ETSI/TC SMG

Released by : ETSI/PT 12
Release date: October 1992

### RELEASE NOTE

### Recommendation GSM 06.31

Discontinuous Transmission (DTX) for Full-Rate Speech Traffic Channels

Previously distributed version: 3.1.0 (Release 92, Phase 1) (See note below)

### 1. Reason for changes

NOTE: In some of the copies of the earlier released version (Release 92, January 1992) the last page (page 13) of the document was missing.

			,
		·	

Recommendation: GSM 06.31

<u>Title</u>: Discontinuous Transmission (DTX) for full-rate speech traffic channels

Date: February, 1992

### List of contents:

- 0. SCOPE
- 1. GENERAL
- 2. TRANSMIT SIDE
- 3. RECEIVE SIDE

ETSI/GSM Version 3.1.0

Language of original: English

Number of pages: 13

#### Detailed contents list \*\*\*\*\*\*

- 0. SCOPE \_\_\_\_
- 1. GENERAL ======
- 1.1. GENERAL ORGANISATION
- 1.2. NAMING CONVENTION
- 1.2.1. Definition of general terms 1.2.2. Definition of terms on the receive side
- 2. TRANSMIT SIDE \_\_\_\_\_\_
- 2.1. GENERAL OPERATION
- 2.1.1. Functions of the TX DTX handler
- 2.1.2. Functions of the TX radio subsystem
- 3. RECEIVE SIDE \_\_\_\_\_\_
- 3.1. GENERAL OPERATION
- 3.1.1. Functions of the RX radio subsystem 3.1.2. Functions of the RX DTX handler

## 0. SCOPE

This recommendation gives a description of the general baseband operation of full rate speech traffic channels in the transmitter and in the receiver of GSM Mobile Stations and Base Station Systems during Discontinuous Transmission (DTX).

For clarity, the description is structured according the block diagrams in figure 1 and 2. Except in the case described next, this structure of distributing the various functions between system entities is not mandatory for implementation, as long as the operation on the air interface and on the speech decoder output remains the same.

In the case of Base Station Systems where the speech transcoder is located remotely in the Base Station Controller, the implementation of the interfaces between the DTX Handlers and the Radio Subsystem (RSS) as described in this recommendation together with all their flags is mandatory, being a part of the A-bisinterface as described in recommendation GSM 08.60. In this case the various flags also serve to avoid additional delays.

The DTX functions described in this recommendation are mandatory for implementation in all GSM Mobile Stations. The receiver requirements are mandatory for implementation in all GSM Base Station Systems, the transmitter requirements only for those where downlink DTX will be used.

DTX shall be in operation in GSM Mobile Stations if commanded so by the network, see recommendation GSM 04.08.

## 1. GENERAL

Discontinuous Transmission is a mechanism which allows the radio transmitter to be switched off most of the time during speech pauses for the following two purposes:

- to save power in the Mobile Station
- to reduce the overall interference level on the air.

### 1.1. GENERAL ORGANISATION

The overall DTX mechanism described in this recommendation requires the following functions:

- a Voice Activity Detector on the transmit side,
- evaluation of the background acoustic noise on the transmit side, in order to transmit characteristic parameters to the receive side,
- generation on the receive side of a similar noise, called comfort noise, during periods where the radio transmission is cut.

The Voice Activity Detector is defined in recommendation GSM 06.32 "Voice Activity Detection", the comfort noise functions in recommendation GSM 06.12 "Comfort Noise Aspects". Both are based partly on the speech transcoder and its internal variables, defined in recommendation GSM 06.10 "GSM Full Rate Speech Transcoding".

In addition to these functions, if the parameters arriving at the receive side are detected to be seriously corrupted by errors, the speech or comfort noise must be generated from substituted data in order to avoid seriously annoying effects for the listener. This function is defined in recommendation GSM 06.11 "Substitution and Muting of Lost Frames".

An overall description of the speech processing parts can be found in recommendation GSM 06.01 "Speech processing functions - General description".

# 1.2. NAMING CONVENTION

This section lists the definitions of terms relevant for the DTX functions, as used in this and the recommendations mentioned above.

## 1.2.1. Definition of general terms

Frame: Time interval of 20 msec. corresponding to the time segmentation of the full rate speech transcoder (recommendation GSM 06.10), also used as a short term for a traffic frame.

<u>Traffic frame</u>: Block of 260 information bits (see recommendation GSM 05.03) transmitted on the full rate speech traffic channel.

SID (Silence Descriptor) frame: Frame characterized by the SID code word. It conveys information on the acoustic background noise.

<u>SID code word</u>: Fixed bit pattern defined in recommendation GSM 06.12, for labelling a traffic frame as a SID frame.

<u>SID field</u>: The bit positions defined in recommendation GSM 06.12, of the SID codeword within a SID frame.

Speech frame: Traffic frame that cannot be classified as a SID frame.

# 1.2.2. Definition of terms on the receive side

Bad traffic frame: A traffic frame flagged BFI=1 (Bad Frame Indication) by the Radio Subsystem.

Good traffic frame: A traffic frame flagged BFI=0 by the Radio Subsystem.

Good speech frame: A good traffic frame which is not an accepted SID frame.

Accepted SID frame: Traffic frame in which the SID field deviates in less than 16 bit positions from the SID code word (flag SID=2 or SID=1).

<u>Valid SID frame</u>: Good traffic frame in which the SID field deviates in less than 2 bit positions from the SID code word (flag SID=2). This frame is valid for updating of comfort noise parameters at any time.

Invalid SID frame: Accepted SID frame with BFI=1, or accepted SID frame with BFI=0, in which the SID field deviates in more than 1 bit position from the SID code word (flag SID=1). This frame is not valid for updating comfort noise parameters, but the frame conveys information that comfort noise generations should be started or continued.

<u>Unusable frame</u>: A bad traffic frame that is not an accepted SID frame.

Lost SID frame: An unusable frame received when the RX DTX Handler is generating comfort noise and a SID frame is expected (Time Alignment Flag, TAF=1).

Lost speech frame: An unusable frame received when the RX DTX Handler is passing on traffic frames directly to the speech decoder.

#### 2. TRANSMIT SIDE ---------

A block diagram of the transmit side DTX functions is shown in fig 2-1 below.

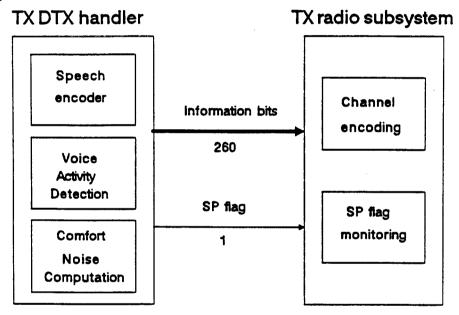


Fig 2 – 1. Block diagram of the transmit side DTX functions

### 2.1. GENERAL OPERATION

The TX DTX Handler continuously passes traffic frames, individually marked by a flag SP, to the Radio Subsystem. This binary flag is redundant to the SID code word labelling. SP=1 indicates a speech frame, SP=0 a SID frame.

The scheduling of the frames for transmission on the air interface is controlled by the radio subsystem alone, on the basis of the SP flag as described next.

## 2.1.1. Functions of the TX DTX handler

To allow an exact verification of the TX DTX handler functions, all frames before the reset of the system have to be treated as if there would have been speech frames for an infinitely long time. Therefore, the first N frames after the reset are always marked with SP=1, even if VAD=0 (hangover period, see below).

The Voice Activity Detector must be operating all the time in order to assess whether the input signal contains speech or not. The output is a binary flag (VAD=1 or VAD=0, respectively) on a frame by frame basis (see recommendation GSM 06.32).

The VAD flag controls indirectly, via the TX DTX Handler operations described below, the overall DTX operation on the transmit side.

Whenever VAD=1, the speech encoder output frame shall be passed directly to the radio subsystem, marked with SP=1.

At the end of a speech burst (transition VAD=1 to VAD=0), it takes N+1 consecutive frames to make a new updated SID frame available (see recommendation GSM 06.12). Normally, the first N speech encoder output frames after the end of the speech burst shall therefore be passed directly to the radio subsystem, marked with SP=1 ("hangover period"). The first new SID frame is then passed to the RSS as frame N+1 after the end of the speech burst, marked with SP=0 (see fig 2-2).

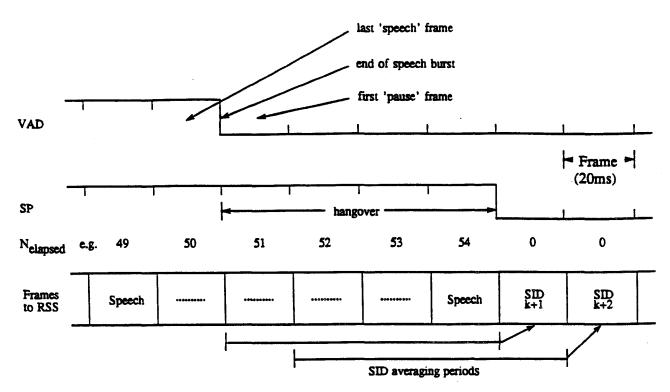


Fig 2-2. 'Normal' hangover procedure (N<sub>elapsed</sub> > 23)
(N<sub>elapsed</sub>: No. of elapsed frames since last updated SID)

If, however, at the end of the speech burst, less than 24 frames have elapsed since the last SID frame was computed and passed to the RSS, then this last last SID frame shall repeatedly be passed to the RSS, until a new updated SID frame is available (N+1 consecutive frames marked with VAD=0). This reduces the activity on the air in cases where short background noise spikes are taken for speech, by avoiding the "hangover" waiting for the SID frame computation (see also fig 2-3: Note that fig 2-3 shows as example the longest possible speech burst without hangover).

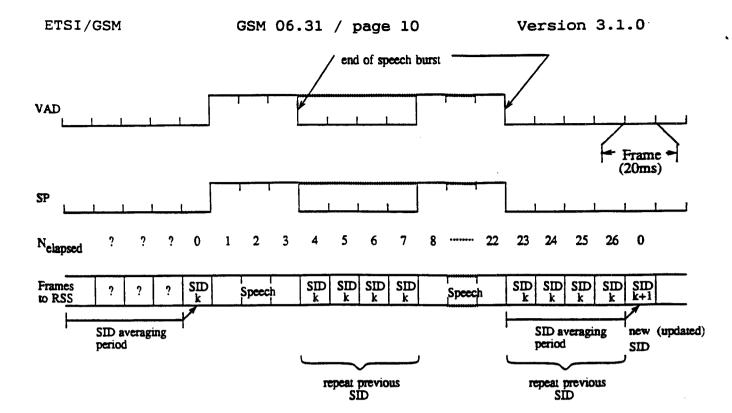


Fig 2-3. Handling of short speech bursts ( $N_{elapsed}$  < 24) (Example) ( $N_{elapsed}$ : No. of elapsed frames since last updated SID)

Once the first SID frame after the end of a speech burst has been computed and passed to the Radio Subsystem, the TX DTX Handler shall continuously compute and pass updated SID frames to the Radio

Subsystem, marked with SP=0 as long as VAD remains VAD=0.

Consequently, the speech encoder must be operating all the time.

## 2.1.2. Functions of the TX radio subsystem

The following traffic frames shall be scheduled for transmission:

- 1) all frames marked with SP=1,
- 2) the first one with SP = 0 after one or more frames with SP=1,
- 3) those marked with SP=0 and aligned with the SACCH multiframe structure as described in rec. GSM 05.08.

This has the overall function, that the radio transmission is cut after the transmission of a SID frame when the speaker stops talking. During speech pauses the transmission is resumed at regular intervals for transmission of one SID frame, in order to update the generated comfort noise on the receive side (and to improve the measurement of the link quality by the radio subsystem).

If a SID frame (SP=0), scheduled for transmission is stolen for signalling (FACCH) purposes, then the subsequent frame shall be scheduled for transmission instead.

# 3. RECEIVE SIDE

A block diagram of the receive side DTX functions is shown in fig 3-1 below.

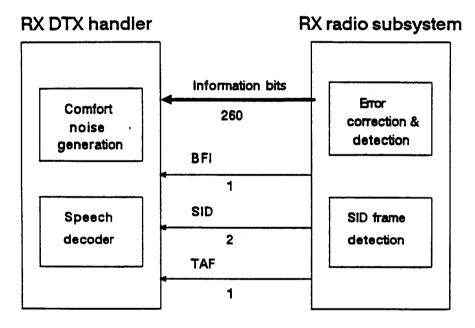


Fig 3 – 1. Block diagram of the receive side DTX functions

### 3.1. GENERAL OPERATION

Whatever their context (speech, SID, FACCH or none), the Radio Subsystem continuously passes the received traffic frames to the RX DTX handler, individually marked by various preprocessing functions with 3 flags. These are the BFI, the SID and the TAF flags described below, which serve to classify the traffic frame according to the list of terms defined in section 1.2.2. This classification, summarized in table 3-1 below, in turn allows the RX DTX Handler to determine in a simple way how the received frame is to be handled.

BFI	SID				
	2   1	0			
0	Valid   SID   frame	Good   speech   frame			
1	Invalid   SID frame	Unusable   frame			

Table 3-1. Classification of traffic frames

# 3.1.1. Functions of the RX radio subsystem

The binary BFI flag (Bad Frame Indication, see also recommendation GSM 05.05) indicates whether the traffic frame is considered to contain meaningful information bits (BFI=0) or not (BFI=1). In the context of this recommendation, a FACCH frame is considered not to contain meaningful bits and must also be marked with BFI=1. The BFI flag must fulfill the performance requirements of recommendation GSM 05.05, section 6.4.

The ternary SID flag is the output of a SID frame detector, which compares bit by bit the relevant bits of the received traffic frame (the SID field) with the SID code word defined in recommendation GSM 06.12. The flag is coded as follows, where n designates the number of bit deviations:

SID=2 when n < 2 SID=1 when 2 <= n < 16 SID=0 when n >= 16

The binary TAF flag (Time Alignment Flag) marks with TAF=1 those traffic frames that are aligned with the SACCH multiframe structure as described in the recommendations referenced in section 2.1.2.

## 3.1.2. Functions of the RX DTX handler

The RX DTX Handler is responsible for the overall DTX operation on the receive side, which shall be as follows:

- \* Whenever a good speech frame is detected, the DTX Handler shall pass it directly on to the speech decoder.
- \* When lost speech or lost SID frames are detected, the substitution and muting procedure defined in recommendation GSM 06.11 shall be applied.
- \* Valid SID frames shall result in comfort noise generation, as defined in recommendation GSM 06.12, until the next SID frame is expected (TAF=1) or good speech frames are detected. During this period, the RX DTX handler shall ignore any unusable frames delivered by the Radio Subsystem.
- \* An invalid SID frame shall be substituted by the last valid SID frame and the procedure for valid SID frames be applied.

NOTE: If the first SID frame after a speech burst (a series of good speech frames) is invalid, then the comfort noise parameters can be taken from the last valid SID frame or from the last received good speech frame which, because of the VAD hangover time (see recommendation GSM 06.32), may be supposed to contain noise only.