements for terminal equipment to digital 140 Mbit/s leased lines (D140U and D140S) as given in ETS 300 690

Reference	Condition	Status	Support (Y/N)
C.1	Is the terminal equipment intended for connection to the D140S leased line?	If YES then M else N	

Table D.2: ETS-RT for attachment requirements for terminal equipment to digital 140 Mbit/s leased lines (D140U and D140S) as given in ETS 300 690

ETS Reference		ETS 300 690		
Item	Reference	Requirement	Status (note 1)	Support (note 2)
1	4.1.1	Sockets	O.1	
2	4.1.2	Plugs	O.1	
3	4.2.1.1	Signal coding	M	
4	4.2.1.2	Waveform shape	M	
5	4.2.1.3	Output timing	M	
6	4.2.1.3 (a)	- internal source of timing	O	
7	4.2.1.3 (b)	- external timing reference (note 3)	O	
8	4.2.1.3 (c)	- timing derived from input port	O	
9	4.2.1.4	Output return loss	M	
10	4.2.1.5	Output jitter	M	
11	4.2.1.6	Output frame structure	C.1	
12	4.2.2.1	Signal coding	M	
13	4.2.2.2	Input return loss	M	
14	4.2.2.3	Input loss tolerance	M	
15	4.2.2.4	Input jitter tolerance	M	
16	4.2.2.5	Input clock tolerance	M	
17	4.2.2.6	Input frame structure	C.1	
18	4.2.2.7	Frame alignment procedure	C.1	
19	4.3	Safety	M	
20	4.4	Overvoltage protection	N	
21	4.5	ElectroMagnetic Compatibility	N	
NOTE 1:	Status is "Mandatory (M)", "Not a requirement (N)", "Optional (O)" or "Conditional (C.x)". For Conditional see table D.1. O.n indicates that one or more of the numbered options shall be provided from the set n.			
NOTE 2:	The support column has been added to the requirements table so that the table may be used as an implementation conformance statement proforma. Support is Y (equipment conforms to the ETS), X (equipment does not conform to this ETS), N (equipment does not claim to conform to this ETS).			
NOTE 3:	Where the timing may be derived from an external reference signal, the terminal equipment supplier shall declare the maximum input jitter and maximum timing deviation of this signal for the purpose of testing the output jitter limits of subclause 4.2.1.5.			

Annex E (informative): Bibliography

- 89/336/EEC: "Council Directive of 3 May 1989 on the approximation of the laws of Member States relating to electromagnetic compatibility".
- 91/263/EEC: "Council Directive of 29 April 1991 on the approximation of the laws of Member States concerning telecommunications terminal equipment, including the mutual recognition of their conformity".
- 92/44/EEC: "Council Directive of 5 June 1992 on the application of Open Network Provision to leased lines".
- CCITT Supplement number 3.8, Fascicle IV.4 (1988): "Guidelines concerning the measurement of jitter".
- prETS 300 686: "34 Mbit/s and 140 Mbit/s digital leased lines (D34U, D34S, D140U and D140S); Network interface presentation".
- prETS 300 688: "140 Mbit/s digital leased lines (D140U and D140S); Connection characteristics".
- DEN/EE-02004: "Earthing for functional and safety aspects and bonding techniques of information technology equipment inside a subscriber's building".
- ETS 300 166: "Transmission and Multiplexing (TM); Physical and electrical characteristics of hierarchical digital interfaces for equipment using the 2 048 kbit/s-based plesiochronous or synchronous digital hierarchies".
- ETS 300 337: "Transmission and Multiplexing (TM); Generic frame structures for the transport of various signals (including Asynchronous Transfer Mode (ATM) cells and Synchronous Digital Hierarchy (SDH) elements) at the CCITT Recommendation G.702 hierarchical rates of 2 048 kbit/s, 34 368 kbit/s and 139 264 kbit/s".
- draft IEC 801-5: "Electromagnetic compatibility for electrical and electronic equipment, Part 5: Surge immunity requirements".
- ITU-T Recommendation G.703 (1991): "Physical/electrical characteristics of hierarchical digital interfaces".
- ITU-T Recommendation G.823 (1988): "The control of jitter and wander within digital networks which are based on the 2 048 kbit/s hierarchy".
- ITU-T Recommendation K.20 (1993): "Resistibility of telecommunication switching equipment to overvoltages and overcurrents".
- ITU-T Recommendation T.50: "International Reference Alphabet (IRA) (Formerly International Alphabet No. 5 or IA5) - Information technology - 7-bit coded character set for information interchange".
- prTBR 25: "Business TeleCommunications (BTC); 140 Mbit/s digital leased lines (D140U and D140S), Attachment requirements for terminal equipment interface".

History

Document history			
April 1995	Public Enquiry	PE 83:	1995-04-24 to 1995-09-15
October 1996	Vote	V 112:	1996-10-07 to 1996-11-29