Methods for Testing and Specification (MTS);
The Testing and Test Control Notation version 3;
TTCN-3 Language Extensions:
Support of interfaces with continuous signals
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Foreword

This ETSI Standard (ES) has been produced by ETSI Technical Committee Methods for Testing and Specification (MTS).

The use of underline (additional text) and strike through (deleted text) highlights the differences between base document and extended documents.

The present document relates to the multi-part standard ETSI ES 201 873 covering the Testing and Test Control Notation version 3, as identified in ETSI ES 201 873-1 [1].

Modal verbs terminology

In the present document "shall", "shall not", "should", "should not", "may", "need not", "will", "will not", "can" and "cannot" are to be interpreted as described in clause 3.2 of the [ETSI Drafting Rules](https://www.etsi.org) (Verbal forms for the expression of provisions).

"must" and "must not" are NOT allowed in ETSI deliverables except when used in direct citation.
1 Scope

The present document defines the "Continuous Signal support" package of TTCN-3. TTCN-3 can be used for the specification of all types of reactive system tests over a variety of communication ports. Typical areas of application are protocol testing (including mobile and Internet protocols), service testing (including supplementary services), module testing, testing of APIs, etc. TTCN-3 is not restricted to conformance testing and can be used for many other kinds of testing including interoperability, robustness, regression, system and integration testing. The specification of test suites for physical layer protocols is outside the scope of the present document.

TTCN-3 packages are intended to define additional TTCN-3 concepts, which are not mandatory as concepts in the TTCN-3 core language, but which are optional as part of a package which is suited for dedicated applications and/or usages of TTCN-3.

This package defines concepts for testing systems using continuous signals as opposed to discrete messages and the characterization of the progression of such signals by use of streams. For both the production as well as the evaluation of continuous signals the concept of mode is introduced. Also, the signals can be processed as history-traces. Finally, basic mathematical functions that are useful for analyzing such traces are defined for TTCN-3. It is thus especially useful for testing systems which communicate with the physical world via sensors and actuators.

While the design of TTCN-3 package has taken into account the consistency of a combined usage of the core language with a number of packages, the concrete usages of and guidelines for this package in combination with other packages is outside the scope of the present document.

2 References

2.1 Normative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the referenced document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at https://docbox.etsi.org/Reference.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are necessary for the application of the present document.


2.2 Informative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the referenced document (including any amendments) applies.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

[i.1] ETSI ES 201 873-7: "Methods for Testing and Specification (MTS); The Testing and Test Control Notation version 3; Part 7: Using ASN.1 with TTCN-3".

[i.2] ETSI ES 201 873-8: "Methods for Testing and Specification (MTS); The Testing and Test Control Notation version 3; Part 8: The IDL to TTCN-3 Mapping".

[i.3] ETSI ES 201 873-9: "Methods for Testing and Specification (MTS); The Testing and Test Control Notation version 3; Part 9: Using XML schema with TTCN-3".

[i.4] ETSI ES 201 873-10: "Methods for Testing and Specification (MTS); The Testing and Test Control Notation version 3; Part 10: TTCN-3 Documentation Comment Specification".

[i.5] ETSI ES 202 784: "Methods for Testing and Specification (MTS); The Testing and Test Control Notation version 3; TTCN-3 Language Extensions: Advanced Parameterization".


3 Definition of terms, symbols and abbreviations

3.1 Terms


3.2 Symbols

Void.

3.3 Abbreviations


4 Package conformance and compatibility

The package presented in the present document is identified by the package tag:

- "TTCN-3:2012 Support for Testing Continuous Signals" - to be used with modules complying with the present document.

For an implementation claiming to conform to this package version, all features specified in the present document shall be implemented consistently with the requirements given in the present document and in ETSI ES 201 873-1 [1], ETSI ES 201 873-4 [2], ETSI ES 201 873-5 [3] and ETSI ES 201 873-6 [4].
The package presented in the present document is compatible to:

- ETSI ES 201 873-1 (V4.9.1) [1]
- ETSI ES 201 873-4 (V4.6.1) [2]
- ETSI ES 201 873-5 (V4.8.1) [3]
- ETSI ES 201 873-6 (V4.9.1) [4]
- ETSI ES 202 785 (V1.3.1) [6]
- ETSI ES 202 781 (V1.3.1) [7]
- ETSI ES 201 873-7 [i.1]
- ETSI ES 201 873-8 [i.2]
- ETSI ES 201 873-9 [i.3]
- ETSI ES 201 873-10 [i.4]
- ETSI ES 202 784 [i.5]
- ETSI ES 202 782 [i.6]

If later versions of those parts are available and should be used instead, the compatibility to the package presented in the present document has to be checked individually.

## 5 Package concepts for the core language

### 5.0 General

Systems can communicate its data or signals, either in discrete form (e.g. as an integer value) or in continuous form (e.g. real values). With respect to this difference signals are classified into four categories. The categories distinguish whether the time and value domain of a signal is of discrete or continuous nature:

1) **Analogue signals** are continuous in the time and value domain. Analogue signals are the most 'natural' signal category, characterized by physical units (e.g. current, voltage, velocity) and measured with sensors. Typical examples of the physical quantities used in the area of embedded system development are the vehicle velocity, the field intensity of a radio station etc. Analogue signals can be described as a piecewise function over time (e.g. \( v_x = f(t) \)).

2) **Time quantified signals** are discrete signals in the time domain. The signal values are defined only at predetermined time points (sampling points). Typical examples of time quantified signals are the time-value pairs of a recorded signal. A typical representation of a time quantified signal is a series or an array of real numbers. Even if the original signal is a synthetic function it can only be reconstructed from a time quantified signal with considerable mathematical effort.

3) **Value quantified signals** are time-continuous signals with discrete values. Typical examples of a value quantified signal are data that are derived from analogue signals and which are dedicated to further processing, e.g. an A/D converted sensor signal that is provided to an electrical control unit.

4) **Digital signals** are discrete on the time and value domain. If the set of possible signal values includes only two elements, one speaks about binary signals. Typical examples of binary signals are switching positions or flags.

Thus on a theoretical level, continuous and discrete evolution of time and values have to be distinguished. In a discrete system, the changes of states are processed at fixed and finite time steps. In a continuous system state changes occur for infinitesimally small time steps. Important mathematical models for continuous systems are ordinary differential equations. A mixed system, which shows continuous and discrete dynamics, is known as a hybrid system. Hybrid systems can be modelled with hybrid automata. Examples for systems that show such variable dynamics are often found in the area of embedded control systems e.g. in the automotive and aircraft industry.
In the general case, a test description notation for embedded software systems shall support all of four categories of signals mentioned above. TTCN-3 currently supports the signal categories 2) and 4). The extension of the language with respect to a support of the signal categories 1) and 3) is the content of the present document.

TTCN-3 is a procedural testing language, thus test behaviour is defined by algorithms that typically send messages to ports and receive messages from ports. For the evaluation of different alternatives of expected messages, or timeout events, the port queues and the timeout queues are frozen when the evaluation starts. This kind of snapshot semantics guarantees a consistent view on the test system input during an individual evaluation step. Whereas the snapshot semantics provides means for a pseudo parallel evaluation of messages from several ports, there is no notion of simultaneous stimulation and time triggered evaluation. To enhance the core language to the requirements of continuous and hybrid behaviour the following are introduced:

- the notions of time and sampling;
- the notions of streams, stream ports and stream variables;
- the definition of an automaton alike control flow structure to support the specification of hybrid behaviour.

5.1 Time and Sampling

5.1.0 General

The TTCN-3 extensions defined in this package adopt the concept of a global clock and enhance it with the notion of sampling and sampled time. As in TTCN-3, all time values are denoted as float values and represent time in seconds. For sampling, simple equidistant sampling models as well as dynamic sampling models are supported.

On technical level an equidistant sampling model of the form \( t = k \cdot \delta \), where \( t \) describes the time progress, \( d \) specifies the number of executed sampling steps and, \( \delta \) yields the minimal achievable step size for a given test system, is used as an overall basis to model equidistant samplings with larger step size or dynamic sampling. The basic sampling with its minimal step size \( \delta \) is a property of a concrete test system and not intended to be specified as part of the test case specification. However, as a consequence of this underlying model, a test system is able to execute user defined samplings if and only if all specified sampling rates at test specification level provide step sizes that are multiples of \( \delta \).

When using the TTCN-3 extension defined in this package, each reference to time, either used for the definition and evaluation of signals but as well by means of ordinary TTCN-3 timers, is considered to be completely synchronized to the global clock and the base sampling.

5.1.1 The now operator

For the specification of time-dependent signal sequences, it is necessary to be able to track the passage of time. The access of time is guaranteed by a globally available clock whose current value can be accessed by means of the now operator. Time progress starts at the beginning of each test case execution, thus time values are related to the start of the test case execution.

**Syntactical Structure**

```
now
```

**Semantic Description**

Evaluation of the now operator yields the current value of the clock which is the duration of time since the start of the currently running test case.

**Restrictions**

The now operator shall only be applied from within a test case, i.e. by test cases, functions and altsteps executed on test components. The now operator shall neither directly nor indirectly be called by TTCN-3 control part.
Example

EXAMPLE:

// Use of now to retrieve the actual time since the test case has started
var float actualTime := now;

5.1.2 Define the default step size for sampling

For sampling, a globally valid base sampling rate defined by the test system is provided. In addition, sampling rates can be set separately and as part of the test specification by means of `stepsize` attribute.

Syntactic Structure

`stepsize StepSizeValue`

Semantic Description

The `StepSizeValue` is a string-literal which shall contain a decimal number. This number interpreted as seconds is used as the default rate of sampling values over the stream ports to which are affected by this `stepsize` attribute. The actual sampling rate of a specific port can be changed dynamically with the `delta` operation.

Restrictions

A `stepsize` attribute can only appear in a with-annotation. A `stepsize` attribute can be applied to individual modules, test cases, groups, component types and stream port types and effects either the statements that are contained in one of these entities or in case of component types and stream port types the respective instances.

Examples

**EXAMPLE 1:**

// sets the stepsize for a module
module myModule{
    ...
} with {stepsize "0.0001"};

**EXAMPLE 2:**

// sets the stepsize for a testcase
testcase myTestcase() runs on myComponent{
    ...
} with {stepsize "0.0001"};

**EXAMPLE 3:**

// sets the stepsize for all instances of the port type StreamOut
type port StreamOut stream { out float} with {stepsize "0.0001"};

5.2 Data streams

5.2.0 General

In computer science the term data stream is used to describe a continuous or discrete sequence of data. Normally the length of a stream cannot be established in advance. The data rate, i.e. the number of samples per time unit, can vary. Data streams are continuously processed and are particularly suited to represent dynamically evolving variables over a course of time. Thus, streams are an ideal representation of the different discrete and continuous signals mentioned in the beginning of clause 5.
While in standard TTCN-3 interactions between the test components and the SUT are realized by sending and receiving messages through ports, the interaction between continuous systems can be represented by means of so called streams. In contrast to scalar values, a stream represents the whole allocation history applied to a port. In computer science, streams are widely used to describe finite or infinite data flows. To represent the relation to time, so called timed streams are used. Timed streams additionally provide timing information for each stream value and thus enable the traceability of timed behaviour. The TTCN-3 extension defined by this package provides timed streams. In the following, the term measurement (record) to denote the unity of a stream value and the related timing in timed streams will be used. Thus, concerning the recording of continuous data, a measurement record represents an individual measurement, consisting of a stream value that represents the data side and timing information that represents the temporal perspective of such a measurement.

In this TTCN-3 extension, two different but not complementary representations of timed data streams are introduced. The term timed considers the fact that the time and value domain of a signal are of interest. As a consequence, a stream is considered to consist of a sequence of samples. Each sample provides information about the timing and the value perspective of the sample:

1) Static perspective: The static perspective provides a direct mapping between a timed stream and the TTCN-3 data structures record and record of. This kind of mapping is referred to below as the static representation of a data stream and allows random access to all elements of the data stream.

2) Dynamic perspective: To provide dynamic online access to data streams, the existing concepts of TTCN-3 port type and port are extended to provide access to data streams and their content. A so called stream port references exactly one data stream and provides access to the dynamically changing values of the referenced data stream.

NOTE: To represent streams in the present document, a tabular notation is used. The table has two rows by which the first one represents the value perspective of a stream and the second represents the temporal perspective. The temporal perspective is defined by means of timestamps that are synchronized with the overall clock. The columns represent the samples of the stream.

**EXAMPLE:**

<table>
<thead>
<tr>
<th>Value</th>
<th>1.2</th>
<th>1.4</th>
<th>1.5</th>
<th>1.7</th>
<th>1.7</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0</td>
<td>0.1</td>
<td>0.2</td>
<td>0.3</td>
<td>0.4</td>
<td>0.5</td>
<td>0.6</td>
<td>0.7</td>
<td>0.8</td>
<td>0.9</td>
<td>1.0</td>
<td>1.1</td>
<td>1.2</td>
<td>1.3</td>
<td>1.4</td>
</tr>
</tbody>
</table>

The example shows a stream with the length of 1.4 seconds and float values that change between 1.0 and 1.5.

### 5.2.1 Data Streams: static perspective

A TTCN-3 data stream can be mapped directly to existing TTCN-3 data structures. The mapping considers each stream to be represented by means of a TTCN-3 record of data structure. This structure itself consists of individual entities, so called samples, each sample representing either a measurement on an incoming stream or stimulus that is dedicated to be applied to an outgoing stream.

A sample itself is represented by means of a TTCN-3 record data structure. The record consists of two fields. It has two fields of type float. The first field with the name value represents what is called the value of a stream. Its data type should be aligned with the data type of the corresponding stream. The second field denotes the temporal perspective of a sample. It denotes the temporal distance to the preceding sample (the sampling step size delta). The second field is of type float and represents time values that have the physical unit second. Example 1 shows the exemplary definition of a data structure to specify individual samples.

**EXAMPLE 1:**

```plaintext
type record Sample{
    float value,
    float delta
}
```

Given such a structure, a timed data stream of an arbitrary data type is modelled as a record of samples.

**EXAMPLE 2:**

```plaintext
type record of Sample MyStreamType;
```
The static representation of data streams can be used for the online and offline evaluation of streams as well as for the piecewise in-memory definition of streams or stream templates, which are to be applied to stream ports in the subsequent test case execution. Thus, the static representation of streams can be used to assess incoming streams and to define outgoing or reference streams and template streams mostly by means of ordinary TTCN-3 operations and control structures and as such provide an ideal interface between ordinary TTCN-3 concepts and the concepts defined in this package. Example 3 shows a short specification of a sampled stream.

EXAMPLE 3:

```tcc
var MyStreamType myStreamVar := {
    {value:=0.0, delta:=0.1},
    {value:=0.2, delta:=0.2},
    {value:=0.1, delta:=0.1},
    {value:=0.0, delta:=0.3}
}
```

If the stream definition from above is applied to an outgoing stream port directly with the beginning of a test case, the result will look as follows.

EXAMPLE 4:

<table>
<thead>
<tr>
<th>Value</th>
<th>0.0</th>
<th>0.0</th>
<th>0.2</th>
<th>0.1</th>
<th>0.0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0</td>
<td>0.1</td>
<td>0.3</td>
<td>0.4</td>
<td>0.7</td>
</tr>
</tbody>
</table>

Each stream port is initialized with a value that defines the valuation of a stream at time 0.0. Thus the first sample in Example 4 is not defined by the specification in example 3 but by the base initialization of the stream port.

NOTE 1: In order to create larger streams a manual specification approach is not feasible. In this case, the data processing capabilities of TTCN-3 can be used. This allows to programatically/algorithmically construct the dedicated record structures.

NOTE 2: The data structures presented in this clause serve for illustration purposes only. They show how timed data streams can be mapped to standard TTCN-3 data structures and thus can be processed easily by using the existing TTCN-3 language features and operators. The TTCN-3 extensions provided in this package do not include type declarations from above.

5.2.2 Data Streams: dynamic perspective

5.2.2.0 General

In standard TTCN-3 ports are used for the communication among test components and between test components and the SUT. To be able to initiate, modify and evaluate a stream based communication between the entities of a test system, this package extends the concepts of standard TTCN-3 port types and ports with the notion of stream-based communication and stream ports. Stream ports are the endpoints of a stream based communication. Thus stream ports in TTCN-3 embedded are used to provide access to streams, their values and the respective timing information. A stream port references exactly one data stream and thus provides access to the respective stream values and timing information.

5.2.2.1 Defining stream port types

The TTCN-3 port concept of message-based and procedure-based ports is extended with stream-based ports. Stream ports support stream-based communication.

**Syntactical Structure**

```tcc
type port PortTypeIdentifier stream "{" {
    ( { in | out | inout } StreamValueType [";" ] )
    ( map param "{" { FormalValuePar ["","" ] |+"" } [";" ] } |
    ( unmap param "{" { FormalValuePar ["","" ] |+"" } [";" ] } )
}"
```

**Semantic Description**

Stream port types shall be declared by using the keyword stream. Stream ports are directional. The directions are specified by the keywords in (for the in direction), out (for the out direction) and inout (for both directions).
The specified StreamValueType references the type of values which can be sent or received (depending on the direction of the port) over ports of the type PortTypeIdentifier.

Like message and procedure ports, stream ports can use map and unmap parameters to pass additional information to the system adapter.

**Restrictions**

Each stream port type definition shall have one and only one entry indicating the allowed type together with the allowed communication direction:

a) Stream port type definition shall always contain exactly one stream value definition.

b) At most one map parameter list should be defined for a port type.

c) At most one unmap parameter list should be defined for a port type.

**Example**

```
EXAMPLE:

// Stream-based port which allows stream values of type float to be received
type port StreamIn stream { in float }

//Stream-based port which allows stream values of type float to be sent
type port StreamOut stream { out float }

//Stream-based port with map and unmap parameter definitions
type port StreamOut stream {
    in float;
    map param (integer p_par1, integer p_par2);
    unmap param (integer p_par1);
}
```

5.2.2.2 Declaration and instantiation of stream ports

The declaration of stream-based ports is similar to the declaration of message-based and procedure-based ports. The component type declares which ports are associated with a component. A component type can have ports with different communication characteristics (e.g. stream-based ports, message-based ports, and procedure based). All ports are instantiated together with the component that owns the port, i.e. when the component is created.

Outgoing stream ports start to emit stream values directly after the component, which contains the respective stream port, has been started. The same applies for incoming stream ports. They start receiving data directly after their component has been started. Both incoming and outgoing stream ports are updated for each sampling step. If no explicit step size is defined by means of step size annotations on module level, test case level, port type level, etc. the port is initially sampled with the test systems' base sampling, which is the smallest available step size.

Outgoing stream ports may already be initialized before its first use, so that their values before the start of their component are defined. The initialization occurs in the context of their declaration.

Outgoing stream ports, when they are not explicitly initialized, are automatically initialized with implicit default values. The implicit default values for the various TTCN-3 basic data types can be found in table 1.

<table>
<thead>
<tr>
<th>Type</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>float</td>
<td>0.0</td>
</tr>
<tr>
<td>integer</td>
<td>0</td>
</tr>
<tr>
<td>boolean</td>
<td>FALSE</td>
</tr>
<tr>
<td>charstring</td>
<td>**</td>
</tr>
<tr>
<td>bitstring</td>
<td>'0'B</td>
</tr>
<tr>
<td>octetstring</td>
<td>'00'</td>
</tr>
</tbody>
</table>

The initial stream port value for outgoing stream port applies to the time point 0.0 and for the following sample steps as long as no other stream value is set. The value initialization for incoming streams is in responsibility of the data provider. Hence either the system adapter or the emitting component (in case of a PTC) is responsible to initialize the streams.
Syntactical Structure

```
port StreamPortTypeReference
  { StreamPortIdentifier [":=" StreamDefaultValue ] [","] }+ [";"]
```

Semantic Description

A stream port PortInstance named StreamPortIdentifier is declared inside a component type definition using a StreamPortTypeReference which is a type-reference expression for an existing stream port type. Optionally, a StreamDefaultValue can be supplied which defines the value of the stream before the first sampling over this port.

Restrictions

The StreamDefaultValue shall be of the type StreamValueType in the port type definition referenced by StreamPortTypeReference.

Examples

EXAMPLE 1:

```
type port StreamIn stream { in float }
type port StreamOut stream { out float }
type component SUT {
  port StreamIn A,B;
  port StreamOut C,D;
}
```

EXAMPLE 2:

```
type component SUT {
  port StreamIn A,B;
  port StreamOut C:=1.0,D:=2.0;
}
```

5.2.2.3 The Connect and Map operations

Stream ports can be mapped and connected. The syntax and general rules for the map and connect operations are described in ETSI ES 201 873-1 [1].

Restrictions

In addition to the general static rules of TTCN-3 given in clauses 9 and 21.1 of ETSI ES 201 873-1 [1], the following restrictions apply:

a) Stream ports can be connected or mapped to stream ports only. Connection or mapping between a stream port and a message port is not allowed.

b) Assuming the following:

1) Ports PORT1 and PORT2 are the stream ports to be connected or mapped;
2) Inval-PORT1 defines the value type of the in-direction of PORT1;
3) Outval-PORT1 defines the value type of the out-direction of PORT1;
4) Inval-PORT2 defines the value type of the in-direction of PORT2; and
5) Outval-PORT2 defines the value type of the out-direction of PORT2; and
6) If no value type is defined for a direction, the value type is considered to be undefined. When checking conditions for stream port connecting and mapping, the undefined type is equal to the undefined type only.

c) The `connect` operation is allowed if and only if:

```
outval-PORT1 = inval-PORT2 and outval-PORT2 = inval-PORT1
```
d) The **map** operation is allowed if and only if:

\[
\text{outval-PORT1} = \text{outval-PORT2} \text{ and inval-PORT2} = \text{inval-PORT1}
\]

e) In all other cases, the connect and map operations shall not be allowed.

f) Incoming stream ports of test components and outgoing stream ports of the system adapter cannot be

connected or mapped to more than one port.

**NOTE:** The restriction on the number of connected and mapped ports does not apply to outgoing stream ports of
test components and incoming ports of the system adapter, making stream broadcast possible.

### 5.2.3 Data Streams: access operations

#### 5.2.3.0 General

Similar to **message-based** and **procedure-based** communication incoming streams can be examined and outgoing

streams can be controlled. In general, access to the actual sample of a stream (i.e. the stream value, the respective timing
and sampling information) is provided by means of **stream data operations**. Moreover, access to the preceding samples
by means of dedicated **navigation operations** is provided. Last but not least, record structured stream data can be

extracted as explained in clause 5.2.1 by means of **stream evaluation statements**.

In contrast to message-based and procedure-based communication, **stream data operations** and **stream navigation
operations** on expression level have been integrated. This allows testers to directly assign values to streams and read

values from streams by means of ordinary TTCN-3 assignments.

#### 5.2.3.1 The value operation

Each data stream connected to a stream port allows accessing its current value by means of the **value** operation. In

case of incoming streams, the value operation yields the actual value that is available at a stream port.

**Syntactical Structure**

\[(\text{StreamPortReference} \mid \text{StreamPortSampleReference}) \text{ "." value}\]

**Semantic Description**

The **value** operation can be applied to either a **StreamPortReference** expression or a **StreamPortSampleReference**

expression which is yielded by the application of a navigation operation on a **StreamPortReference**. In the first case, it

yields the current value of the stream port; in the second case it yields the value in the referenced sampling.

When using a **StreamPortReference** to an outgoing stream port, the **value** operation expression can also be used on the

left hand side of an assignment or as an out parameter to a function.

When using a **value** operation expression as a value expression the type of the value is the **StreamValueType** of the

referenced stream port.

If the value operation is used for setting the actual output value of a stream, the effectiveness of the stream port

evaluation is delayed. A value, which has been assigned to a stream port value handle, becomes effective inside and

outside the component at the beginning of the next sampling step.

**Restrictions**

If the **value** operation expression is used as the target of an assignment, the type of the assigned value shall be

compatible with the **StreamValueType** of the referenced stream port.

**Examples**

EXAMPLE 1:

```
// accessing the actual input value of a stream
var float myVar:=streamInPort.value;
```
EXAMPLE 2:

```java
if (streamInPort.value >= 100.0) {...};
```

NOTE 1: The value, which is provided by means of the `value` operation, is the value that has been measured at the beginning of the actual sampling period.

EXAMPLE 3:

```java
streamOutPort.value := 100.0;
```

NOTE 2: The use of the `value` operation can be combined in such a way that the specification of complex equations and equation systems is supported.

EXAMPLE 4:

```java
voltage.value := amperage.value * resistance.value;
```

5.2.3.2 The timestamp operation

Similar to the `value` operation the `timestamp` operation allows to access the time related information of the actual sample.

**Syntactical Structure**

```java
(StreamPortReference | StreamPortSampleReference) "." timestamp
```

**Semantic Description**

The `timestamp` operation can be applied to a stream port referenced by a `StreamPortReference` expression or a `StreamPortSampleReference` referring to a specific sample of a stream port.

The application of the `timestamp` operation on a `StreamPortReference` yields the exact time point at which the actual stream port value has been measured. The application of the `timestamp` operation on a `StreamPortSampleReference` yields the exact time point at which the referenced sample has been measured. The exact sample time denotes the moment when a stream value has been made available at the test system's input and thus strongly dependent on the sampling rate.

The time point is provided as a floating-point number (`float`) and has the physical unit seconds. The time information is completely synchronized with the test system clock described in clause 5.1.

**Restrictions**

The `timestamp` operation always yields a non-negative `float` value.

**Example**

```java
var float measurementTime1 := streamport.timestamp;
```

NOTE: Data streams are used to represent samples in a dynamic measurement process. A sample that is taken from a data stream is usually historical information, i.e. the result of a `timestamp` operation refers to the state of the system (i.e. the SUT) at a time in the past.

5.2.3.3 The delta operation

The step size of a data stream can dynamically change during a test execution. The change can be initiated either by the test specification or by means of the measurement system (i.e. the system adapter). The `delta` operation provides access to the actual step size of a port.
In addition to the timestamp operator TTCN-3 embedded allows to obtain the step size that has been used to measure a certain value. This information is provided by the delta operation. The delta operation can be used in a similar way than the value and the timestamp operation. It returns the size of the last sampling step (in seconds).

**Syntactical Structure**

```
(StreamPortReference | StreamPortSampleReference) "." delta
```

**Semantic Description**

When used on a StreamPortReference, the delta operation allows read and write access to the actual step size of a port. When the delta operation is used for reading on a StreamPortReference, it yields the actual step size for a given port. When the delta operation is used for writing on a StreamPortReference it sets the length of the step size for future writing and reading at the given port. The step size is defined as a float number and has the unit seconds.

When used on a StreamPortSampleReference it yields the actual step size active at the time of the referenced sample measurement.

A value, which has been assigned to a stream port delta handle, affects the length of the next sampling period, not the actual one. Thus, it cannot be used to shorten or lengthen the actual sampling step.

**Restrictions**

When used on a StreamPortSampleReference, the delta operation only allows read access.

**Examples**

**EXAMPLE 1:**

```
var float actualStepSize;
// reads the actual stream size from a port
actualStepSize = streamport.delta;
```

**EXAMPLE 2:**

```
// sets the actual step size for a port
streamport.delta:= 0.001;
```

### 5.2.4 Data Streams: navigation operations

#### 5.2.4.0 General

Besides access to the actual values of a stream, additional access to the history of streams by means of so called stream navigation operations is provided. The result of a navigation operation is a handle, which allows the application of the value, timestamp or delta operation for preceding stream states. Such a state is identified by means of two different operations. The at operation demands a time index of type float that denotes the time that has passed since the beginning of the test case. The prev operation backtracks the sample steps beginning with the actual step and demands an integer index value to define the number of sampling steps to step back.

#### 5.2.4.1 The prev operation

The prev operation returns a handle to obtain stream related information for previous states of a stream.

**Syntactic Structure**

```
StreamPortReference "." prev [ "(" PrevIndex ")" ]
```

**Semantic Description**

The prev operation can be applied to a stream port StreamPortReference. It can optionally be parameterized with an integer index parameter PrevIndex and returns a StreamPortSampleReference handle to retrieve values, timestamps and sampling step sizes for preceding stream states. The index parameter denotes the number of samples to step back in stream history. If no parameter list is given, this is equivalent with the index 1.
Restrictions

The `prev` operation can only appear as an operand to a `value`, `timestamp` or `delta` read operation.

NOTE 1: The application of the `prev` operation needs the combination with the `value` operation, the `timestamp` operation or the `delta` operation to provide meaningful results.

Examples

EXAMPLE 1:

```c
port.prev(0).value; // provides access to the actual stream value
port.prev.value; // provides access to the previous stream value
port.prev(1).value; // provides access to the previous stream value
port.prev(2).value; // provides access to the stream value 2 steps ago
```

NOTE 2: The expressions `port.prev` and `port.prev(1)` yield identical results.

EXAMPLE 2:

```c
port.prev(0).timestamp; // provides access to the timestamp
// that denotes the beginning the actual sampling step
port.prev(0).delta; // provides access to the length of the last sampling step
port.prev(1).timestamp; // that denotes the beginning the preceding sampling step
port.prev(1).delta; // provides access to the length of the sampling step 2 steps ago
```

EXAMPLE 3:

<table>
<thead>
<tr>
<th>Value</th>
<th>1.2</th>
<th>1.4</th>
<th>1.5</th>
<th>1.7</th>
<th>1.7</th>
<th>1.5</th>
<th>1.2</th>
<th>1.1</th>
<th>1.4</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0</td>
<td>0.1</td>
<td>0.2</td>
<td>0.3</td>
<td>0.4</td>
<td>0.5</td>
<td>0.6</td>
<td>0.7</td>
<td>0.8</td>
<td>0.9</td>
<td>1.0</td>
<td>1.1</td>
<td>1.2</td>
<td>1.3</td>
</tr>
</tbody>
</table>

```c
port.prev(0).value; // yields 1.4
port.prev.value; // yields 1.1
port.prev(1).value; // yields 1.1
port.prev(2).value; // yields 1.0
```

```c
port.prev(0).timestamp; // yields 1.4
port.prev(0).delta; // yields 0.1
port.prev(1).timestamp; // yields 1.3
port.prev(1).delta; // yields 0.1
```

5.2.4.2 The `at` operation

The `at` operation returns a handle to obtain stream related information for previous states of a stream, which are identified by means of a timestamp value.

Syntactical Structure

```
StreamPortReference "." at [ "(" Timepoint ")" ]
```

Semantic Description

The `at` operation can be applied to a stream port `StreamPortReference`. The `at` operation can optionally be parameterized with a `float` parameter `Timepoint` and returns a `StreamPortSampleReference` handle to retrieve values, timestamps and sampling step sizes for preceding stream states. The `Timepoint` parameter represents a time stamp that identifies a sample at a certain place in time. The time stamp denotes the time that has passed since the start of the test case (see clause 5.1). It references the sample that has either the same time stamp or, if such a sample does not exist, the sample with the next smaller time stamp.

Restrictions

The `at` operation can only appear as an operand to a `value`, `timestamp` or `delta` read operation.

NOTE: The application of the `at` operation has to be done in combination with a `value` operation, a `timestamp` operation or a `delta` operation to provide meaningful results.
Examples

EXAMPLE 1:

```c
port.at(now).value; // provides access to the actual stream value
port.at(0).value;  // provides access to the initial stream value
port.at(10.0).value; // provides the stream value at the time point 10.0
                    // (i.e. 10. Seconds after the beginning of the test case)
```

EXAMPLE 2:

```c
port.at(now).timestamp; // provides access to the beginning of the actual sampling step
port.at(0).timestamp;   // provides access to the beginning of the initial sampling
                         // (i.e. always 0.0)
port.at(10.0).timestamp; // provides access to the beginning of the sampling step
                         // at time point 10.0
```

EXAMPLE 3:

```c
<table>
<thead>
<tr>
<th>Value</th>
<th>1.2</th>
<th>1.4</th>
<th>1.5</th>
<th>1.7</th>
<th>1.7</th>
<th>1.5</th>
<th>1.2</th>
<th>1.1</th>
<th>1.4</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0</td>
<td>0.1</td>
<td>0.2</td>
<td>0.3</td>
<td>0.4</td>
<td>0.5</td>
<td>0.6</td>
<td>0.7</td>
<td>0.8</td>
<td>0.9</td>
<td>1.0</td>
<td>1.1</td>
<td>1.2</td>
<td>1.3</td>
</tr>
</tbody>
</table>
```

```c
port.at(now).value;      // yields 1.4
port.at(0).value;        // yields 1.2
port.at(1.0).value;      // yields 1.5
port.at(1.09).value;     // yields 1.5
port.at(now).timestamp;  // yields 1.4
port.at(0).timestamp;    // yields 0.0
port.at(1.09).timestamp; // yields 1.0
```

5.2.5 Data Streams: extraction and application operations

5.2.5.0 General

Beside access to individual values of a stream, this package supports the extraction and application of stream segments that are represented by means of the record of data structure (data perspective) described in clause 5.2.1. The history operation allows to extract arbitrary stream segments. The apply operation is used to apply extracted or manually or programmatically defined stream segments to stream ports.

5.2.5.1 The history operation

The history operation allows obtaining the complete or partial history of a stream as a TTCN-3 record of structure (see clause 5.1, data representation). The history operation has two parameters that denote the start time and end time of the desired stream segment.

**Syntactical Structure**

```
StreamPortReference "." history "(" StartTime "," EndTime ")"
```

**Semantic Description**

The history operation provides a record of based sample representation of a stream. The operation has two parameters StartTime and EndTime that denote the start time and end time of the stream segment that is designated for export. The parameters are each of type float and represent the time that has passed since the beginning of the respective test case. Time values are given in units of seconds. The first parameter describes the measurement time of the first stream entry to be considered for history export. The second parameter denotes the time of the last record. If the specified start time value is greater than the specified end time value the history operation results in an empty record of structure.

**Restrictions**

The EndTime parameter shall not have a value greater than now.
Examples

EXAMPLE 1:

```c
myStreamRec := myPort.history(0.0, now);
```

EXAMPLE 2:

```c
type record BoolSample { boolean v, float t };
type port BoolStreamType stream { in boolean };
type component MyStreamComponent { port myPort BoolStreamType };
var record of BoolSample myStreamRec;

myStreamRec := myPort.history(0.0, now);
```

EXAMPLE 3:

```c
<table>
<thead>
<tr>
<th>Value</th>
<th>1.2</th>
<th>1.4</th>
<th>1.5</th>
<th>1.7</th>
<th>1.8</th>
<th>1.9</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0.0</td>
<td>0.1</td>
<td>0.2</td>
<td>0.3</td>
<td>0.4</td>
<td>0.5</td>
<td>0.6</td>
<td>0.7</td>
<td>0.8</td>
</tr>
</tbody>
</table>

myStreamRec := port.history(0.0, now);
```

```c
// yields
// [ {1.2, 0.0}, {1.4, 0.1}, {1.5, 0.1}, {1.7, 0.1}, {1.8, 0.1}, {1.9, 0.1}, {1.5, 0.1}, {1.2, 0.1}, {1.0, 0.1},
// {1.1, 0.1}, {1.4, 0.1}, {1.5, 0.1}, {1.2, 0.1}, {1.0, 0.1}, {1.1, 0.1}, {1.4, 0.1} ]
```

5.2.5.2 The values operation

The `values` function allows obtaining the complete or partial history of a stream as a TTCN-3 `record of` structure without any timing information.

### Syntactical Structure

```
StreamPortReference "." values "(" StartTime "," EndTime ")"
```

### Semantic Description

The value operation has two parameters `StartTime` and `EndTime` that denote the start time and end time of the desired stream segment.

The `history` function provides a `record of` based value representation of a stream. The parameters are each of type `float` and represent the time that has passed since the beginning of the respective test case. Time values are given in units of seconds. The first parameter describes the measurement time of the first stream entry to be considered for history export. The second parameter denotes the time of the last record. If the specified start time value is greater than end time value the `history` operation results in an empty `record of` structure.

The result of the value operation applied to a stream port of type `T` is a value of `record of T`.

### Restrictions

The `EndTime` parameter shall not have a value greater than `now`.

### Examples

EXAMPLE 1:

```c
myStreamRec := port.values(0.0, now);
```

EXAMPLE 2:

```c
type port BoolStreamType { in boolean };
type component { port myPort BoolStreamType }
var record of boolean myStreamRec;

myStreamRec := myPort.values(0.0, now);
```
**EXAMPLE 3:**

<table>
<thead>
<tr>
<th>Value</th>
<th>1.2</th>
<th>1.4</th>
<th>1.5</th>
<th>1.7</th>
<th>1.7</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
<th>1.5</th>
<th>1.2</th>
<th>1.0</th>
<th>1.1</th>
<th>1.4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timestamp</td>
<td>0</td>
<td>0.1</td>
<td>0.2</td>
<td>0.3</td>
<td>0.4</td>
<td>0.5</td>
<td>0.6</td>
<td>0.7</td>
<td>0.8</td>
<td>0.9</td>
<td>1.0</td>
<td>1.1</td>
<td>1.2</td>
<td>1.3</td>
<td>1.4</td>
</tr>
</tbody>
</table>

myStreamRec := port.history(0.0, now);
// yields
// {1.2, 1.4, 1.5, 1.7, 1.7, 1.5, 1.2, 1.0, 1.1, 1.4, 1.5, 1.2, 1.0, 1.1, 1.4}

### 5.2.5.3 The apply operation

The apply operation is used to apply stream data to a stream port that are represented by means of a TTCN-3 *record* of structure. The apply operation applies the sample records contained in the *record* of data structure one after the other in time to the given port.

**Syntactical Structure**

StreamPortReference "." apply "("Samples")"

**Semantic Description**

Application of the *apply* operation to the stream port `StreamPortReference`, it will consecutively write the values of the given *record* of *Samples* to the port, using the sampling deltas from *Samples* as deltas for writing the values, as well.

The application of an apply operation `p.apply(v)` is equivalent to the following construction:

```plaintext
var float v_nextSample := p.timestamp + p.delta; // time of the scheduled next step
for (var integer i := 0; i < lengthof(v); i := i + 1) {
    if (i + 1 < lengthof(v)) {
        p.delta := v[i + 1].delta; // schedule delta for the next step
    }
    // value will become efficient at the beginning of the next sampling step
    p.value := v[i].value;
    wait(v_nextSample); // wait for the current sampling step to finish
    if (i + 1 < lengthof(v)) {
        // time of the next sampling step
        v_nextSample := v_nextSample + v[i + 1].delta;
    }
}
```

**Examples**

**EXAMPLE 1:**

```plaintext
type port FloatIn {in float}
type port FloatOut {out float}

type component {
    port myInPort FloatIn;
    port myOutPort FloatOut
}

type record Sample {boolean value, float delta};
var record of Sample myStreamRec;
testcase myTestcase () runs on tester {
    // measure on all incoming ports for 100 seconds
    wait(100.0);
    // get the all sampless at myInport until now
    myStreamRec := myInPort.history(0.0, now);
    // and apply the measured data to myOutPort.
    myOutPort.apply(myStreamRec); // lasts 100 seconds
}
```

**EXAMPLE 2:**

```plaintext
var MyStreamType<float> myStream := {
    (0.0, 0.1),
    (0.2, 0.2),
    (0.1, 0.1),
    (0.0, 0.3)
}
port.apply(myStream);
// yield -> see table below
```
5.2.6 Port control operations

This clause specifies the rules for port control operation in case they are applied to a stream port. The operations behave differently specified in the clause 22.5 of ETSI ES 201 873-1 [1] as steam ports do not have any queues, but might contain sampling history.

The close operation applied to a stream port removes the port history completely. Only the last acquired sample is kept and it is still possible to access it with the value and timestamp operations.

The start operation applied to a stream port removes port history completely, activates port sampling (if it was suspended by the stop or halt operation) and allows the use of data stream access operation (value, timestamp, delta), data navigation operations (prev, at) and data extraction and application operations (history, values, apply). The started port will have its default value.

The stop operation applied to a stream port removes port history and suspends port sampling, i.e. port history will not be updated while the port is stopped. In case of stopped out ports, the value of all ports connected or mapped to the stopped port will not change while the port is stopped. During the time when the port is stopped, it is not allowed to call any of the data stream access operation (value, timestamp, delta), data navigation operations (prev, at) and data extraction and application operations (history, values, apply). Calling any of these operations shall cause an error.

The halt operation applied to a stream port suspends port sampling, i.e. port history will not be updated while the port is halted. In case of halted out ports, the value of all ports connected or mapped to the halted port will not change while the port is halted. During the time when the port is halted, it is not allowed to use any of the data stream access operation (value, timestamp, delta) on the left hand side of an assignment and the apply operation. Calling any of these operations shall cause an error. The history of the halted port is not discarded and it possible to use any of the data stream access operation (value, timestamp, delta) if they occur on the right hand side of an assignment, data navigation operations (prev, at) and data extraction operations history and values.

5.2.7 Stream ports in static configurations

Components containing stream ports can be used in static configurations specified in ETSI ES 202 781 [7]. Most of the rules valid for non-static components apply in this case too, with the following differences:

a) Time progress for static MTCs starts in the beginning of configuration function (and not in the beginning of a test case).

b) Sampling of static ports shall be active even when a test case is not running (during transition between test cases).

5.3 The assert statement

The assert statement is used as a short hand for the specification of expected system behaviour.

Syntactical Structure

```
assert "(" Predicate { "," Predicate } ")"
```

Semantic Description

The assert statement specifies one or a list of predicates that express the expectation on the SUT. A predicate consist of an arbitrary TTCN-3 boolean expression. If one of the predicates fail, the assert statement automatically sets the verdict to fail. The assert statement is allowed at any place in the TTCN-3 source code that allows the application of the setverdict statement. To assess continuous data it will be used in particular within the hybrid machine alike control flow structures described in clause 5.4.
NOTE: The semantics of the assert statement can be mapped to existing TTCN-3 statements in the following way:

\[
\text{assert (pred1, pred2, ..., predn)};
\]

is fully equivalent to:

\[
\text{if (! pred1) setverdict(fail);} \\
\text{if (! Pred2) setverdict(fail);} \\
\vdots \\
\text{if (! predn) setverdict(fail);} \\
\]

**Examples**

**EXAMPLE 1:**

```
assert(a.value==4.0);
```

**EXAMPLE 2:**

```
assert(a.value==4.0, b.value ==5.0, d.value ==445.0);
```

## 5.4 Control structures for continuous and hybrid behaviour

### 5.4.0 General

This clause introduces control flow structures that allow the parallel and sampled application and assessment of stream values at ports. The concepts defined in clauses 5.1, 5.2 and 5.3 allow the construction, application and assessment of individual streams. For more advanced test behaviour, such as concurrent application and assessment of multiple streams and the detection of complex events (e.g. zero crossing or flag changes at multiple ports), stronger concepts are needed. For this purpose, the concepts defined in the last clauses are combined with state-machine-like specification concepts, so called **modes**.

A **mode** expresses a certain runtime mode of a system or an SUT. This kind of runtime mode is characterized by a defined behaviour at ports and a set of predicates that limit the applicability of the behaviour. Unlike ordinary behavioural TTCN-3 statements, a mode applies its behaviour over time (at least for one sampling step).

### 5.4.1 Modes

#### 5.4.1.0 General

The term **mode** is used to specify the discrete and countable macro states of a dynamic hybrid system. It mainly serves to distinguish the macro states of a hybrid system from the theoretically infinite number of micro-states. By means of modes, this package provides a layer of abstraction that helps distinguishing between the discrete changes of a hybrid system (or test system) that are relevant from the users (and testers) perspective and the discrete changes that are introduced by the underlying test execution environment in order to map continuous behaviour to a computational environment (which is naturally discrete). The interpretation and calculation of micro steps depend on the underlying technical environment, i.e. the sampling. Thus, a micro step is calculated by the combination of the active macro-states with the sampled evaluation of data at the stream ports.
If the velocity v remains constant for more than 5 sec., it shall not underrun the limit x for 5 seconds.
To detect: the velocity remains constant for more than 5 seconds
To check: v shall not underrun the limit x for 5 seconds

Figure 1: Abstract test specification for a continuous system that show the values v and x

Modes and the transitions between modes can be written down in a state-machine-like structure, which is closely defined in the theory of hybrid automata. Figure 1 shows an abstract test specification that consists of three atomic modes, transitions, invariants and assertions.

For realizing such hybrid automata, three new block statements are introduced, the cont statement, the seq statement and the par statement. While the cont statement is used for the specification of atomic modes, the par and seq statement are used to aggregate modes to larger constructs by means of parallel and sequential composition.

Modes in general are characterized by their duration and their internal behaviour (i.e. the assignment and assessment of values at stream ports). The duration, or better the duration of the mode's activity, is defined by a set of predicates, which relates to time or the valuation of (stream) ports, variables, etc.

**Syntactical Structure**

```
( cont | par | seq ) "{"  
  [Declaration]  
  [OnEntryBlock]  
  [InvariantBlock]  
  Body  
  [OnExitBlock]  
  "}"  
  [UntilBlock]
```

A mode specification consists of several syntactical compartments:

- local declarations to be used inside the mode;
- an optional onentry block, that defines behaviour that has to be executed once at the activation of the mode;
- an optional invariant block that defines predicates that should not be hurt while the mode is active;
- an obligatory body to specify the mode's internal behaviour;
- an optional onexit block that defines the behaviour that has to be executed once at the deactivation of the mode; and
- an optional transition block (UntilBlock) that defines the exit conditions to end the mode's activity.

Atomic modes may be composed to composite modes. Composite modes show nearly the same structural setup as atomic modes. The only differences refer to their behavioural descriptions. While atomic modes contain assignments, assert statements and the inv, onexit, onentry blocks described above, composite modes contain other modes instead of statements. As far as invariants, onentry and onexit blocks and transitions are concerned, the structural setup and the behaviour of composite modes both are identical to atomic modes.
**Semantic Description**

While a mode is active, each invariant of a composite mode has to hold. Additionally, each transition of a composite mode ends the activity of the mode when it applies.

When a mode is entered, its onentry-block is executed. When a mode is exited, its onexit-block is executed.

For every step of an active mode, the contents (either modes or statements) of the mode are executed. Modes always use the base sampling rate when processing steps. The `stepsize` attribute has no effect on the mode sampling rate.

**NOTE:** Mode sampling is just a theoretical concept for describing behaviour of the mode statement. The way how TTCN-3 tools perform mode sampling is implementation specific. It is possible e.g. to implement mode sampling so that it is automatically triggered after port sampling or by a receiving event that has occurred on a referenced port.

**Examples**

Example 1 shows the definition of an atomic mode consisting of two assignments to stream ports, an invariant that checks the state of an outgoing stream port, an `onentry` block that initializes the variable `x`, and an `onexit` block that resets the stream port `to_Set_Point` to the value of `0.0`, and transitions that check the valuation of an incoming stream port.

**EXAMPLE 1:**

```c
cont{//body
  onentry{x:=10.0;}
  inv{//invariant
to_Set_Point.value>20000.0;
}
to_Set_Point.value:=3.0*now;
to_Engine_Perturbation.value:=0.0+x;
onexit{to_Set_Point.value:=0.0}
} until{//transition
  [ti_Engine_Speed.value>2000.0]{to_Engine_Perturbation.value:=2.0;}
  [ti_Engine_Speed.value>3000.0]{to_Engine_Perturbation.value:=1.0;}
}
```

Example 2 shows the setup of a parallel mode that contains two sequential modes, which each of them containing further atomic modes.

**EXAMPLE 2:**

```c
par { // overall perturbation and assessment
  inv{//invariant
}
  seq{// perturbation sequence
    cont{// stimulation action 1}
    cont{// stimulation action 2}
  }
  seq{// assessment sequence
    cont{// assessment action 1}
    cont{// assessment action 1}
  }
} until{//transition
}
```

**5.4.1.1 Definition of the until block**

**5.4.1.1.0 General**

The `until` block allows the specification of exit conditions for modes and additionally the specification of explicit transitions between modes. The entries of the until block are called `transitions`. Each transition specifies conditions for their activation (i.e. guards and trigger events) and may provide an explicit definition of the mode that has to be activated next (target mode). An `until` block can contain several alternative transitions that each specify different exit conditions and target modes.
5.4.1.1.1 Definition of transition guards and events

The until block defines a number of transitions between modes. A transition contains either a guard or a trigger event specification or both. The guard and the trigger event specification are both used to determine whether a transition can fire or not. A guard is modelled as a boolean TTCN-3 expression. A trigger event is modelled by means of TTCN-3 receiving operations (receive statement, trigger statement, getcall statement, etc.). The predicate or the TTCN-3 receiving operations may be followed by an optional statement block, which contain instructions to be executed upon activation of the transition. At the end of the transition there may be a goto clause which specifies the follow-up mode.

Syntactical Structure

until "{" [Guard] [" [TriggerEvent] [StatementBlock] [goto Target] ] "}*

Semantic Description

A transition is considered to be activated if the guard expression is satisfied and a valid receiving event occurred at the specified TTCN-3 receiving operation and the invariant of the target mode holds (with the exception of the notinv predicate, see clause 5.4.1.5 for more details). Transitions are checked for each active mode at each sampling step. If a transition becomes active then the optional statement block is executed once. Afterwards the enclosing mode and all his child modes are deactivated. The control flow is continued with the activation of the follow-up mode. The transitions in an until block are checked in the given order. If multiple transitions exist, the first transition that fulfils the activation conditions is activated.

Restrictions

In addition to the general semantic rules the following restrictions apply:

- The functions invoked from the guard statement or trigger event shall not use any blocking instructions (i.e. the following operations and statements: all receiving operations, timeout, done, killed, wait and mode). Such constructs may block evaluation of the guard or trigger with the consequence, that the next sampling step is missed.
- In the optional statement block of a transition any TTCN-3 statement is principally allowed, except each type of control flow related statement that leads to the leaving of the enclosing mode (e.g. goto, return).

Example

EXAMPLE:

```tcc
cont{ //mode
A.value:=3;
}
until { // transitions
[C.value > 4.0] MPort1.receive(TemplExp) { log(" statement block 1" ); } 
[C.value > 4.0 and D.value > E.value] { log(" statement block 1" ); } 
[] Port2.receive(TemplExp) { log(" statement block 1" )}; }
```
Restrictions

Besides the restrictions that already exist for the use of the goto statement, this package defines additional restrictions for the use of the goto clause in the context of modes. Goto jumps are only allowed in a sequential environment, either inside seq modes or on the top level of a composition, i.e. directly on testcase level. Moreover, goto jumps are not allowed to violate the composition hierarchy, thus it is not possible to jump to a parent mode or into a child mode. Jumps are only allowed between modes on the same hierarchy level.

However, if no follow up mode is explicitly defined by means of a goto statement the sequential ordering of mode specification implicitly defines the follow up mode. Thus, when two atomic modes follow each other in the specification, the second mode is the follow up mode for all active transition transitions of the preceding mode that do not have an explicit goto clause.

Examples

Example 1 shows the application of labels and goto statements in the context of modes.

EXAMPLE 1:

```
label state1;
cont{ //mode
  A.value:=3;
} until{[C.value > 2.0]}
label state2;
cont{ //mode
  A.value:=4;
} until { // transitions
  [C.value > 4.0] { log(" statement block 1" ); } goto state1
  [D.value > E.value] { log(" statement block 2" ); } goto state2
  [] Port2.receive(TemplExp) { log(" statement block 1" ); }
}
```

EXAMPLE 2:

```
cont{ A.value:=3;} until {
  [B.value >3]
cont{ A.value:=5;} until {
  [C.value >=3*D.value]
cont{ A.value:=7;} until {
  [C.value >=3]}
```

5.4.1.1.3 The repeat statement

The control flow of a mode’s transition’s statement block may end in a repeat statement.

Semantic Description

The repeat statement causes the re-execution of a par statement, seq statement or cont statement, i.e. the execution of the par statement, seq statement or cont is activated again and executed with the next sampling step.

NOTE 1: In case of the execution of the repeat statement the local time of the respective mode (see duration symbol in clause 5.4.1.3) is reset, in case of composite modes the child modes are first deactivated and then again activated according to the kind (parallel or sequential) of the mode. Moreover, the respective onentry and onexit blocks are executed.

Example

EXAMPLE:

```
cont{ //mode
  A.value:=4;
} until { // transitions
  [C.value > 4.0] { log(" statement block 1" ); } goto state1
  [D.value > E.value] { log(" repeat the execution" ); repeat}
  [] Port2.receive(TemplExp) { log(" statement block 1" ); }
}
```

NOTE 2: The repeat statement is functional equivalent to the use of a goto clause that addresses a label directly above the current mode.
5.4.1.1.4 The continue statement

The control flow of a mode's transition's statement block may end with a `continue` statement.

**Semantic Description**

The `continue` statement causes the further execution of a `par` statement, `seq` statement or `cont` statement, i.e. the execution of the `par` statement, `seq` statement or `cont` is continued with the next sampling step without a reset to the local time (see duration symbol in clause 5.4.1.3). The `onentry` and `onexit` blocks are not executed.

**Example**

```plaintext
EXAMPLE:
cont{ // mode
    A.value:=4;
} until { // transitions
    [C.value > 4.0] { log(" statement block 1" ); } goto state1
    [D.value > E.value]{ log(" continue the execution" ); continue} 
    [] Port2.receive(TemplExp) { log(" statement block 1" ); }
}
```

5.4.1.2 Definition of invariant blocks

**Syntactical Structure**

```plaintext
inv "{" Predicate "," Predicate } "
```

**Semantic Description**

An invariant block contains boolean predicates (expressions) which characterize the applicability of a mode. Thus, an invariant block is always related to its containing mode specification and it specifies the conditions that shall be valid for a mode during runtime.

For each mode, all invariants are checked for each sampling step when the mode is active. While a mode is active the invariants of a mode shall not be violated. The invariant block is always checked at the beginning of each sampling step, even before the body of each mode is executed. Violation of the invariant causes that the body of the mode is not executed and processing continues with the `until` clause which shall only handle notinv predicates in this case. If the `until` block is not present or if it does not handle the notinv predicate, the active mode shall be terminated and the execution shall continue with the implicit follow-up mode (i.e. the mode immediately textually following the active mode statement). If no implicit follow-up mode is available, the test system shall generate a dynamic error.

**Restrictions**

In the general semantic rules the following restrictions apply:

- The functions invoked from the invariant statement shall not use any blocking instructions (i.e. the following operations and statements: all receiving operations, timeout, done, killed, wait and mode). Such constructs would potentially block the execution of the invariant block with the consequence, that the next sampling step is missed.

**Examples**

Example 1 below shows the definition of an atomic mode that sets the out port A continuously with the value of 3.0. Moreover, the invariant prescribes conditions on the incoming ports B, C and D. When one of the invariants is violated by the actual value at ports, mode execution is stopped.

```plaintext
EXAMPLE 1:

type port StreamIn stream { in float }
type port StreamOut stream { out float }

type component SUT {
    port StreamIn A,B;
    port StreamOut C,D;
}

cont{
```
A.value:=3;
inv {B.value > 3, C.value >=3*D.value}
}

The specification of invariants allows the easy definition of ending conditions for the execution of modes. Based on a simple sequential control flow paradigm, this supports the specification of sequences of modes, that are executed one after the other whenever the invariant state of the active mode changes.

EXAMPLE 2:

cont{
A.value:=3;
inv {B.value >3,C.value >=3*D.value}
}
cont{
A.value:=5;
inv {B.value <=3,C.value >=3*D.value}
}

5.4.1.3 Definition of the onentry block

The onentry block contains a statement list that is to be executed once and only once during the activation of a mode.

Syntactical Structure

onentry StatementBlock

Semantic Description

The onentry block is executed as part of the activation procedure of a mode. To successfully start the onentry block all invariants shall satisfy their conditions. The onentry blocks of hierarchically ordered modes are executed sequentially, beginning with the onentry block of the outer-most mode to the inner modes.

Restrictions

In an onentry block of a mode any TTCN-3 statement is principally allowed, except:

- Blocking instructions (i.e. the following operations and statements: all receiving operations, timeout, done, killed, wait and mode) referenced directly or called inside functions invoked from the onentry block shall not be used. Such constructs would potentially block the execution of the statement block with the consequence, that the next sampling step is missed.
- Each type of control flow related statement that leads to the leaving of the mode (e.g. goto, return).

Example

The example below shows the definition of an atomic mode that sets the sampling of a port during its activation time.

EXAMPLE:

cont{
    onentry {A.delta:=0.001;}
    A.value:=3;
}

5.4.1.4 Definition of the onexit block

The onexit block contains a statement list that is to be executed once and only once during the deactivation of a mode.

Syntactical Structure

onexit StatementBlock
Semantic Description

The **onexit** block is executed as part of the deactivation procedure of a mode. The execution of the **onexit** block is triggered either by an activated transition or the violation of an invariant that lead to the leaving of the mode. In case of an active transition the **onexit** block is executed directly after the execution of the transition's optional action block. The **onexit** blocks of hierarchically ordered modes are executed sequentially, beginning with the **onexit** blocks of the inner-most modes towards the outer modes.

Restrictions

In an **onexit** block of a mode any TTCN-3 statement is principally allowed, except:

- Blocking instructions (i.e. the following operations and statements: all receiving operations, timeout, done, killed, wait and mode) referenced directly or called inside functions invoked from the **onexit** block shall not be used. Such constructs would potentially block the execution of the statement block with the consequence, that the next sampling step is missed.
- Each type of control flow related statement that leads to the leaving of the mode (e.g. goto, return).

Example

The following example shows the definition of an atomic mode that sets the sampling of a port during its deactivation time.

```
EXAMPLE:
cont{
    A.value:=3.0;
    onexit {A.value:=1.0;}
} until {
    \{B.value> 3.0\}
}
```

5.4.1.5 Local predicate symbols in the context of modes

To enable an explicit treatment of some exceptional situations, the keywords **notinv** and **finished** have been introduced. They represent special predicates with a mode local evaluation.

Semantic Description

The keyword **notinv** can be used as a predicate that indicates the violation of any local mode invariant. Thus, if one of the invariants of a mode is violated and the mode is active, the evaluation of the **notinv** symbol yields true for all expressions in the contained until block. Otherwise it yields false. Thus, the **notinv** symbol allows the explicit handling of occurring invariant violation by means of transitions. The **notinv** predicate is the only predicate that allows activating a transition when an invariant is violated. The **notinv** predicate shall not be followed by any trigger event.

The **finished** keyword can be used as a predicate to handle the proper termination of a composite mode. A proper termination is given when the termination is triggered by the status of the child elements of a composite mode and not by its transitions or invariants. If and only if a mode is terminated by the status of its child elements the term **finished** yields true. Thus, the **finished** predicate allows the explicit handling of proper mode terminations by means of transitions.

Examples

```
EXAMPLE 1:
cont{ //mode
    A.value:=3;
} until { // transitions
    \{notinv\} \{ log(" Invariant violated" ); \} \\
    \{[] Port2.receive(TemplExp) \{ log(" Invariant not violated" ); \} \\
}
```
EXAMPLE 2:

```plaintext
par { //mode
  cont { //inner mode 1
    A.value:=3.0;
  } until {[C.value>3.0]}
  cont { //inner mode 2
    B.value:=3.0;
  } until {[D.value>3.0]}
} until {[finished] { log(" finished by childs' state" ); }
        [D.value > 4.0] { log(" not finished by childs' state" ); }}
```

## 5.4.1.6 The duration operator

Within a mode there is continuous access to the time that has elapsed since the beginning of the test case by using the `now` operator. It is also possible to access the time that has elapsed since the activation of the enclosing mode construct. The access is provided by means of the **duration operator**, which is applicable in expressions in all mode related substructures like the body block, the invariant block and the until block.

**NOTE:** The evaluation of the `duration` operator depends on its context. Thus, it may differ dependent on its place of application.

**Examples**

**EXAMPLE 1:**

```plaintext
cont{ A.value:=3.0; } until {[now > 4.0]}
// executes the content of the body block until
// the overall test case time has reached 4.0 seconds
```

**EXAMPLE 2:**

```plaintext
cont{ A.value:=3.0; } until {[duration > 4.0]}
// executes the content of the body block for 4.0 seconds
```

Example 3 shows the application of the `duration` operator in two different modes. Both modes are activated at different times and thus the application of the duration symbol in the second cont mode yields different results than the application of the `duration` operator in the enclosing `par` mode.

**EXAMPLE 3:**

```plaintext
par{
  cont{ A.value:=2.0; } until (duration > 4.0)
  cont{ A.value:=3.0; } until (duration > 4.0)
} until{[duration > 6.0]}
```

## 5.4.2 Atomic modes: the cont statement

**Syntactical Structure**

The syntactical structure and context for the `cont` statement is part of the syntactical structure provided in clause 5.4.1.

**Semantic Description**

The `cont` statement is used to define atomic modes. Atomic modes directly define the test behaviour at stream ports by means of value allocation and value assessments. A `cont` mode may contain assignments and assert statements and forms the leaves of a hierarchical mode structure.

When a `cont` statement is activated, all contained elements are executed repetitively for each sample step. The execution ends when a transition fires or an invariant is violated.
Restrictions

a) A `cont` mode shall not invoke any potentially blocking behaviour.

b) A `cont` mode cannot contain other modes.

Examples

EXAMPLE 1:

```plaintext
// executes the assignments at each sample step
cont { // Mode 1
  Port1.value := 10.0;
  Port2.value := 2.0 * duration;
}
until (duration > 5.0)
```

NOTE: Assignment and evaluation of the `cont` mode is, in a theoretical sense, continuous, i.e. executed at each step, provided for sampling. The `cont` mode allows the organization of periodic assignments and periodic revisions of values or variables of stream and stream ports.

EXAMPLE 2:

```plaintext
cont { // mode 1
  outport1.value := inport1.prev.value * 2;
  streamvar.value := inport1.prev(5).value;
}
```

EXAMPLE 3:

```plaintext
cont { // mode 1
  outport1.value := inport1.prev.value * 2;
  streamvar.value := inport1.prev(5).value;
  inv {
    streamvar.value > 200.0
  }
}
until { // Transition
  [streamvar.value > 150] { streamvar.value = 0; }
  [streamvar.value > 180] ()
}
```

5.4.3 Parallel mode composition: the `par` statement

The parallel composition of modes is specified by means of the `par` statement. A parallel composition may contain sequential modes, parallel modes and atomic modes.

Syntactical Structure

The syntactical structure and context for the `cont` statement is part of the syntactical structure provided in clause 5.4.1. The general structure of the `par` statement is similar to the `cont` statement and the `seq` statement. It consists of a body part, which defines the overall behaviour of the mode. In case of the `par` statement the body part contains the mode definitions that are to be composed in parallel. The mode can define an optional invariant and a transition part, as well as onentry and onexit blocks.

Semantic Description

In case of its activation, a parallel composition leads to a parallel execution of all composed (i.e. contained) modes. While being active, each invariant of a composite mode has to hold. Additionally, each transition of a composite mode ends the activity of the mode when it fires. Furthermore, each mode provides access to an individual local clock that returns the time that has passed since the mode has been activated. The value of the local clock can be obtained by means of the duration keyword.
The activation of a parallel mode leads to the parallel activation of all child modes. During execution, the parallel mode is responsible to check the status of all contained modes. The execution of a parallel mode ends, either when a transition in the transition block has fired or when the execution of at least one child mode has been completed. The second situation is called a proper termination of a parallel mode and forces the local symbol finished to yield \( \text{true} \) (see clause 5.4.1.3).

**Examples**

**EXAMPLE 1:**

```plaintext
var integer count := 0;
par{
  cont{
    x.value:=1;
    y.value:=2;
  }
  until { // Transition
    [z.value> 3.0] { }
    [] Port2.receive {}
  }
  cont{
    x.value:=2;
    y.value:=1;
  }
  until { // Transition
    [z.value> 10.0] { }
    [] Port1.receive {}
  }
  until { // Transition
    [finished] {if(count > 1) {count++; continue}}
  }
}
```

**NOTE 1:** The predicate \( \text{finished} \) yields \( \text{true} \) only during the distinct sample step when a child of a parallel mode has finished. Moreover, it yields true for every child element that has finished. Thus, it serves as a notification event, which can be used to model complex termination conditions for parallel modes.

**NOTE 2:** For parallel execution, it is always possible that several children modes terminate at the same time. Thus, counting the finished child modes to determine if all child modes have finished is not reliable. Instead, the child modes should set conditions that can be queried in the finished.

**EXAMPLE 2:**

```plaintext
par{
  cont{
    x.value:=1;
    y.value:=2;
  }
  until { // Transition
    [z.value> 1.0] { }
    [] Port1.receive(msg1) {}
  }
  cont{
    x.value:=2;
    y.value:=1;
  }
  until { // Transition
    [z.value> 10.0] { }
    [] Port1.receive() {}
  }
  until { // Transition
    [z.value > 11.0] { }
    [] Port1.receive(msg) {}
  }
}
```

5.4.4 Sequential mode composition: the seq statement

The sequential composition of modes is specified by means of the seq statement. A sequential composition may contain sequential modes, parallel modes and atomic modes.
Syntactical Structure

The syntactical structure and context for the `cont` statement is part of the syntactical structure provided in clause 5.4.1.

The general structure of the `seq` statement is similar to the `cont` statement and the `par` statement. It consists of a body part, which defines the overall behaviour of the mode. In case of the `seq` statement the body part contains the mode definitions that are to be composed.

Semantic Description

In case of its activation, a sequential composition leads to a sequential execution of the composed (i.e. contained) modes.

While being active, each invariant of a composite mode has to hold. Additionally, each transition of a composite mode ends the activity of the mode when it fires. Furthermore, each mode provides access to an individual local clock that returns the time that has passed since the mode has been activated. The value of the local clock can be obtained by means of the `duration` keyword.

The activation of a sequential mode leads to the activation of its first child mode. During execution, the sequential mode is responsible to schedule the contained modes in their sequential order. Thus, when a child mode has finished, the target mode of the exit transition is activated. Per default, the target mode is the next mode in the sequence. The execution of a sequential mode ends either when a transition in the transition block is fired or when the execution of the last child mode has been completed. The second situation is called a proper termination of a sequential mode and forces the local symbol `finished` to yield `true` (see clause 5.4.1.3).

Example

The following example defines the sequential execution of two atomic modes, which are composed sequentially by means of a sequential mode.

```
EXAMPLE:

seq{
  cont{
    x.value:=1;
    y.value:=2;
  }
  until { // Transition
    [z.value> 2.0] { }
    [] Port1.receive() {}
  }
  cont{
    x.value:=2;
    y.value:=1;
  }
  until { // Transition
    [z.value> 1.0] { }
    [] Port1.receive() {}
  }
  until { // Transition
    [z.value> 12.0] { }
    [] Port1.receive(msg) {}
  }
}
```

5.4.5 Parameterizable modes

5.4.5.0 General

To provide a higher degree of flexibility, it is possible to specify parameterizable modes. Values, templates, ports, and modes can be used as mode parameters. The definition of parameterizable modes is similar to the definition of TTCN-3 functions.

**NOTE:** Unlike functions parameterizable modes are not called in the sense of a function call but inserted by means of a substitution mechanism at compile time. Thus, the recursive application of parameterizable modes is not possible.
5.4.5.1 Parameterizable mode definitions

A parameterizable mode definition allows the definition of reusable and parameterizable modes. A parameterizable mode may be defined within a module.

Syntactical Structure

```plaintext
mode ModeName
   ["(" { FormalValuePar | FormalTimerPar | FormalTemplatePar | FormalPortPar | FormalModePar 
   [","] } ")"]
   [ runs on ComponentType ]
   ( ContMode | ParMode | SeqMode )
```

Semantic Description

In a module, the behaviour of a mode can be defined by using the statements and operations described in clauses 5.4.1 to 5.4.4.

Restrictions

a) If a mode uses variables, constants, timers and ports that are declared in a component type definition, the component type shall be referenced using the `runs on` keywords in the mode header. The one exception to this rule is if all component-wide information used within the mode is passed in as parameters.

b) A mode without `runs on` clause shall never invoke functions or modes with a `runs on` clause locally.

Examples

EXAMPLE 1:

```plaintext
mode myMode runs on Tester cont{assert(engine_speed >= 500.0)}
```

EXAMPLE 2:

```plaintext
mode pert_seq_2(in float startVal, in float increase, in float expected_speed)
runs on Tester
par{
   seq{// perturbation sequence
      cont{to_Set_Point:=startVal} until [{duration>=2.0}]
      cont{to_Set_Point:=startVal + duration/to_Set_Point.delta*increase} until [{duration>=5.0}]
   }
   cont{assert(engine_speed >= expected_speed)};
}
testcase myTestcase runs on EngineTester {
   pert_seq_2(1000.0, 10.0, 500.0);
   pert_seq_2(5000.0, 1.0, 0.0);
}
```

5.4.5.2 Mode types (optional)

Mode types are optional. They are available only if this extension package is used in combination with the TTCN-3 extension package ETSI ES 202 785 [6] "Behaviour Types". If this package is used in combination with [6], both packages have to be named with their package tags in the language clause of the TTCN-3 module in which the packages are used.

Mode types are the set of identifiers of mode definitions with a specific parameter list and runs on clauses. They denote those modes defined in the test suite that have a compatible parameter list and compatible `runs on` clauses.

Syntactical Structure

```plaintext
type mode BehaviorTypeIdentifier
   ["(" { FormalValuePar | FormalTimerPar | FormalTemplatePar | FormalPortPar | FormalModePar 
   [","] } ")"]
   [ runs on ( ComponentType | self )]
```
5.5 The wait statement

**Syntactical Structure**

```plaintext
wait "(* Expression *)"
```

**Semantic Description**

The `wait` statement suspends the execution of a component until a given point in time. The time point is specified as a float value and relates to the internal clock.

The execution of the `wait` statement suspends the execution of the related component until the point in time specified by its argument. If the argument holds a value that precedes the actual clock value an error verdict shall be set.

**Example**

```plaintext
EXAMPLE:

streamoutport.value = 10.0;
wait(100.0 + now);     // suspends the execution of a component
// until 100.0 seconds after the start of the testcase
streamoutport.value = 12.0;
```

**NOTE:** The `wait` statement has no impact on sampling. All stream ports of the given component are still sampled with respect to their sampling rate.

6 TRI extensions for the package

**6.0 General**

In addition to the TRI types defined in ETSI ES 201 873-5 [3], the following type is used in TRI operations if static configurations specified in ETSI ES 202 781 [7] are supported.

**TriConfigurationIdType**

A value of type `TriConfigurationIdType` includes a unique identifier of the configuration and the configuration function name as specified in the TTCN-3 ATS. This abstract type is used to resolve clock operations related to specific configurations as there might be several configurations active in the same time.
6.1 Extensions to clause 5.5 of ETSI ES 201 873-5: Communication interface operations

Clause 5.5.6 Stream operations

5.5.6.1 triSetStreamValue (TE → SA)

<table>
<thead>
<tr>
<th>Signature</th>
<th>TriStatusType triSetStreamValue (in TriComponentIdType componentId, in TriPortIdType tsiPortId, in TriMessageType streamValue)</th>
</tr>
</thead>
<tbody>
<tr>
<td>In Parameters</td>
<td>componentId identifier of the sending test component. tsiPortId identifier of the test system interface port via which the message is sent to the SUT Adapter. streamValue the encoded stream value (message) to be sent.</td>
</tr>
<tr>
<td>Out Parameters</td>
<td>n.a.</td>
</tr>
<tr>
<td>Return Value</td>
<td>The return status of the triSetStreamValue operation. The return status indicates the local success (TRI_OK) or failure (TRI_Error) of the operation.</td>
</tr>
<tr>
<td>Constraints</td>
<td>The TE calls this operation when it executes a new sampling step on a sampled output stream port, which has been mapped to a TSI port. The TE calls the operation for all sampling steps of all outgoing stream ports if no system component has been specified for a test case, i.e. only a MTC test component is created for a test case. The encoding of streamValue has to be done in the TE prior to this TRI operation call.</td>
</tr>
<tr>
<td>Effect</td>
<td>The SA can update the message to the SUT. The triSetStreamValue operation returns TRI_OK in case it has been completed successfully. Otherwise TRI_Error shall be returned. Notice that the return value TRI_OK does not imply that the SUT has received streamValue.</td>
</tr>
</tbody>
</table>

5.5.6.2 triGetStreamValue (TE → SA)

<table>
<thead>
<tr>
<th>Signature</th>
<th>TriStatusType triGetStreamValue (in TriComponentIdType componentId, in TriPortIdType tsiPortId, out TriMessageType streamValue)</th>
</tr>
</thead>
<tbody>
<tr>
<td>In Parameters</td>
<td>componentId identifier of the sending test component. tsiPortId identifier of the test system interface port via which the message is sent to the SUT Adapter.</td>
</tr>
<tr>
<td>Out Parameters</td>
<td>streamValue the encoded stream value (message) that has been received from the SUT.</td>
</tr>
<tr>
<td>Return Value</td>
<td>The return status of the triGetStreamValue operation. The return status indicates the local success (TRI_OK) or failure (TRI_Error) of the operation.</td>
</tr>
<tr>
<td>Constraints</td>
<td>The TE calls this operation when it executes a new sampling step on a sampled input stream port, which has been mapped to a TSI port. The TE calls the operation for all sampling steps of all outgoing stream ports if no system component has been specified for a test case, i.e. only a MTC test component is created for a test case. The decoding of streamValue has to be done in the TE after to this TRI operation call.</td>
</tr>
<tr>
<td>Effect</td>
<td>The SA can update the stream value at the input port. The triGetStreamValue operation returns TRI_OK in case it has been completed successfully. Otherwise TRI_Error shall be returned.</td>
</tr>
</tbody>
</table>
### 6.2 Extensions to clause 5.6 of ETSI ES 201 873-5: Platform interface operations

#### Clause 5.6.4 Clock and sampling operations

##### 5.6.4.1 triStartClock (TE → PA)

<table>
<thead>
<tr>
<th>Signature</th>
<th>TriStatusType triStartClock(in long ticksPerSecond)</th>
</tr>
</thead>
<tbody>
<tr>
<td>In Parameters</td>
<td>ticksPerSecond: the precision of the clock given in ticks per second.</td>
</tr>
<tr>
<td>Out Parameters</td>
<td>n.a.</td>
</tr>
<tr>
<td>Return Value</td>
<td>The return status of the operation. The return status indicates the success (TRI_OK) or failure (TRI_Error) of the operation.</td>
</tr>
<tr>
<td>Constraints</td>
<td>n.a.</td>
</tr>
<tr>
<td>Effect</td>
<td>The operation starts the test system clock with a given precision. The precision is defined by the in parameter ticksPerSecond. The parameter specifies the number of time units (ticks) that characterizes a second.</td>
</tr>
</tbody>
</table>

##### 5.6.4.2 triReadClock (TE → PA)

<table>
<thead>
<tr>
<th>Signature</th>
<th>TriStatusType triReadClock(out long timepoint)</th>
</tr>
</thead>
<tbody>
<tr>
<td>In Parameters</td>
<td>n.a.</td>
</tr>
<tr>
<td>Out Parameters</td>
<td>timepoint: current time.</td>
</tr>
<tr>
<td>Return Value</td>
<td>The return status of the operation. The return status indicates the success (TRI_OK) or failure (TRI_Error) of the operation.</td>
</tr>
<tr>
<td>Constraints</td>
<td>There was a preceding invocation of triStartClock(in long ticksPerSecond).</td>
</tr>
<tr>
<td>Effect</td>
<td>The operation yields the actual clock value. The clock value is given by the out parameter timepoint, which represents the number of time units (ticks) that has elapsed since the start of the clock (see triStartClock).</td>
</tr>
</tbody>
</table>

##### 5.6.4.3 triNextSampling (TE → PA, SA → PA)

<table>
<thead>
<tr>
<th>Signature</th>
<th>TriStatusType triNextSampling</th>
</tr>
</thead>
<tbody>
<tr>
<td>(in long timepoint, in TriPortIDType port)</td>
<td></td>
</tr>
<tr>
<td>In Parameters</td>
<td>timepoint: point in time when the execution of the next sample step for a given stream port shall be started. port: the stream port the sample step is requested for.</td>
</tr>
<tr>
<td>Out Parameters</td>
<td>n.a.</td>
</tr>
<tr>
<td>Return Value</td>
<td>The return status of the operation. The return status indicates the success (TRI_OK) or failure (TRI_Error) of the operation.</td>
</tr>
<tr>
<td>Constraints</td>
<td>There was a preceding invocation of triStartClock(in long ticksPerSecond).</td>
</tr>
<tr>
<td>Effect</td>
<td>The operation signals that the next sample step for a given port shall start at the specified point of time timepoint. At this point in time the PA will issue a triProcessStep(in TriPortIDListType ports) operation to inform the TE which ports shall be sampled next. The parameter timepoint is expressed as the number of time units (ticks), that has elapsed since the start of the clock (see triStartClock). A call to this operation returns immediately. The operation merely triggers the corresponding triProcessStep operation. If timepoint represent a point of time in the past then the operation returns a TRI_Error value and has no other effect.</td>
</tr>
</tbody>
</table>
### 5.6.4.4 
- **Signature**
  
  Signature: `TriStatusType triBeginWait`
  
  (in long `timepoint`,
  
  in TriComponentIdType `component`)

- **In Parameters**
  
  `timepoint` point in time until execution of a component should be suspended.
  
  `component` component whose execution should be suspended.

- **Out Parameters**
  
  n.a.

- **Return Value**
  
  The return status of the operation. The return status indicates the success (`TRI_OK`) or failure (`TRI_Error`) of the operation.

- **Constraints**
  
  There was a preceding invocation of `triStartClock(int long ticksPerSecond)`.

- **Effect**
  
  The operation signals that the execution of component `component` should be suspended until the specified point of time `timepoint`. At this point in time the PA will issue a `triEndWait(component)` operation.
  
  `timepoint` is expressed as the number of time units (ticks), that has elapsed since the start of the clock (see `triStartClock`).
  
  A call to this operation returns immediately. The operation merely triggers the corresponding `triEndWait` operation, it does not schedule the execution of the component.
  
  If `timepoint` represent a point of time in the past then the operation returns a `TRI_Error` value and has no other effect.

### 5.6.4.5 
- **Signature**
  
  Signature: `void triProcessStep(in TriPortIDListType ports)`

- **In Parameters**
  
  Ports a list of ports that shall be sampled at the operation call.

- **Out Parameters**
  
  n.a.

- **Return Value**
  
  n.a.

- **Constraints**
  
  There was a preceding invocation of `triNextSampling(port)`.

- **Effect**
  
  The operation signals that the point in time `timepoint` that was specified in the corresponding `triNextSampling(timepoint, port)` has been reached.

### 5.6.4.6 
- **Signature**
  
  Signature: `void triEndWait(in TriComponentIdType component)`

- **In Parameters**
  
  Component `component` of the corresponding `triBeginWait` operation.

- **Out Parameters**
  
  n.a.

- **Return Value**
  
  n.a.

- **Constraints**
  
  There was a preceding invocation of `triBeginWait(timepoint, component)`.

- **Effect**
  
  The operation signals that the point in time `timepoint` that was specified in the corresponding `triBeginWait(timepoint, component)` has been reached.
5.6.4.7 triStartClockStatic (TE → PA)

**Signature**

TriStatusType triStartClock(in long ticksPerSecond, TriConfigurationIdType ref)

**In Parameters**

- ticksPerSecond: the precision of the clock given in ticks per second.
- ref: reference to the static configuration owning the clock.

**Out Parameters**

n.a.

**Return Value**

The return status of the operation. The return status indicates the success (TRI_OK) or failure (TRI_Error) of the operation.

**Constraints**

This operation is optional and shall be present in the interface only if static configurations specified in ETSI ES 202 781 [7] are supported.

**Effect**

The operation starts the test system clock with a given precision. The precision is defined by the in parameter ticksPerSecond. The parameter specifies the number of time units (ticks) that characterizes a second.

5.6.4.8 triReadClockStatic (TE → PA)

**Signature**

TriStatusType triReadClock(out long timepoint, TriConfigurationIdType ref)

**In Parameters**

n.a.

**Out Parameters**

- timepoint: current time.
- ref: reference to the static configuration owning the clock.

**Return Value**

The return status of the operation. The return status indicates the success (TRI_OK) or failure (TRI_Error) of the operation.

**Constraints**

This operation is optional and shall be present in the interface only if static configurations specified in ETSI ES 202 781 [7] are supported. There was a preceding invocation of triStartClockStatic(int long ticksPerSecond, TriConfigurationIdType ref).

**Effect**

The operation yields the actual clock value. The clock value is given by the out parameter timepoint, which represents the number of time units (ticks) that has elapsed since the start of the clock (see triStartClock).

6.3 Extensions to clause 6.3.2 of ETSI ES 201 873-5: Structured type mapping

6.3.1 TriConfigurationIdType

6.3.1.0 General

**TriConfigurationIdType** is mapped to the following interface:

```java
// TRI IDL TriConfigurationIdType
package org.etsi.ttcn.tri;
public interface TriConfigurationId {
    public String getConfigurationId();
    public String getConfigurationName();
    public boolean equals(TriConfigurationId component);
}
```

6.3.1.1 Methods

- **getConfigurationId**
  Returns a representation of this unique configuration identifier.

- **getConfigurationName**
  Returns the configuration function name as defined in the TTCN-3 specification.
等于

比较配置与此TriConfigurationId的相等性。返回true，如果且仅如果两个配置具有相同的唯一配置标识符的表示形式，false否则。

6.4 扩展到ETSI ES 201 873-5条目6.5.2.1的ETSI ES 201 873-5：
TriCommunicationSA

TriCommunicationSA接口应按照以下方式扩展:

```java
public interface triCommunicationSA {
    // Stream operations
    // Ref: 5.5.6.1
    public TriStatus triSetStreamValue(TriComponentId componentId,
                                        TriPortId tsiPortId,
                                        TriMessage streamValue);
    // Ref: 5.5.6.2
    public TriStatus triGetStreamValue(TriComponentId componentId,
                                        TriPortId tsiPortId,
                                        TriAddress SUTaddress,
                                        TriMessage streamValue);
}
```

6.5 扩展到ETSI ES 201 873-5条目6.5.3.1的ETSI ES 201 873-5：
TriPlatformPA

TriPlatformPA接口应按照以下方式扩展:

```java
public interface triPlatformPA {
    // Clock and sampling operations
    // Ref: 5.6.4.1
    public TriStatus triStartClock(long ticksPerSecond);
    // Ref: 5.6.4.2
    public TriStatus triReadClock(TriLong timepoint);
    // Ref: 5.6.4.3
    public TriStatus triNextSampling(long timepoint, TriPortId port);
    // Ref: 5.6.4.4 (optional)
    public TriStatus triBeginWait(int timepoint, TriComponentId component);
    // Ref: 5.6.4.7 (optional)
    public TriStatus triStartClockStatic(long ticksPerSecond, TriConfigurationId ref);
    // Ref: 5.6.4.8 (optional)
    public TriStatus triReadClockStatic(TriLong timepoint, TriConfigurationId ref);
}
```

其中TriLong定义如下:

```java
package org.etsi.ttcn.tri;

public interface TriLong {
    public void setLongValue(long value);
    public long getLongValue();
}
```
6.6 Extensions to clause 6.5.3.2 of ETSI ES 201 873-5: TriPlatformTE

The triPlatformTE interface is to be extended as follows:

```java
public interface triPlatformTE {
    // Clock and sampling operations
    // Ref: 5.6.4.5
    public void triProcessStep(TriPortIdList ports);
    // Ref: 5.6.4.6
    public void triEndWait(TriComponentId component);
}
```

6.7 Extensions to clause 7.2.1 of ETSI ES 201 873-5: Abstract type mapping

<table>
<thead>
<tr>
<th>TRI ADT</th>
<th>ANSI C Representation</th>
<th>Notes and comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>TriConfigurationId</td>
<td>typedef struct TriConfigurationId {</td>
<td>confId is stands for the unique configuration identifier and</td>
</tr>
<tr>
<td></td>
<td>BinaryString confId;</td>
<td>confName is used for the name of the related configuration function.</td>
</tr>
<tr>
<td></td>
<td>QualifiedName confName;</td>
<td></td>
</tr>
<tr>
<td></td>
<td>TriComponentId;</td>
<td></td>
</tr>
</tbody>
</table>

6.8 Extensions to clause 7.2.4 of ETSI ES 201 873-5: TRI operation mapping

The table is to be extended as follows:

<table>
<thead>
<tr>
<th>IDL Representation</th>
<th>ANSI C Representation</th>
</tr>
</thead>
<tbody>
<tr>
<td>TriStatusType triSetStreamValue(</td>
<td>TriStatus triSetStreamValue(</td>
</tr>
<tr>
<td>in TriComponentIdType componentId,</td>
<td>const TriComponentId *componentId,</td>
</tr>
<tr>
<td>in TriPortIdType tsiPortId,</td>
<td>const TriPortId *tsiPortId,</td>
</tr>
<tr>
<td>in TriMessageType streamValue)</td>
<td>const TriMessage *streamValue);</td>
</tr>
<tr>
<td>TriStatusType triGetStreamValue(</td>
<td>TriStatus triGetStreamValue(</td>
</tr>
<tr>
<td>in TriComponentIdType componentId,</td>
<td>const TriComponentId *componentId,</td>
</tr>
<tr>
<td>in TriPortIdType tsiPortId,</td>
<td>const TriPortId *tsiPortId,</td>
</tr>
<tr>
<td>put TriMessageType streamValue)</td>
<td>const TriMessage *streamValue);</td>
</tr>
<tr>
<td>TriStatusType triStartClock(in long ticksPerSecond)</td>
<td>TriStatus triStartClock(</td>
</tr>
<tr>
<td></td>
<td>const long long ticksPerSecond);</td>
</tr>
<tr>
<td>TriStatusType triReadClock(out long timepoint),</td>
<td>TriStatus triReadClock(</td>
</tr>
<tr>
<td>in long timepoint, in TriPortIdType port)</td>
<td>const long long timepoint,</td>
</tr>
<tr>
<td></td>
<td>const TriPortId port);</td>
</tr>
<tr>
<td>TriStatusType triNextSampling</td>
<td>TriStatus triNextSampling(</td>
</tr>
<tr>
<td>(in long timepoint, in TriPortIdType port)</td>
<td>const long long timepoint,</td>
</tr>
<tr>
<td></td>
<td>const TriPortId port);</td>
</tr>
<tr>
<td>TriStatusType triBeginWait</td>
<td>TriStatus triBeginWait(</td>
</tr>
<tr>
<td>(in long timepoint,</td>
<td>const long long timepoint,</td>
</tr>
<tr>
<td>in TriComponentIdType component)</td>
<td>const TriComponentId component);</td>
</tr>
<tr>
<td>void triProcessStep(in TriPortIdListType ports)</td>
<td>void triProcessStep(</td>
</tr>
<tr>
<td></td>
<td>const TriPortIdList *ports);</td>
</tr>
<tr>
<td>void triEndWait(in TriComponentIdType component)</td>
<td>void triEndWait(</td>
</tr>
<tr>
<td></td>
<td>const TriComponentId *component);</td>
</tr>
<tr>
<td>TriStatusType triStartClock(in long ticksPerSecond)</td>
<td>TriStatus triStartClockStatic(</td>
</tr>
<tr>
<td></td>
<td>const long long ticksPerSecond,</td>
</tr>
<tr>
<td></td>
<td>const TriComponentId *ref);</td>
</tr>
<tr>
<td>TriStatusType triReadClock(out long timepoint)</td>
<td>TriStatus triReadClockStatic(</td>
</tr>
<tr>
<td></td>
<td>const long long timepoint,</td>
</tr>
<tr>
<td></td>
<td>const TriConfigurationId *ref);</td>
</tr>
</tbody>
</table>
6.9 Extensions to clause 8.5.2 of ETSI ES 201 873-5: Abstract data types

6.9.1 TriConfigurationId

6.9.1.0 General

A value of type TriComponentId includes an identifier and configuration function name. This abstract type is for distinguishing between different parallel configurations in static clock operations:

```cpp
class TriConfigurationId {
public:
    virtual ~TriConfigurationId ();
    virtual const QualifiedName & getConfigurationName () const =0;
    virtual const Tstring & getConfigurationId () const =0;
    virtual Tboolean operator==(const TriConfigurationId &cmp) const =0;
    virtual TriConfigurationId * cloneComponentId () const =0;
    virtual Tboolean operator<(const TriConfigurationId &cmp) const =0;
}
```

6.9.1.1 Methods

- `~TriConfigurationId` 
  Destructor.

- `getConfigurationName`
  Returns a const reference to the configuration function name.

- `getConfigurationId`
  Returns the configuration unique identifier.

- `operator==`
  Returns true if both TriConfigurationId objects are equal.

- `cloneComponentId`
  Returns a copy of the TriConfigurationId.

- `operator<`
  Operator < overload.

6.10 Extensions to clause 8.6.1 of ETSI ES 201 873-5: TriCommunicationSA

The triCommunicationSA interface is to be extended as follows:

```cpp
class TriCommunicationTe {
public:
    // Stream operations
    // Ref: 5.5.6.1
    virtual TriStatus triSetStreamValue(const TriComponentId *componentId,
                                         const TriPortId *tsiPortId,
                                         const TriMessage *streamValue)=0;
    // Ref: 5.5.6.2
    virtual TriStatus triGetStreamValue(const TriComponentId *componentId,
                                         const TriPortId *tsiPortId,
                                         const TriMessage *streamValue)=0;
}
```
6.11 Extensions to clause 8.6.3 of ETSI ES 201 873-5: TriPlatformPA

The triPlatformPA interface is to be extended as follows:

class TriPlatformPa {
public:
    // Clock and sampling operations
    // Ref: 5.6.4.1
    virtual TriStatus triStartClock(const long long ticksPerSecond)=0;
    // Ref: 5.6.4.2
    virtual TriStatus triReadClock(const long long *timepoint)=0;
    // Ref: 5.6.4.3
    virtual TriStatus triNextSampling(const long long timepoint, const TriPortId *port)=0;
    // Ref: 5.6.4.4
    virtual TriStatus triBeginWait(const long long timepoint, const TriComponentId *component)=0;
    // Ref: 5.6.4.7 (optional)
    virtual TriStatus triStartClockStatic(const long long ticksPerSecond, const TriConfigurationId *ref)=0;
    // Ref: 5.6.4.8 (optional)
    virtual TriStatus triReadClockStatic(const long long *timepoint, const TriConfigurationId *ref)=0;
}

6.12 Extensions to clause 8.6.4 of ETSI ES 201 873-5: TriPlatformTE

The triPlatformTE interface is to be extended as follows:

class TriPlatformTe {
public:
    // Clock and sampling operations
    // Ref: 5.6.4.5
    virtual void triProcessStep(const TriPortIdList *ports)=0;
    // Ref: 5.6.4.6
    virtual void triEndWait(const TriComponentId *component)=0;
}

6.13 Extensions to clause 9.4.2 of ETSI ES 201 873-5: Structured type mapping

6.13.1 TriConfigurationIdType

6.13.1.0 General

TriConfigurationIdType is mapped to the following interface:

public interface ITriConfigurationId {
    string ConfigurationId { get; }
    IQualifiedName ConfigurationName { get; }
    bool Equals(ITriConfigurationId comp);
}

6.13.1.1 Members

- ConfigurationId
  Returns a representation of this unique configuration identifier.

- ConfigurationName
  Returns the configuration function name as defined in the TTCN-3 specification.
• Equals
   Compares a configuration with this TriConfigurationId for equality. Returns true if and only if both configurations have the same representation of the unique configuration identifier, false otherwise.

6.14 Extensions to clause 9.5.2.1 of ETSI ES 201 873-5: ITriCommunicationSA

The ITriCommunicationSA interface is to be extended as follows:

```java
public interface ITriCommunicationSA {
    // Stream operations
    // Ref: 5.5.6.1
    TriStatus TriSetStreamValue(ITriComponentId componentId,
                               TriPortId tsiPortId,
                               TriMessage streamValue);
    // Ref: 5.5.6.2
    TriStatus TriGetStreamValue(ITriComponentId componentId,
                                TriPortId tsiPortId,
                                TriMessage streamValue);
}
```

6.15 Extensions to clause 9.5.2.3 of ETSI ES 201 873-5: ITriPlatformPA

The ITriPlatformPA interface is to be extended as follows:

```java
public interface ITriPlatformPA {
    // Clock and sampling operations
    // Ref: 5.6.4.1
    TriStatus TriStartClock(long ticksPerSecond);
    // Ref: 5.6.4.2
    TriStatus TriReadClock(out long timepoint);
    // Ref: 5.6.4.3
    TriStatus TriNextSampling(long timepoint, ITriPortId port);
    // Ref: 5.6.4.4
    TriStatus TriBeginWait(long timepoint, ITriComponentId component);
    // Ref: 5.6.4.7 (optional)
    TriStatus TriStartClockStatic(long ticksPerSecond, ITriConfigurationId refConf);
    // Ref: 5.6.4.8 (optional)
    TriStatus TriReadClockStatic(out long timepoint, ITriConfigurationId refConf);
}
```

6.16 Extensions to clause 9.5.2.4 of ETSI ES 201 873-5: ITriPlatformTE

The ITriPlatformTE interface is to be extended as follows:

```java
public interface ITriPlatformTE {
    // Clock and sampling operations
    // Ref: 5.6.4.5
    void TriProcessStep(ITriPortIdList ports);
    // Ref: 5.6.4.6
    void TriEndWait(ITriComponentId component);
}
```
7 TCI extensions for the package

7.1 Extensions to clause 7.3.3.2 of ETSI ES 201 873-6: TCI-CH provided

Clause 7.3.3.2.31  tciSetStreamValueReq (TE → CH)

<table>
<thead>
<tr>
<th>Signature</th>
<th>void tciSetStreamValueReq</th>
</tr>
</thead>
<tbody>
<tr>
<td>(in TriPortIdType sender,</td>
<td></td>
</tr>
<tr>
<td>in TriComponentIdType receiver,</td>
<td></td>
</tr>
<tr>
<td>in Value streamValue)</td>
<td></td>
</tr>
</tbody>
</table>

| In Parameters | sender identifier of the port via which the message is sent to the receiving component. |
|              | receiver identifier of the receiving component. |
|              | streamValue the stream value to be set. |

| Out Parameters | n.a. |
| Return Value   | void |

| Constraints   | The TE calls this operation at the CH when it executes a new sampling step on a sampled output stream port, which has been connected with a test component port. |

| Effect   | If receiving a tciSetStreamValueReq operation, the CH can call tciSetStreamValue in the TE on the node where the receiver component is deployed. |

Clause 7.3.3.2.33  tciGetStreamValueReq (TE → CH)

<table>
<thead>
<tr>
<th>Signature</th>
<th>void tciGetStreamValueReq</th>
</tr>
</thead>
<tbody>
<tr>
<td>(in TriPortIdType receiver,</td>
<td></td>
</tr>
<tr>
<td>in TriComponentIdType sender,</td>
<td></td>
</tr>
<tr>
<td>in Value streamValue)</td>
<td></td>
</tr>
</tbody>
</table>

| In Parameters | receiver identifier of the port via which the message is received from the sending component. |
|              | sender identifier of the sending component. |
|              | streamValue the stream value to be received. |

| Out Parameters | n.a. |
| Return Value   | void |

| Constraints   | The TE calls this operation at the CH when it executes a new sampling step on a sampled input stream port, which has been connected with a test component port. |

| Effect   | The CH calls tciGetStreamValue in the TE on the node where the sending component is deployed. |
7.2 Extensions to clause 7.3.3.1 of ETSI ES 201 873-6: TCI-CH required

Clause 7.3.3.1.23 tciSetStreamValue (CH → TE)

| Signature | void tciSetStreamValue  
|           | (in TriPortIdType sender,  
|           | in TriComponentIdType receiver,  
|           | in Value streamValue) |
| In Parameters | sender identifier of the port via which the message is sent to the receiving component.  
|               | receiver identifier of the receiving component.  
|               | streamValue the stream value to be set. |
| Out Parameters | n.a. |
| Return Value | void |
| Constraints | The CH calls this operation in the local TE where receiver is deployed when tciSetStreamValueReq has been called. |
| Effect | The CH updates the respective outgoing stream port on the test component. |

Clause 7.3.3.1.24 tciGetStreamValue (CH → TE)

| Signature | void tciGetStreamValue  
|           | (in TriPortIdType receiver,  
|           | in TriComponentIdType sender,  
|           | in Value streamValue) |
| In Parameters | receiver identifier of the port via which the message is received from the sending component.  
|               | sender identifier of the sending component.  
|               | streamValue the stream value to be received. |
| Out Parameters | n.a. |
| Return Value | void |
| Constraints | The CH calls this operation in the local TE where sender is deployed when tciGetStreamValueReq has been called. |
| Effect | The CH updates the respective incoming stream port on the test component. |

7.3 Extensions to clause 8.5.3.1 of ETSI ES 201 873-6: TCI-CH provided

The interface TciCHProvided is to be extended as follows:

```java
public interface TciCHProvided {
    public void tciSetStreamValue (TriPortId sender, TriComponentId receiver, Value streamValue);  
    public void tciGetStreamValue (TriPortId receiver, TriComponentId sender, Value streamValue);  
}
```
7.4 Extensions to clause 8.5.3.2 of ETSI ES 201 873-6: TCI-CH required

The interface TciCHRequired is to be extended as follows:

```java
public interface TciCHRequired extends TciCDRequired {

    public void tciSetStreamValueReq (TriPortId sender, TriComponentId receiver, Value streamValue);
    public void tciGetStreamValueReq (TriPortId receiver, TriComponentId sender, Value streamValue);
}
```

7.5 Extensions to clause 9.4.3.1 of ETSI ES 201 873-6: TCI-CH provided

The interface TCI-CH Provided is to be extended as follows:

```java
void tciSetStreamValue (TriPortId sender, TriComponentId receiver, Value streamValue)
void tciGetStreamValue (TriPortId receiver, TriComponentId sender, Value streamValue)
```

7.6 Extensions to clause 9.4.3.2 of ETSI ES 201 873-6: TCI-CH required

The interface TCI-CH Required is to be extended as follows:

```java
void tciSetStreamValueReq (TriPortId sender, TriComponentId receiver, Value streamValue)
void tciGetStreamValueReq (TriPortId receiver, TriComponentId sender, Value streamValue)
```

7.7 Extensions to clause 10.6.3.1 of ETSI ES 201 873-6: TciChRequired

The class that defines the TCI_CH required interface is to be extended as follows:

```java
virtual void tciSetStreamValueReq (const TriPortId *sender, const TriComponentId *receiver, const TciValue *streamValue)=0;
virtual void tciGetStreamValueReq (const TriPortId *receiver, const TriComponentId *sender, const TciValue *streamValue)=0;
```

7.8 Extensions to clause 10.6.3.2 of ETSI ES 201 873-6: TciChProvided

The class that defines the TCI_CH provided interface is to be extended as follows:

```java
virtual void tciSetStreamValue (const TriPortId *sender, const TriComponentId *receiver, const TciValue *streamValue)=0;
virtual void tciGetStreamValue (const TriPortId *receiver, const TriComponentId *sender, const TciValue *streamValue)=0;
```
7.9 Extensions to clause 12.5.3.1 of ETSI ES 201 873-6: TCI-CH provided

The interface ITciCHProvided is to be extended as follows:

```java
public interface ITciCHProvided {
    public void tciSetStreamValue (ITriPortId sender,
                                   ITriComponentId receiver,
                                   ITciValue streamValue);
    public void tciGetStreamValue (ITriPortId receiver,
                                    ITriComponentId sender,
                                    ITciValue streamValue);
}
```

7.10 Extensions to clause 12.5.3.2 of ETSI ES 201 873-6: TCI-CH required

The interface ITciCHRequired is to be extended as follows:

```java
public interface ITciCHRequired {
    public void tciSetStreamValueReq (ITriPortId sender,
                                       ITriComponentId receiver,
                                       ITciValue streamValue);
    public void tciGetStreamValueReq (ITriPortId receiver,
                                         ITriComponentId sender,
                                         ITciValue streamValue);
}
```
Annex A (normative):  
BNF and static semantics

A.1 New TTCN-3 terminals

Table A.1: List of new TTCN-3 terminals defined in this package which are reserved words

<table>
<thead>
<tr>
<th>apply</th>
<th>at</th>
<th>history</th>
<th>inv</th>
<th>par</th>
<th>values</th>
</tr>
</thead>
<tbody>
<tr>
<td>assert</td>
<td>cont</td>
<td>duration</td>
<td>finished</td>
<td>seq</td>
<td>wait</td>
</tr>
<tr>
<td>delta</td>
<td>mode</td>
<td>notinv</td>
<td>onentry</td>
<td>stepsize</td>
<td></td>
</tr>
<tr>
<td>duration</td>
<td></td>
<td></td>
<td></td>
<td>stream</td>
<td></td>
</tr>
<tr>
<td>finished</td>
<td></td>
<td></td>
<td></td>
<td>timestamp</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>until</td>
<td></td>
</tr>
</tbody>
</table>

The TTCN-3 terminals listed in table A.1 shall not be used as identifiers in a TTCN-3 module. These terminals shall be written in all lowercase letters.

A.2 Changed BNF Rules

This clause includes all BNF productions that are modifications of BNF rules defined in the TTCN-3 core language document ETSI ES 201 873-1 [1]. When using this package the BNF rules below replace the corresponding BNF rules in the TTCN-3 core language document. The rule numbers define the correspondence of BNF rules.

Additions to clause A.1.6 of ETSI ES 201 873-1 [1] are identified by underlined font, deletions are identified by strikethrough font. In case of contradiction between the above clause of ETSI ES 201 873-1 [1] and this clause (i.e. parts of the productions not marked by strikethrough font is changed in ETSI ES 201 873-1 [1]), ETSI ES 201 873-1 [1] takes precedence, i.e. tools supporting the present document shall apply the insertions and deletions of this clause to the actual ETSI ES 201 873-1 [1] production or static semantics rule automatically.

7. ModuleDefinition ::= (Visibility) (TypeDef | ConstDef | TemplateDef | ModuleParDef | FunctionDef | SignatureDef | TestcaseDef | AltstepDef | ImportDef | ExtFunctionDef | ExtConstDef | ModuleControlDef | ModeDef )  
   ("public") GroupDef | ("private") FriendModuleDef)  
   ) [WithStatement]

52. PortDefAttribs ::= MessageAttribs | ProcedureAttribs | MixedAttribs | StreamAttribs

81. PortElement ::= Identifier [ArrayDef] [AssignmentChar PortInitialValue]

A.3 New BNF Rules

This clause includes all additional BNF productions that needed to define the syntax introduced by this package. All rules start with the digits "786". The numbering of other new rules start with number 786001.

786001. NowOp ::= "now"
786002. StepsizeKeyword ::= "stepsize"
786003. StreamAttribs ::= StreamKeyword "{ [ { StreamValueDef | ConfigParamDef } [SemiColon]+ ] }"
786004. StreamValueDef ::= StreamDirection Type
786005. StreamKeyword ::= "stream"
786006. StreamDirection ::= InParKeyword | OutParKeyword | InOutParKeyword
786007. PortInitialValue ::= Expression
786008. StreamDataOps ::= ArrayIdentifierRef Dot PortDataOp
/** STATIC SEMANTICS The ArrayIdentifierRef part shall identify a stream port*/
786010. PortValueOp ::= ValueKeyword
786011. PortTimestampOp ::= "timestamp"
786012. PortDeltaOp ::= "delta"
786013. PortHistoryOp ::= HistoryOpKeyword [ "(" StartValue ["," EndValue ")" ]
786014. HistoryOpKeyword ::= "history"
786015. StartValue ::= Expression
786016. EndValue ::= Expression
786017. PortValuesOp ::= ValuesOpKeyword [ "(" StartValue ["," EndValue ")" ]
786018. ValuesOpKeyword ::= "values"
786019. StreamNavigationOps ::= ArrayIdentifierRef Dot ( PortPrevOp | PortAtOp ) [ Dot PortDataOp ]
/** STATIC SEMANTICS The ArrayIdentifierRef part shall identify a stream port*/
786020. PortPrevOp ::= PrevOpKeyword [ "(" IndexValue ")" ]
786021. PrevOpKeyword ::= "prev"
786022. IndexValue ::= Expression
786023. PortAtOp ::= AtOpKeyword [ "(" TimeIndexValue ")" ]
786024. AtOpKeyword ::= "at"
786025. TimeIndexValue ::= Expression
786026. ModeLocalOps ::= DurationOp | FinishedOp | NotinvOp
786027. DurationOp ::= "duration"
786028. FinishedOp ::= "finished"
786029. NotinvOp ::= "notinv"
786030. StreamEvalStatements ::= ArrayIdentifierRef Dot PortApplyOp
    /** STATIC SEMANTICS The ArrayIdentifierRef part shall identify a stream port*/
786031. PortApplyOp ::= ApplyKeyword [ "(" ApplyParameter ")" ]
786032. ApplyKeyword ::= "apply"
786033. ApplyParameter ::= TemplateInstance
786034. AssertStatement ::= AssertKeyword [ "(" AssertionList ")" ]
786035. AssertKeyword ::= "assert"
786036. AssertionList ::= Expression {"," Expression }
786037. WaitStatement ::= WaitKeyword "(" WaitDuration ")"
786038. WaitKeyword ::= "wait"
786039. WaitDuration ::= Expression
786040. ModeSpecification ::= { BasicMode | SeqMode | ParMode } [ UntilBlock ] | ModeInstance
786041. BasicMode ::= ContKeyword "{ [VarInstance [SemiColon] |
    [OnEntryBlock |
    [InvariantBlock] |
    [BasicModeOp [SemiColon] |
    [OnExitBlock ]
    ]"
786042. ContKeyword ::= "cont"
786043. OnEntryBlock ::= OnEntryKeyword "{ [StatementBlock ]"
786044. OnEntryKeyword ::= "onentry"
786045. InvariantBlock ::= InvKeyword "{ [InvariantList ]"
786046. InvKeyword ::= "inv"
786047. InvariantList ::= [BooleanExpression {"," BooleanExpression ]
786048. BasicModeOp ::= Assignment | AssertStatement
786049. OnExitBlock ::= OnExitKeyword "{ [StatementBlock ]"
786050. OnExitKeyword ::= "onexit"
786051. SeqMode ::= SeqKeyword "{ [VarInstance] |
    [OnEntryBlock |
    [InvariantBlock] |
    ModeList |
    [OnExitBlock ]
    ]"
786052. SeqKeyword ::= "seq"
786053. ParMode ::= ParKeyword "{ [VarInstance] |
    [OnEntryBlock |
    [InvariantBlock] |
    [ModeSpecification [SemiColon] |
    [OnExitBlock ]
    ]"
786054. ParKeyword ::= "par"
786056. UntilBlock ::= UntilKeyword "{ [UntilGuardList ]"
786057. UntilKeyword ::= "until"
786058. UntilGuardList ::= [UntilGuardStatement]
786059. UntilGuardStatement ::= { ( ["[" BooleanExpression "]" [GuardOp ] ) |
    ["[" ]" GuardOp ] ) |
    [StatementBlock ] [GotoStatement]
786060. ModeTypeDef ::=TypeDefKeyword ModeKeyword Identifier |
    ["(" TemplateOrValueFormalParList ")" ] |
    [RunsOnSpec]
786061. ModeKeyword ::= "mode"
786062. ModeDef ::= ModeKeyword Identifier |
    ["(" TemplateOrValueFormalParList ")" ] |
    [RunsOnSpec] |
    ModeSpecification
786063. ModeInstance ::= ModeRef "{ [ActualParList ]"
786064. ModeRef ::= [Identifier Dot] Identifier
Annex B (informative):
Bibliography


- DIN 40146: "Begriffe der Nachrichtenübertragung".
## History

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