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Network Aspects (NA); Metropolitan Area Network (MAN) Physical Layer Convergence Procedure (PLCP) for 139,264 Mbit/s Protocol Implementation Conformance Statement (PICS)

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Page 2 ETS 300 271: March 1994		
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ETS 300 271: March 1994

Contents

Fore	word			
1	Scope			
0	Nicono	C		<u>-</u>
2	Norma	tive reteren	ces	
3	Definition	ons		·····
4	Symbo	ls and abbr	eviations	
5	DICS f	or the "DLC	P for E4 based systems"	c
5	5.1	F4 relation	onship to the PLCP	
	5.2		CP frame format	
	5.3		eld definitions	
	5.4	PLCP be	ehaviour during faults	10
	5.5	PLCP be	ehaviour during DQDB layer out of service	10
	5.6	PLCP fra	aming	
		5.6.1		
		5.6.2	Physical layer frame timing operations table	11
Hiete	nr./			10
1 11310	/I V			

ETS 300 271: March 1994

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ETS 300 271: March 1994

Foreword

This European Telecommunication Standard (ETS) has been prepared by the Network Aspects (NA) Technical Committee of the European Telecommunications Standards Institute (ETSI).

This ETS details the Protocol Implementation Conformance Statement (PICS) for the Physical Layer Convergence Procedure (PLCP) for a European Metropolitan Area Network (MAN) based on the Distributed Queue Dual Bus (DQDB) access method as defined in ETS 300 212 [2] operating at a transmission rate of 139,264 Mbit/s in accordance with ETS 300 215 [1].

ETS 300 271: March 1994

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ETS 300 271: March 1994

1 Scope

[3]

This European Telecommunication Standard (ETS) defines Protocol Implementation Conformance Statement (PICS) for the Physical Layer Convergence Procedure (PLCP) at 139,264 Mbit/s for use in the context of a subnetwork of a Metropolitan Area Network (MAN) as defined in ETS 300 215 [1].

2 Normative references

This ETS incorporates, by dated or undated reference, provisions from other publications. These normative references are cited at the appropriate places in the text and the publications are listed below. For dated references, subsequent amendments to or revisions of these publications apply to this ETS only when incorporated in it by amendment or revision. For undated references the latest edition of the publication referred to applies.

[1]	ETS 300 215: "Network Aspects (NA); Metropolitan Area Network (MAN) Physical layer convergence procedure for 139,264 Mbit/s".
[2]	ETS 300 212: "Network Aspects (NA); Metropolitan Area Network (MAN) Media access control layer and physical layer specification".

IEEE Standard 802.6 (1990): "Distributed Queue Dual Bus (DQDB) Subnetwork

of a Metropolitan Area Network (MAN)".

Definitions 3

For the purposes of this ETS, the definitions as defined in IEEE Standard 802.6 [3] shall apply.

4 Symbols and abbreviations

For the purposes of this ETS, the symbols and abbreviations as defined in IEEE Standard 802.6 [3] shall apply.

Additionally, for this PICS proforma, the following abbreviations are used in defining the support type of a feature, parameter or capability:

m mandatory optional 0 conditional default value defined d n/a not applicable

When used in the column labelled "Value", the following abbreviations are defined:

from number xx to number yy xx - yy

either number xx or number yy applies, depending on the actual conditions xx/yy

For each of the conditional items, an explanation of the parameter or capability under which the feature, parameter or capability is mandatory, is given in the Clause or subclause in which the conditional items appear.

The notation X_ in the column "Support" means that numbers may be entered in this place pointing to notes which indicate deviation from the standard.

ETS 300 271: March 1994

For ease of reference, the numbering of the following Clauses is identical to that contained in ETS 300 215 [1].

5 PICS for the "PLCP for E4 based systems"

An implementation is required to conform to the functional models defined in ETS 300 215 [1] with regard to all of the externally observable effects.

5.1 E4 relationship to the PLCP

Table 1

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	E4 octets "sliding"	5.1.1	m			Y[]N[]
5.2	Octet alignment	5.1.1	m			Y[]N[]
5.3	Octet coding	5.1.1	m		111110100000 A NNN	Y[]N[]
	A = Alarm indication to the remote end bit. NNN = Three bits reserved for national use.					

5.2 The PLCP frame format

Table 2

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	Format per figure 1	5.2	m			Y[]N[] X_

Page 9 ETS 300 271: March 1994

5.3 PLCP field definitions

Table 3

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	Framing octets	5.3.1	m		1111011000101000	Y[]N[] X
5.2	Path Overhead Identification (POI) octets	5.3.2	m			Y[]N[] X_
5.3	Coding of POI octets	5.3.2 Table 1	m			Y[]N[] X_
5.4	F1 octet	5.3.3.1	m,d		0000000	Y[]N[] X_
5.5	B1 octet (BIP-8)	5.3.3.2	m			Y[]N[] X_
5.6	G1 octet FEBE	5.3.3.3	0			Y[]N[] X_
5.7	Default FEBE code (NOTE 1)	5.3.3.3	С		1111	Y[]N[]
5.8	Alarm signal G1	5.3.3.3	0			Y[]N[] X_
5.9	Default code for alarm signal (NOTE 2)	5.3.3.3	С		0	Y[]N[]
5.10	LSS in G1 octet	5.3.3.3 Table 2	m			Y[]N[] X_
5.11	Ignore invalid LSS codes	5.3.3.3	m			Y[]N[] X_
5.12	M1 and M2 octets	5.3.3.4	m			Y[]N[] X_
5.13	C1 octet	5.3.3.5	m			Y[]N[] X_
5.14	Z1-Z31 octets	5.3.3.6	m,d		0000 0000	Y[]N[] X_
5.15	Trailer octets	5.3.4	m		11001100	Y[]N[] X_

NOTE 1: The default code 1111 shall be generated if the Far End Block Error (FEBE) count is not implemented.

NOTE 2: The default code 0 shall be generated if the alarm signal is not implemented.

ETS 300 271: March 1994

5.4 PLCP behaviour during faults

This subclause provides an overview of the behaviour of the PLCP layer during transmission system faults, PLCP faults, and DQDB layer faults. Details of the behaviour of the PLCP are given in subclause 5.6.

Table 4

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	Jam signal	5.4	m		Repeating 11001100 octets	Y[]N[]
5.2	Jam signal de- tect >= 8 μs	5.4	m			Y[]N[]
5.3	Timer P x reset and started when Jam signal detected	5.4	m		1 ms ± 10 μs	Y[]N[] X_
5.4	Timer_P_x expires	5.4	m			Y[]N[] X_

5.5 PLCP behaviour during DQDB layer out of service

Table 5

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	PLCP continues normal operation	5.5	m			Y[]N[] X_
5.2	M1, M2 octets relayed unmodi- fied	5.5	m			Y[]N[] X_

5.6 PLCP framing

This subclause defines the state machine for the PLCP framing and the behaviour of the PLCP in each state of the state machine. The state machine requirements are presented first.

Table 6

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	Bus A and Bus B framing state machine provided	figure 3	m			Y[]N[] X_

ETS 300 271: March 1994

5.6.1 Link status signal operations table

Table 7 describes the behaviour of the PLCP in each state of the framing state machine; this information is in addition to requirements in subclause 11.3.1 of IEEE Standard 802.6 [3].

Table 7

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	LSS operations	5.6.1 table 3	m			Y[]N[] X_

5.6.2 Physical layer frame timing operations table

This subclause supplements the timing source information of tables 10.10(b), 10.11, and 10.12 of IEEE Standard 802.6 [3] and details the physical layer frame timing operations.

Table 8

Item	Feature	Reference	Status	Predicate	Value	Support
5.1	Frame timing operation	5.6.2 table 4	m			Y[]N[]

Page 12 ETS 300 271: March 1994

History

	Document history				
March 1994	First Edition				
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