



EUROPEAN
TELECOMMUNICATION
STANDARD

FINAL DRAFT
pr **ETS 300 581-3**

August 1995

Source: ETSI TC-SMG

Reference: DE/SMG-020621

ICS: 33.060.50

Key words: European digital cellular telecommunications system, Global System for Mobile communications (GSM)

**European digital cellular telecommunications system;
Half rate speech
Part 3: Substitution and muting of lost frames for half rate
speech traffic channels
(GSM 06.21)**

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Foreword

This final draft European Telecommunication Standard (ETS) has been produced by the Special Mobile Group (SMG) Technical Committee of the European Telecommunications Standards Institute (ETSI), and is now submitted for the Voting phase of the ETSI standards approval procedure.

This final draft ETS specifies the half rate speech traffic channels for the European digital cellular telecommunications system. This ETS corresponds to GSM technical specification, GSM 06.21, version 4.0.1 and is part 3 of a multi-part ETS covering the half rate speech traffic channels as described below:

GSM 06.02	ETS 300 581-1: "European digital cellular telecommunications system; Half rate speech Part 1: Half rate speech processing functions".
GSM 06.20	ETS 300 581-2: "European digital cellular telecommunications system; Half rate speech Part 2: Half rate speech transcoding".
GSM 06.21	ETS 300 581-3: "European digital cellular telecommunications system; Half rate speech Part 3: Substitution and muting of lost frames for half rate speech traffic channels".
GSM 06.22	ETS 300 581-4: "European digital cellular telecommunications system; Half rate speech Part 4: Comfort noise aspects for half rate speech traffic channels".
GSM 06.41	ETS 300 581-5: "European digital cellular telecommunications system; Half rate speech Part 5: Discontinuous Transmission (DTX) for half rate speech traffic channels".
GSM 06.42	ETS 300 581-6: "European digital cellular telecommunications system; Half rate speech Part 6: Voice Activity Detection (VAD) for half rate speech traffic channels".
GSM 06.06	ETS 300 581-7: "European digital cellular telecommunications system; Half rate speech Part 7: ANSI-C code for the GSM half rate speech codec".
GSM 06.07	ETS 300 581-8: "European digital cellular telecommunications system; Half rate speech Part 8: Test vectors for the GSM half rate speech codec".

NOTE: TC-SMG has produced documents which give the technical specifications for the implementation of the European digital cellular telecommunications system. Historically, these documents have been identified as GSM Technical Specifications (GSM-TS). These TSs may have subsequently become Interim European Telecommunication Standards (I-ETs), (Phase 1), or European Telecommunication Standards (ETs), (Phase 2), whilst others may become ETSI Technical Reports (ETRs).

Proposed transposition dates	
Date of latest announcement of this ETS (doa):	3 months after ETSI publication
Date of latest publication of new National Standard or endorsement of this ETS (dop/e):	6 months after doa
Date of withdrawal of any conflicting National Standard (dow):	6 months after doa

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1 Scope

This European Telecommunication Standard (ETS) defines a frame substitution and muting procedure which shall be used by the Receive (RX) Discontinuous Transmission (DTX) handler when one or more lost or unreliable speech or Silence Descriptor (SID) frames are received from the Radio Sub System (RSS).

The requirements of this ETS are mandatory for implementation in all GSM Base Station Systems (BSS)s and Mobile Stations (MS)s capable of supporting the half rate speech traffic channel.

2 Normative references

This ETS incorporates by dated and undated reference, provisions from other publications. These normative references are cited at the appropriate places in the text and the publications are listed hereafter. For dated references, subsequent amendments to or revisions of any of these publications apply to this ETS only when incorporated in it by amendment or revision. For undated references, the latest edition of the publication referred to applies.

- [1] GSM 01.04 (ETR 100): "European digital cellular telecommunication system (Phase 2); Abbreviations and acronyms".
- [2] GSM 05.03 (ETS 300 575): "European digital cellular telecommunications system (Phase 2); Channel coding".
- [3] GSM 06.20 (ETS 300 581-2): "European digital cellular telecommunications system Half rate speech Part 2: Half rate speech transcoding".
- [4] GSM 06.41 (ETS 300 581-5): "European digital cellular telecommunications system Half rate speech Part 5: Discontinuous transmission (DTX) for half rate speech traffic channels".
- [5] GSM 06.06 (ETS 300 581-7): "European digital cellular telecommunications system (Phase 2); Half rate speech Part 7: ANSI-C code for the GSM half rate speech codec".

3 Definitions and abbreviations

3.1 Definitions

The definitions of terms used in this ETS can be found in GSM 06.20 (ETS 300 581-2) [3], GSM 06.41 (ETS 300 581-5) [4], GSM 05.03 (ETS 300 575) [2].

3.2 Abbreviations

For the purposes of this ETS the following abbreviations apply.

BFI	Bad Frame Indication
BSS	Base Station System
DTX	Discontinuous Transmission
ETS	European Telecommunication Standard
GSM	Global System for Mobile communications
LPC	Linear Predictive Coding
MS	Mobile Station
RX	Receive
RSS	Radio Sub System
SID	Silence Descriptor
UFI	Unreliable Frame Indication

For abbreviations not given in this subclause see GSM 01.04 (ETR 100) [1].

4 General

The RSS indicates lost speech or SID frames by setting the Bad Frame Indication (BFI) flag and unreliably decoded speech or SID frames by setting the Unreliable Frame Indication (UFI) flag.

If the BFI flag is set, the speech decoder performs frame substitution and muting of the speech output. The purpose of frame substitution is to conceal the effect of lost frames. The purpose of muting the speech output in case of several lost frames is to indicate the breakdown of the channel to the Mobile Station (MS) user in a way that avoids excessively unpleasant sounds.

If the UFI flag is set, the speech decoder performs a plausibility analysis of the received frame parameters and of the output signal aiming at the detection and concealment of erroneous frames which are not marked with the BFI flag.

5 Requirements

5.1 Error detection and concealment in case of unreliable speech or SID frames

A cleared BFI flag (BFI="0") and a set UFI flag (UFI="1") indicate a probably erroneous speech or SID frame. To improve the subjective quality, the probability of decoding erroneous frames shall be decreased by additional error detection which is based on both the exploitation of the frame parameters' properties and the decoder output signal's properties.

5.1.1 Error detection

By investigating the frame parameter properties it shall be decided whether the frame is to be considered as usable or unusable. In the latter case the BFI flag is set and substitution and muting is performed (subclause 5.2). Subclause 6.1 gives an example solution for error detection in case of unreliable frames.

5.1.2 Output signal concealment

If the frame is considered as usable, properties of the decoder output signal shall be compared to the corresponding signal properties of the previous valid frames. In case of large differences the output signal shall be modified such that these differences are limited. Subclause 6.2 gives an example solution for output signal concealment in case of unreliable frames.

5.2 Frame substitution and muting in case of lost speech or SID frames

A set BFI flag (BFI="1") indicates a lost speech or SID frame. Normal decoding of these frames would result in a degradation of the subjective quality of the speech. To improve the subjective quality of the speech, the frame parameters shall be appropriately modified prior to the execution of the speech decoder functions.

5.2.1 First and second lost speech frame

The first and second lost speech frame shall be partly or completely substituted with the last valid speech frame. For the first and second lost speech frame, the output shall not be muted directly.

5.2.2 Subsequent lost speech frames

For subsequent lost speech frames, a muting technique shall be used that will gradually decrease the output level, resulting in silencing of the output after a maximum of 80 ms. For subsequent lost speech frames, the muting of the output shall be maintained. Subclause 6.3 gives an example of such a method.

5.2.3 First and second lost SID frame

The first and second lost SID frame shall be substituted with the last good SID frame. For the first and second lost SID frame, the output shall not be muted directly.

5.2.4 Subsequent lost SID frames

For subsequent lost SID frames, a muting technique shall be used that will gradually decrease the output level, resulting in silencing of the output after a maximum of 320 ms. For subsequent lost SID frames, the muting of the output shall be maintained. Subclause 6.4 gives an example of such a method.

6 Example solutions

The C code of the following example solutions are given in GSM 06.06 (ETS 300 581-7) [5].

6.1 Example solution for error detection in case of unreliable frames

With the parameter R0 the average signal energy is transmitted. Except at the beginning or the end of a talk spurt this parameter shows a smooth behaviour from frame to frame. For error detection purposes, the difference of the R0-value between the actual and the last good frame is computed. If this difference exceeds a level dependent threshold and the frame is marked as unreliable, it is declared unusable by setting the BFI flag equal to "1".

6.2 Example solution for output signal concealment in case of unreliable frames

In the speech decoder the output signal is created by processing an excitation sequence through an LPC synthesis filter. The output signal energy of each subframe is calculated and compared to the output signal energy of the previous subframes. If the difference exceeds a level dependent threshold, the excitation sequence is attenuated such that the output signal energy corresponds to the output signal energy of the previous subframes.

6.3 Example solution for substitution and muting of lost speech frames

For the half rate speech decoder, a possible substitution and muting strategy is based on an 8-state machine:

The state, with the exception of states 6 and 7, indicates how many consecutive frames were lost. For example, state 5 indicates that 5 consecutive frames (including the current frame) were lost. State 7 is the initial state of the system, so that if the first decoded frame is lost, the frame is muted. Usually, the system will operate in state 0. The state machine remains in this state unless a frame is lost. On each successive lost speech frame, the state machine moves to the next higher numbered state. As soon as a frame is not declared lost, the machine returns to state 0 (unless it is in state 6). The machine remains in state 6 in the case of additional lost speech frames. If the machine is in state 6, a single frame without detected errors moves the machine to state 7 (i.e., two successive frames with no detected errors are needed to return to state 0 from state 6). This provides additional protection during prolonged intervals of very poor channel conditions which might cause false indications of valid speech data. If the machine is in state 7 and a lost speech frame is received the machine returns to state 6.

In each state, the following occurs:

- State 0 - No error is detected. The received decoded speech data is output. The current frame parameters are stored.
- State 1 - An error has been detected in the frame. If the last speech frame in state 0 is in the unvoiced mode, then the parameters R0, INT_LPC and the LPC coefficients in the current frame are replaced with the corresponding values from the last good frame. All GSP0 parameters are replaced with the GSP0_4 parameter from the last good frame. If the MODE bits for the current frame indicate unvoiced, the current frame of codevectors is used. If not, the codevectors from the last good frame are used. The frame's remaining decoded bits are passed to the speech decoder without modification.

Alternatively, if the last speech frame in state 0 was in the voiced mode, the long term predictor lag from the last good frame is used for all subframes in the current frame. The parameters MODE, R0, INT_LPC and the LPC coefficients are replaced with those from the last good frame. All GSP0 parameters are replaced with the GSP0_4 parameter from the last good frame. If the MODE bits for the current frame indicate voiced (MODE = 1,2 or 3), the current frame of codevectors is used. If not, the codevectors from the last good frame are used. The frame's remaining decoded bits are passed to the speech decoder without modification.

- State 2 - Same action as in state 1.
- State 3 - As in state 1 and 2, a frame repetition is performed, but the frame energy R0 (coded on the interval from 0 to 31) is decreased by a value of 2.
- State 4 - Same action as in state 3.
- State 5 - Same action as in state 3.
- State 6 - Again a frame repetition is performed. The output speech signal is muted by setting R0 to zero.
- State 7 - The speech signal remains muted, R0 remains zero.

6.4 Example solution for substitution and muting of lost SID frames

The first and second lost SID frame is replaced by the last good SID frame.

For subsequent lost SID frames the last good SID frame is repeated, but the frame energy R0 (coded on the interval from 0 to 31) is decreased with a constant value of 2 in each frame down to R0 = 0. This value is maintained if additional lost SID frames occur.

History

Document history	
March 1995	Public Enquiry PE 80: 1995-03-06 to 1995-06-30
August 1995	Vote V 86: 1995-08-21 to 1995-10-13 extended: 1995-08-21 to 1995-10-27
November 1995	Converted into Adobe Acrobat Portable Document Format (PDF)