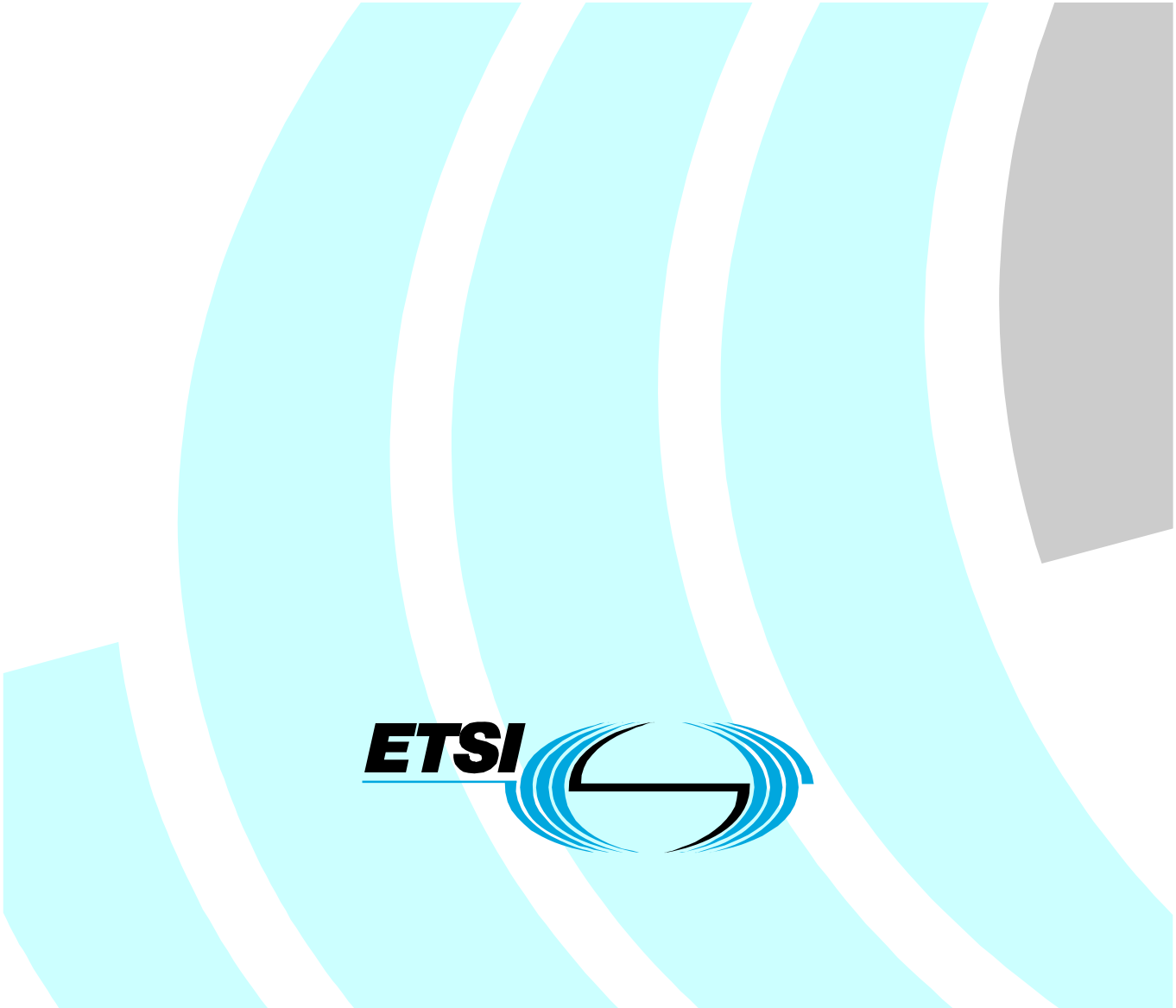
ETSI EN 303 213-2 V1.1.1 (2010-10)

European Standard (Telecommunications series)

Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 2: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 2 including external interfaces



Reference
DEN/AERO-00001-2

Keywords
air traffic management, aeronautical,
interoperability

ETSI

650 Route des Lucioles
F-06921 Sophia Antipolis Cedex - FRANCE

Tel.: +33 4 92 94 42 00 Fax: +33 4 93 65 47 16

Siret N° 348 623 562 00017 - NAF 742 C
Association à but non lucratif enregistrée à la
Sous-Préfecture de Grasse (06) N° 7803/88

Important notice

Individual copies of the present document can be downloaded from:
http://www.etsi.org

The present document may be made available in more than one electronic version or in print. In any case of existing or perceived difference in contents between such versions, the reference version is the Portable Document Format (PDF). In case of dispute, the reference shall be the printing on ETSI printers of the PDF version kept on a specific network drive within ETSI Secretariat.

Users of the present document should be aware that the document may be subject to revision or change of status.
Information on the current status of this and other ETSI documents is available at
http://portal.etsi.org/tb/status/status.asp

If you find errors in the present document, please send your comment to one of the following services:
http://portal.etsi.org/chaircor/ETSI_support.asp

Copyright Notification

Contents

Intellectual Property Rights 5
Foreword 5
Introduction 6
1 Scope 7
2 References 7
2.1 Normative references 7
2.2 Informative references 8
3 Definitions and abbreviations 8
3.1 Definitions 8
3.2 Abbreviations 10
4 Requirements for design, implement, built, maintain and operate an A-SMGCS Level 2 System 11
4.1 Requirements for implementing A-SMGCS Level 2 Systems 11
4.1.1 Monitoring and alerting 11
4.1.2 Velocity 11
4.1.3 Alert situation 11
4.1.4 Safety 11
4.1.4.1 Safety assessment 11
4.1.4.2 Service requirements 11
4.1.4.3 Safety net 11
4.1.4.4 Information to Vehicle Drivers 11
4.1.5 Human capabilities 11
4.1.5.1 Presentations of alert 11
4.1.5.2 Human-Machine Interface 12
4.2 Design Requirements for A-SMGCS Level 2 Systems 12
4.2.1 Requirements for ATC Workstation HMI 12
4.2.2 Alerts 12
4.2.3 Presentation of Alerts 12
4.2.4 Monitoring and Alerting Parameters 12
4.2.4.1 Probability of Detection of an Alert Situation 12
4.2.4.2 Accuracy and Resolution 12
4.2.4.3 Probability of False Alert 12
4.2.5 Performance 12
4.2.6 Procedures and Working Methods 12
4.2.7 Control service 12
4.2.8 Pre-requisite 13
4.2.9 Interface to Vehicle Driver 13
4.3 Logical Architecture and Construction of the system 13
4.3.1 Surveillance Services and Conflict detection 13
4.3.2 Pre-requisite for A-SMGCS Level 2 13
4.3.3 Void 13
4.3.4 HMI and Vehicle HMI 13
4.3.5 Guidance Service to Vehicle Drivers 13
4.4 Build requirements for A-SMGCS Level 2 System 13
4.4.1 Probability of Detection 13
4.4.2 Probability of False Detection 13
4.4.3 Probability of Identification 13
4.4.4 Probability of False Identification 13
4.4.5 Reported Position Accuracy 13
4.4.6 Reported Velocity Accuracy 14
4.4.7 Target Report Update Rate 14
4.4.8 Position Renewal Time-Out Period 14
4.4.9 Identification Renewal Time-Out Period 14
4.4.10 Track Continuity 14

4.4.11 Monitoring and Alerting 14
4.5 Maintenance Requirements for A-SMGCS Level 2 Systems 14
4.6 Requirements for operation of A-SMGCS Level 2 Systems 14
4.6.1 Compliance with ATC Procedures and Working Methods 14
4.6.2 Operational procedures 14
4.6.3 Safety 14
4.6.4 Vehicle identifier 14

5 Testing 14

Annex SA (normative): Standards Annex 15

SA.1 Correspondence between this European Standard and the Single European Sky Interoperability Regulation for A-SMGCS Systems Level 2 15

Annex A (normative): Checklist 19

A.1 Interoperability Regulation Annex II Essential Requirements; Part A: General requirements 20

A.2 Interoperability Regulation Annex II Essential Requirements; Part B: Specific requirements 24
A.2.1 Systems and procedures for airspace management 24
A.2.2 Systems and procedures for air traffic flow management 25
A.2.3 Systems and procedures for air traffic services 25
A.2.3.1 Flight data processing systems 25
A.2.3.2 Surveillance data processing systems 27
A.2.3.3 Human-machine interface systems 28
A.2.4 Communications systems and procedures for ground-to-ground, air-to-ground and air-to-air communications 29
A.2.5 Navigation systems and procedures 30
A.2.6 Surveillance systems and procedures 30
A.2.7 Systems and procedures for aeronautical information services 31
A.2.8 Systems and procedures for the use of meteorological information 31

Annex B (informative): The EN title in the official languages 33

Annex C (informative): Bibliography 35

History 36

Intellectual Property Rights

IPRs essential or potentially essential to the present document may have been declared to ETSI. The information pertaining to these essential IPRs, if any, is publicly available for **ETSI members and non-members**, and can be found in ETSI SR 000 314: *"Intellectual Property Rights (IPRs); Essential, or potentially Essential, IPRs notified to ETSI in respect of ETSI standards"*, which is available from the ETSI Secretariat. Latest updates are available on the ETSI Web server (http://webapp.etsi.org/IPR/home.asp).

Pursuant to the ETSI IPR Policy, no investigation, including IPR searches, has been carried out by ETSI. No guarantee can be given as to the existence of other IPRs not referenced in ETSI SR 000 314 (or the updates on the ETSI Web server) which are, or may be, or may become, essential to the present document.

Foreword

This European Standard (Telecommunications series) has been produced by ETSI Technical Committee Aeronautics (AERO).

The present document has been produced by ETSI in response to European Commission mandate M/390 for the Interoperability of the European Air Traffic Management Network.

The present document has been developed in cooperation with Eurocae for compliance with the Essential Requirements of the Single European Sky Interoperability Regulation 552/2004 [i.1] and/or requirements given in implementing rules for the Single European Sky Interoperability Regulation.

The presumption of conformity which is linked to the full application of EN 303 213 (parts 1 to 4) can only be claimed after EN 303 213 (parts 1 to 4) has been listed in the Official Journal of the European Union as Community Specification.

General and specific requirements for presumption of conformity to SES Interoperability Regulation 552/2004 [i.1] as amended by Regulation 1070/2009 [i.5] are given in the normative annexes of the present document.

NOTE: Other requirements and other EU Regulations and/or Directives may be applicable to the product(s) falling within the scope of the present document.

The present document is part 2 of a multi-part deliverable covering Advanced Surface Movement Guidance and Control System (A-SMGCS), as identified below:

Part 1: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 1 including external interfaces";

Part 2: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 2 including external interfaces";

Part 3: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed cooperative sensor including its interfaces";

Part 4: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed non-cooperative sensor including its interfaces";

Part 5: "Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for transmitter used in multilateration equipment";

Part 6: "Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for deployed surface movement radar sensors".

National transposition dates	
Date of adoption of this EN:	15 October 2010
Date of latest announcement of this EN (doa):	31 January 2011
Date of latest publication of new National Standard or endorsement of this EN (dop/e):	31 July 2011
Date of withdrawal of any conflicting National Standard (dow):	31 July 2012

Introduction

The European Union launched the Legislation "Single European Sky" (SES) in 2002 which was adopted in 2004 and amended by Regulation (EC) No 1070/2009 [i.5].

The SES legislation is based on a framework of 4 regulations, which includes the Interoperability Regulation [i.1]. The objective of the Interoperability Regulation is to ensure interoperability of the European Air Traffic Management Network (EATMN) consistent with air navigation services. Under this regulation, the use of a European Standard referenced in the Official Journal of the European Union as Community Specification (CS) is a means of compliance to the essential requirements of the Regulation and/or the relevant implementing rules for interoperability.

The present document takes into account the Council Decision 2009/320/EC endorsing the European Air Traffic Management Master Plan of the Single European Sky ATM Research (SESAR) project [i.3].

1 Scope

The present document is applicable to Advanced Surface Movement Guidance and Control Systems (A-SMGCS) Level 2. This system provides enhanced surveillance functionalities such as advanced monitoring and alerting functions.

The present document provides a European Standard for Air Navigation Service Providers, who have to demonstrate and declare compliance of their systems and procedures to the IOP Regulation.

Any software elements related to the software assurance level of an A-SMGCS are outside of the scope of the present document. As such the essential requirements of the Interoperability Regulation are not considered for software elements within the present document.

The present document does not give presumption of conformity related to the maintenance requirements, environmental constraints, procedure level, effect of harmful interference and civil/military coordination.

NOTE 1: For these ERs, please refer to the Air Navigation Service Provider procedures.

NOTE 2: For those parts of the essential requirements, where annexes A and SA give no presumption of conformity, please refer to the Air Navigation Service Provider procedures.

Requirements in the present document which refer to "should" statements or recommendations in the normatively referenced material (clause 2.1) are to be interpreted as fully normative ("shall") for the purpose of compliance with the present document.

2 References

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at http://docbox.etsi.org/Reference.

NOTE: While any hyperlinks included in this clause were valid at the time of publication ETSI cannot guarantee their long term validity.

2.1 Normative references

The following referenced documents are necessary for the application of the present document.

[1] EUROCAE ED-87B (ED-87B including Amendment No 1 published 01/2009): "MASPS for Advanced Surface Movement Guidance and Control Systems".

[2] EUROCONTROL 07/01/11-05 (V2.0: December 2006): "Operational Concept and Requirements for A-SMGCS Implementation Level 2".

[3] EUROCONTROL 07/01/09-01 (V2.0: November 2006): "A-SMGCS Levels 1 & 2 Preliminary Safety Case".

[4] EUROCONTROL 07/01/11-07 (V2.0: December 2006): "Functional Specification for A-SMGCS Implementation Level 2".

[5] ETSI EN 303 213-1: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 1: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 1 including external interfaces".

2.2 Informative references

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

[i.1] Regulation (EC) No 552/2004 of the European Parliament and of the Council of 10 March 2004 on the interoperability of the European Air Traffic Management network (interoperability Regulation), OJ L 96, 31.03.2004 as amended by Regulation (EC) No 1070/2009.

[i.2] Regulation (EC) No 549/2004 of the European Parliament and of the Council of 10 March 2004 laying down the framework for the creation of the single European sky (the framework Regulation), OJ L 96, 31.03.2004 as amended by Regulation (EC) No 1070/2009.

[i.3] Council Decision 2009/320/EC endorsing the European Air Traffic Management Master Plan of the Single European Sky ATM Research (SESAR) project, 30.03.2009.

[i.4] ICAO Document 9830, AN/452: "Advanced Surface Movement Guidance and Control Systems (A-SMGCS) Manual", First Edition, 2004.

[i.5] Regulation (EC) No 1070/2009 of the European Parliament and of the Council of 21 October 2009 amending Regulations (EC) No 549/2004, (EC) No 550/2004, (EC) No 551/2004 and (EC) No 552/2004 in order to improve the performance and sustainability of the European aviation system, OJ L 300, 14.11.2009.

[i.6] ETSI EN 303 213-3: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed cooperative sensor including its interfaces".

[i.7] ETSI EN 303 213-4: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed non-cooperative sensor including its interfaces".

3 Definitions and abbreviations

3.1 Definitions

For the purposes of the present document, the following terms and definitions apply:

alert situation: any situation relating to aerodrome operations which has been defined as requiring particular attention or action

A-SMGCS Level 1: A-SMGCS including a comprehensive Surveillance element capable of the location and classification of all aircraft and vehicles within the area of interest and the identification of cooperative aircraft and vehicles

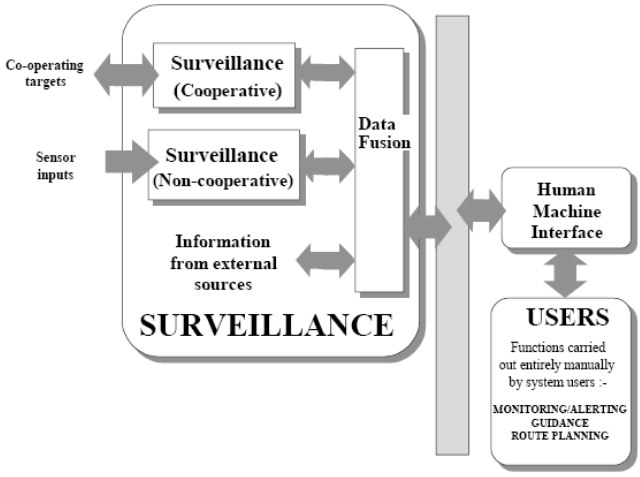


Figure 1: A-SMGCS Level 1 Functional Configuration

A-SMGCS Level 2: A-SMGCS including the capabilities of A-SMGCS Level 1 and uses the comprehensive surveillance data available to monitor the situation in the area of interest against a set of rules which will enable the system to alert the user to hazardous situations

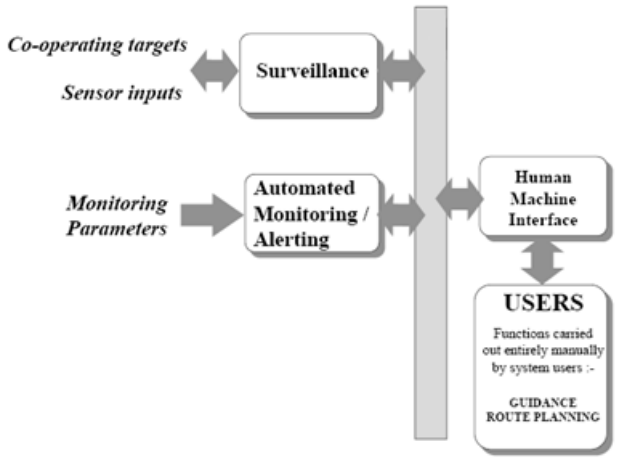


Figure 2: A-SMGCS Level 2 Functional Configuration

Advanced Surface Movement Guidance and Control System: system providing routing, guidance, surveillance for the control to aircraft and vehicles in order to maintain the declared surface movement rate under all local weather conditions within the aerodrome visibility operational Level (AVOL) while maintaining the required level of safety

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

aerodrome: defined area on land or water (including any buildings, installations, and equipment) intended to be used either wholly or in part for arrival, departure and surface movement of aircraft

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

apron: defined area on a land aerodrome, intended to accommodate aircraft for purposes of loading or unloading passengers, mail or cargo, fuelling, parking or maintenance

NOTE 1: This definition is derived from the ICAO Document 9830 [i.4].

NOTE 2: De-icing platforms, including remote de-icing areas, are considered as apron areas.

availability: probability that a system or an item is in a functioning state at a given point in time

classification: function which groups targets into various types (e.g. large, medium, small)

constituents: tangible objects such as hardware and intangible objects such as software upon which the interoperability of the EATMN depends

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

manoeuvring area: part of an aerodrome to be used for take-off, landing and taxiing of aircraft, excluding aprons

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

movement area: part of an aerodrome to be used for take-off, landing and taxiing of aircraft, consisting of the manoeuvring area and apron(s)

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

procedure: standard method for either the technical or operational use of the system, in the context of agreed and validated concepts of operation requiring uniform implementation throughout the EATMN

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

reported velocity accuracy: difference, at a specified confidence level, between the reported Target velocity and the actual Target velocity at the time of the report

system: aggregation of airborne and ground based constituents, as well as space-based equipment, that provides support for air navigation services for all phases of flight

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

target: aircraft, vehicle or obstacle that is displayed on a surveillance display

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

test targets: form of either fixed reflectors or active devices transponders, mounted at fixed positions within the Coverage Volume

update: renewal of target reports relating to all targets under surveillance

3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply:

A-SMGCS	Advanced Surface Movement Guidance and Control Systems
ATC	Air Traffic Control
ATCO	Air Traffic Controller
ATM	Air Traffic Management
AVOL	Aerodrome Visibility Operational Level
CS	Community Specification
doa	date of announcement
dow	date of withdrawal
EATMN	European Air Traffic Management Network
EC	European Communities
EN	European Norm - (standard)
ER	Essential Requirement
EUROCAE	EUROpean organization for Civil Aviation Equipment
EUROCONTROL	EUROpean organization for the safety of air navigation
HMI	Human Machine Interface
ICAO	International Civil Aviation Organization
IOP Regulation	InterOPerability Regulation
MASPS	Minimum Aviation Systems Performance Specification
SES	Single European Sky
SESAR	Single European Sky ATM Research

4 Requirements for design, implement, built, maintain and operate an A-SMGCS Level 2 System

4.1 Requirements for implementing A-SMGCS Level 2 Systems

4.1.1 Monitoring and alerting

The monitoring and alerting function shall comply with the requirements as defined in ED-87B [1], clause 2.5.1.2.

4.1.2 Velocity

The A-SMGCS System shall provide a Reported Velocity Accuracy as defined in ED-87B [1], clause 3.2.2.6.

4.1.3 Alert situation

The A-SMGCS System shall be able to distinguish between alert situations as defined in ED-87B [1], clause 3.3.1.

4.1.4 Safety

4.1.4.1 Safety assessment

A safety assessment for A-SMGCS Level 2 system shall be provided. The safety objectives shall comply with the requirements as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 2.1.

NOTE: The safety assessment may follow the methodology from A-SMGCS Levels 1&2 Preliminary Safety Case [3].

4.1.4.2 Service requirements

The A-SMCS System shall comply with the services as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 9.3.1 references Op_Serv-14-Service, Op_Serv-15-User, Op_Serv-16-Conflicts/infringements on runway, Op_Serv-17-Restricted area incursions,Op_Serv-18-Runway protection area, Op_Serv-19-Ground boundary, Op_Serv-20-Air boundary, Op_Serv-21-Traffic Context Update, Op_Serv-22-Alert, Op_Serv-27-Stages of alert, Op_Serv-28-Alert priority, Op_Serv-29-Adaptation to local procedures, Op_Serv-30-Traffic Information Update.

4.1.4.3 Safety net

The A-SMGCS System shall provide a safety net as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 4 and clause 9.3.1 Op_Serv-29-Adaptation to local procedures.

4.1.4.4 Information to Vehicle Drivers

The A-SMGCS System shall provide information to the Vehicle Driver as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 6.3.

4.1.5 Human capabilities

4.1.5.1 Presentations of alert

The A-SMGCS System shall provide alerts to ATCOs as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.2.1.

4.1.5.2 Human-Machine Interface

The HMI of the A-SMGCS System shall comply with the requirements as defined in ED-87B [1], clause 2.5.2.

4.2 Design Requirements for A-SMGCS Level 2 Systems

4.2.1 Requirements for ATC Workstation HMI

The ATC Workstation HMI of the A-SMGCS System shall comply with the requirements as defined in ED-87B [1], clauses 2.5.2 and 2.5.2.1.

4.2.2 Alerts

The A-SMGCS System shall provide the stages of alerts as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.2.2.

4.2.3 Presentation of Alerts

The Presentation of Alerts requirement shall comply with the requirement as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.2.1.

4.2.4 Monitoring and Alerting Parameters

The monitoring and alerting parameters shall comply with the requirements as defined in ED-87B [1], clause 3.3.2.

4.2.4.1 Probability of Detection of an Alert Situation

The Probability of Detection requirement shall comply with the requirement as defined in ED-87B [1], clause 3.3.2.1.

4.2.4.2 Accuracy and Resolution

The Accuracy and Resolution requirement shall comply with the requirement as defined in ED-87B [1], clause 3.3.2.2.

4.2.4.3 Probability of False Alert

The Probability of False Alert requirement shall comply with the requirement as defined in ED-87B [1], clause 3.3.2.3.

4.2.5 Performance

The performance of the A-SMGCS System shall comply with the requirements as defined in ED-87B [1], clause 3.2.3.2.

4.2.6 Procedures and Working Methods

The procedures and Working Methods shall comply with the requirement as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.3 and clause 9.3.1 Op_Serv-29-Adaptation to local procedures.

4.2.7 Control service

The A-SMGCS System shall provide the Control services as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 9.3.1 reference Op_Serv-14-Service, Op_Serv-16-Conflicts/ infringements on runway, Op_Serv-17-Restricted area incursions, Op_Serv-21-Traffic Context Update, Op_Serv-22-Alert, Op_Serv-27-Stages of alert, Op_Serv-28-Alert priority, Op_Serv-29-Adaptation to local procedures, Op_Serv-30-Traffic Information Update.

4.2.8 Pre-requisite

The A-SMGCS System shall comply with the pre-requisite as defined in EN 303 213-1 [5] and A-SMGCS Levels 1 & 2 Preliminary Safety Case [3].

4.2.9 Interface to Vehicle Driver

The A-SMGCS System shall provide an Interface to the Vehicle Driver as defined in Functional Specification for A-SMGCS Implementation Level 2 [4], clause 7.2.3.

4.3 Logical Architecture and Construction of the system

4.3.1 Surveillance Services and Conflict detection

The surveillance services and the conflict detection shall comply with the requirements as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 2.1.

4.3.2 Pre-requisite for A-SMGCS Level 2

The A-SMGCS System shall comply with the pre-requisite as defined in EN 303 213-1 [5].

4.3.3 Void

4.3.4 HMI and Vehicle HMI

The logical architecture of the A-SMGCS System shall comply with the requirements as defined in ED-87B [1], clause 2.5.2 with the modification that all requirements marked as optional in clause 2.5.2.1 Table 2.1 are mandatory.

4.3.5 Guidance Service to Vehicle Drivers

The A-SMGCS System shall comply with requirements as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.5 with the modification that this requirement is mandatory.

4.4 Build requirements for A-SMGCS Level 2 System

4.4.1 Probability of Detection

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.2.

4.4.2 Probability of False Detection

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.3.

4.4.3 Probability of Identification

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.4.

4.4.4 Probability of False Identification

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.5.

4.4.5 Reported Position Accuracy

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.6.

4.4.6 Reported Velocity Accuracy

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.7.

4.4.7 Target Report Update Rate

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.8.

4.4.8 Position Renewal Time-Out Period

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.9.

4.4.9 Identification Renewal Time-Out Period

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.10.

4.4.10 Track Continuity

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.6.11.

4.4.11 Monitoring and Alerting

The A-SMGCS System shall perform the test as defined in ED-87B [1], clause 4.7.

NOTE: This test shall also performed for the HMI.

4.5 Maintenance Requirements for A-SMGCS Level 2 Systems

The present document does not give presumption of conformity related to the maintenance requirements.

4.6 Requirements for operation of A-SMGCS Level 2 Systems

4.6.1 Compliance with ATC Procedures and Working Methods

The ATC Procedures and Working Methods shall comply with the requirements as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 3.3.

4.6.2 Operational procedures

The operational procedures shall comply with the requirements as defined in Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2], clause 7.

4.6.3 Safety

The operational procedures on safety shall comply with the requirements as defined in clause 4.1.4.1.

4.6.4 Vehicle identifier

The A-SMGCS System shall comply with the requirements as defined in ED-87B [1], clause 3.2.2.1.

5 Testing

The testing of an A-SMGCS Level 2 System is covered with the build requirements from clause 4.4.

Annex SA (normative): Standards Annex

This annex provides a relationship between the present document and the Essential Requirements of the Single European Sky Interoperability Regulation.

A-SMGCS Systems Level 2 shall comply with the Essential Requirements of the Interoperability Regulation as defined and described in the traceability matrixes of this annex (tables SA.1 and SA.2).

SA.1 Correspondence between this European Standard and the Single European Sky Interoperability Regulation for A-SMGCS Systems Level 2

Table SA.1: Traceability from Interoperability Regulation to clauses of the present document

(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Part A	Clause(s) of the present document	Qualifying remarks/Notes
ER 1 Seamless operation.	4.1.1 Monitoring and alerting 4.1.2 Velocity 4.1.3 Alert situation 4.1.4.2 Service requirements 4.1.4.3 Safety net 4.1.5.1 Presentations of alert 4.1.5.2 Human-Machine Interface 4.2.1 Requirements for ATC Workstation HMI 4.2.2 Alerts 4.2.3 Performance 4.2.4 Monitoring and Alerting Parameters 4.2.4.1 Probability of Detection of an Alert Situation 4.2.4.3 Probability of False Alert 4.2.5 Presentation of Alerts 4.2.6 Procedures and Working Methods 4.2.7 Control service 4.2.8 Pre-requisite 4.2.9 Interface to Vehicle Driver 4.3.2 Pre-requisite for A-SMGCS Level 2 4.3.4 HMI and Vehicle HMI 4.4.11 Monitoring and Alerting 4.6.1 Compliance with ATC Procedures and Working Methods 4.6.2 Operational procedures 4.6.4 Vehicle identifier	The present document does not give presumption of conformity related to maintenance of the system.
ER 2 Support for new concepts of operation.	4.1.4.1 Safety assessment 4.1.4.4 Information to Vehicle Drivers	
ER 3 Safety.	4.1.4.1 Safety assessment 4.1.4.3 Safety net 4.1.5.1 Presentations of alert 4.1.5.2 Human-Machine Interface 4.2.8 Pre-requisite	
ER 4 Civil-military coordination.		The present document does not give presumption of conformity.
ER 5 Environmental constraints.		The present document does not give presumption of conformity.
ER 6 Principles governing the logical architecture of systems.	4.3.1 Surveillance Services and Conflict detection 4.3.2 Pre-requisite for A-SMGCS Level 2 4.3.4 HMI and Vehicle HMI 4.3.5 Guidance Service to Vehicle Drivers	

(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Part A	Clause(s) of the present document	Qualifying remarks/Notes
ER 7 Principles governing the construction of systems.	4.2.8 Pre-requisite	

(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Part B	Clause(s) of the present document	Qualifying remarks/Notes
ER 1.1 Seamless operation of airspace management.		Not covered by EN 303 213 (parts 1 to 4)
ER 2.1 Seamless operation of air traffic flow management.		Not covered by EN 303 213 (parts 1 to 4)
ER 3.1.1 Seamless operation of flight data processing.		Not covered by EN 303 213 (parts 1 to 4)
ER 3.1.2 Support for new concepts of operation for flight data processing.		Not covered by EN 303 213 (parts 1 to 4)
ER 3.2.1 Seamless operation surveillance data processing systems.	4.2.4.2 Accuracy and Resolution 4.4.1 Probability of Detection 4.4.2 Probability of False Detection 4.4.3 Probability of Identification 4.4.4 Probability of False Identification 4.4.5 Reported Position Accuracy 4.4.6 Reported Velocity Accuracy 4.4.7 Target Report Update Rate 4.4.8 Position Renewal Time-Out Period 4.4.9 Identification Renewal Time-Out Period 4.4.10 Track Continuity 4.4.11 Monitoring and Alerting	
ER 3.2.2 Support for new concepts of operation for surveillance data processing systems.	4.2.8 Pre-requisite	
ER 3.3.1 Seamless operation of Human-machine interface systems.	4.3.4 HMI and Vehicle HMI 4.4.11 Monitoring and Alerting	
ER 3.3.2 Support for new concepts of operation for Human-machine interface systems.	4.3.4 HMI and Vehicle HMI	
ER 4.1 Seamless operation of Communications systems and procedures for ground-to-ground, air-to-ground and air-to-air communications.		Not covered by EN 303 213 (parts 1 to 4)
ER 4.2 Support for new concepts of operation for Communications systems and procedures for ground-to-ground, air-to-ground and air-to-air communications.		Not covered by EN 303 213 (parts 1 to 4)
ER 5.1 Seamless operation of Navigation systems and procedures.		Not covered by EN 303 213 (parts 1 to 4)
ER 6.1 Seamless operation of Surveillance systems and procedures.		Not covered by EN 303 213 (parts 1 to 4)
ER 7.1 Seamless operation of Systems and procedures for aeronautical information services.		Not covered by EN 303 213 (parts 1 to 4)
ER 7.2 Support for new concepts of operation for systems and procedures for aeronautical information services.		Not covered by EN 303 213 (parts 1 to 4)
ER 8.1 Seamless operation of systems and procedures for the use of meteorological information.		Not covered by EN 303 213 (parts 1 to 4)

(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Part B	Clause(s) of the present document	Qualifying remarks/Notes
ER 8.2 Support for new concepts of operation for systems and procedures for the use of meteorological information.		Not covered by EN 303 213 (parts 1 to 4)

Table SA.2: Traceability from clauses of the present document to Interoperability Regulation

Clause(s) of the present document	(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Parts A and B	Qualifying remarks/Notes
4.1.1 Monitoring and alerting	ER 1 Seamless operation	
4.1.2 Velocity	ER 1 Seamless operation	
4.1.3 Alert situation	ER 1 Seamless operation	
4.1.4.1 Safety assessment	ER 2 Support for new concepts of operation ER 3 Safety	
4.1.4.2 Service requirements	ER 1 Seamless operation	
4.1.4.3 Safety net	ER 1 Seamless operation ER 3 Safety	
4.1.4.4 Information to Vehicle Drivers	ER 2 Support for new concepts of operation	
4.1.5.1 Presentations of alert	ER 1 Seamless operation ER 3 Safety	
4.1.5.2 Human-Machine Interface	ER 1 Seamless operation ER 3 Safety	
4.2.1 Requirements for ATC Workstation HMI	ER 1 Seamless operation	
4.2.2 Alerts	ER 1 Seamless operation	
4.2.3 Presentation of Alerts	ER 1 Seamless operation	
4.2.4 Monitoring and Alerting Parameters	ER 1 Seamless operation	
4.2.4.1 Probability of Detection of an Alert Situation	ER 1 Seamless operation	
4.2.4.2 Accuracy and Resolution	ER 3.2.1 Seamless operation surveillance data processing systems	
4.2.4.3 Probability of False Alert	ER 1 Seamless operation	
4.2.5 Performance	ER 1 Seamless operation	
4.2.6 Procedures and Working Methods	ER 1 Seamless operation	
4.2.7 Control service	ER 1 Seamless operation	
4.2.8 Pre-requisite	ER 1 Seamless operation ER 3 Safety ER 3.2.2 Support for new concepts of operation for surveillance data processing systems ER 7 Principles governing the construction of systems	
4.2.9 Interface to Vehicle Driver	ER 1 Seamless operation	
4.3.1 Surveillance Services and Conflict detection	ER 6 Principles governing the logical architecture of systems	
4.3.2 Pre-requisite for A-SMGCS Level 2	ER 1 Seamless operation	
4.3.3 Void	n/a	
4.3.4 HMI and Vehicle HMI	ER 1 Seamless operation ER 3.3.1 Seamless operation of Human-machine interface systems ER 3.3.2 Support for new concepts of operation for Human-machine interface systems	
4.3.5 Guidance Service to Vehicle Drivers	ER 7 Principles governing the construction of systems	
4.4.1 Probability of Detection	ER 3.2.1 Seamless operation surveillance data processing systems	

Clause(s) of the present document	(Essential) Requirements (ERs) of SES Interoperability Regulation, Annex II, Parts A and B	Qualifying remarks/Notes
4.4.2 Probability of False Detection	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.3 Probability of Identification	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.4 Probability of False Identification	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.5 Reported Position Accuracy	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.6 Reported Velocity Accuracy	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.7 Target Report Update Rate	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.8 Position Renewal Time-Out Period	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.9 Identification Renewal Time-Out Period	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.10 Track Continuity	ER 3.2.1 Seamless operation surveillance data processing systems	
4.4.11 Monitoring and Alerting	ER 1 Seamless operation ER 3.2.1 Seamless operation surveillance data processing systems ER 3.3.1 Seamless operation of Human-machine interface systems	
4.6.1 Compliance with ATC Procedures and Working Methods	ER 1 Seamless operation	
4.6.2 Operational procedures	ER 1 Seamless operation	
4.6.4 Vehicle identifier	ER 1 Seamless operation	

NOTE: Other requirements and other EU Regulations and/or Directives may be applicable to the product(s) falling within the scope of the present document.

Annex A (normative): Checklist

The purpose of this annex is to provide a comprehensive traceability of evidence on constituents and system levels against sub-clauses of the Essential Requirements (ERs) of the Interoperability Regulation (EC 552/2004 [i.1]) as amended by Regulation EC 1070/2009 [i.5], analyzing keywords of these same essential requirements.

These keywords mainly address the phases of design, build, operation and maintenance of systems and constituents as well as specifically required qualities or attributes as defined in the ERs of the SES Interoperability Regulation.

A-SMGCS Systems Level 2 shall comply with the Essential Requirements of the Interoperability Regulation as defined and described in the tables of this annex.

A.1 Interoperability Regulation Annex II Essential Requirements; Part A: General requirements

Table A.1

1	**ER 1 seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Air traffic management systems and their constituents shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to ensure the seamless operation of the EATMN at all times and for all phases of flight. Seamless operation can be expressed, in particular, in terms of information sharing, including the relevant operational status information, common understanding of information, comparable processing performances and the associated procedures enabling common operational performances agreed for the whole or parts of the EATMN."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
1.1	Designed	n/a	ED-87B [1] Clause 2.5.2 Human-Machine Interface Clause 2.5.2.1 General Requirements for ATC Workstation HMI Clause 3.2.2 Stages of alert Clause 3.2.3.2 Level 2 Systems Clause 3.3.2 Definition of Monitoring/Alerting Parameters Clause 3.3.2.1 Probability of Detection of an Alert Situation (PDAS) Clause 3.3.2.3 Probability of False Alert (PFA) Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 3.2.1 Presentation of alerts to ATCOs Clause 3.3 Compliance with ATC Procedures and Working Methods Clause 9.3.1 Service Requirements Op_Serv-14-Service Op_Serv-16-Conflicts/infringements on runway Op_Serv-17-Restricted area incursions Op_Serv-18-Runway protection area Op_Serv-19-Ground boundary Op_Serv-20-Air boundary Op_Serv-21-Traffic Context Update, Op_Serv-22-Alert Op_Serv-27-Stages of alert Op_Serv-28-Alert priority Op_Serv-29-Adaptation to local procedures Op_Serv-30-Traffic Information Update EN 303 213-1 [5] Functional Specification for A-SMGCS Implementation Level 2 [4] Clause 7.2.3 Interface with driver
1.2	Built	n/a	ED-87B [1] Clause 4.7 Monitoring/alerting element tests
1.3	Maintained	The present document does not give presumption of conformity.	The present document does not give presumption of conformity.

1	**ER 1 seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Air traffic management systems and their constituents shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to ensure the seamless operation of the EATMN at all times and for all phases of flight. Seamless operation can be expressed, in particular, in terms of information sharing, including the relevant operational status information, common understanding of information, comparable processing performances and the associated procedures enabling common operational performances agreed for the whole or parts of the EATMN."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
1.4	Operated	Operation is only applicable at the system level.	Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 3.3 Compliance with ATC Procedures and Working Methods Clause 9.3.1 Service Requirements Op_Serv-29-Adaptation to local procedures Clause 7 Operational procedures ED-87B [1] Clause 2.5.1.2 Monitoring/Alerting Clause 3.2.2.1 Identification
1.5	Information sharing	n/a	Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 3.2.1 Presentation of alerts to ATCOs ED-87B [1] Clause 2.5.1.2 Monitoring/Alerting Clause 2.5.2 Human-Machine Interface Clause 3.2.2.6 Velocity Clause 3.3.1 Alert Situation

Table A.2

2	**ER 2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "The EATMN, its systems and their constituents shall support, on a coordinated basis, new agreed and validated concepts of operation that improve the quality, sustainability and effectiveness of air navigation services, in particular in terms of safety and capacity. The potential of new concepts, such as collaborative decision-making, increasing automation and alternative methods of delegation of separation responsibility, shall be examined taking due account of technological developments and of their safe implementation, following validation."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
2.1	Validated concepts of operation - safety	Operation is only applicable at the system level.	A-SMGCS Levels 1 & 2 Preliminary Safety Case [3] Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 6.3 Vehicle driver
2.2	Validated concepts of operation - capacity	Operation is only applicable at the system level.	Covered by EN 303 213-1 [5]
2.3	Validated concepts of operation - quality	Operation is only applicable at the system level.	Covered by EN 303 213-1 [5]

Table A.3

3	**ER 3 Safety** Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems and operations of the EATMN shall achieve agreed high levels of safety. Agreed safety management and reporting methodologies shall be established to achieve this. In respect of appropriate ground-based systems, or parts thereof, these high levels of safety shall be enhanced by safety nets which shall be subject to agreed common performance characteristics. A harmonized set of safety requirements for the design, implementation, maintenance and operation of systems and their constituents, both for normal and degraded modes of operation, shall be defined with a view to achieving the agreed safety levels, for all phases of flight and for the entire EATMN. Systems shall be designed, built, maintained and operated, using the appropriate and validated procedures, in such a way that the tasks assigned to the control staff are compatible with human capabilities, in both the normal and degraded modes of operation, and are consistent with required safety levels. Systems shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to be free from harmful interference in their normal operational environment."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
3.1	Design	n/a.	A-SMGCS Levels 1 & 2 Preliminary Safety Case [3] EN 303 213-1 [5]	The present document does not give presumption of conformity.
3.2	Implementation	n/a.	A-SMGCS Levels 1 & 2 Preliminary Safety Case [3] Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 9.3.1 Service Requirements Op_Serv-29-Adaptation to local procedures Clause 4. Runway safety net	The present document does not give presumption of conformity.
3.3	Maintenance	n/a.	The present document does not give presumption of conformity	n/a.
3.4	Operation	n/a.	A-SMGCS Levels 1 & 2 Preliminary Safety Case [3] Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 2.1 Objectives	The present document does not give presumption of conformity.
3.5	Human capabilities	n/a.	Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 3.2.1 Presentation of alerts to ATCOs ED-87B [1] Clause 2.5.2 Human Machine Interface	The present document does not give presumption of conformity.
3.6	Harmful interference	n/a.	The present document does not give presumption of conformity	n/a.

Table A.4

4	**ER 4 Civil-military coordination**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "The EATMN, its systems and their constituents shall support the progressive implementation of civil/military coordination, to the extent necessary for effective airspace and air traffic flow management, and the safe and efficient use of airspace by all users, through the application of the concept of the flexible use of airspace. To achieve these objectives, the EATMN, its systems and their constituents shall support the timely sharing of correct and consistent information covering all phases of flight, between civil and military parties. Account should be taken of national security requirements."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
4.1	Flexible use of airspace	The present document does not give presumption of conformity	The present document does not give presumption of conformity
4.2	Timely sharing	n/a	The present document does not give presumption of conformity
4.3	National security requirements	n/a	The present document does not give presumption of conformity

Table A.5

5	**ER 5 Environmental constraints**			
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems and operations of the EATMN shall take into account the need to minimize environmental impact in accordance with Community legislation."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
5.1	Minimize environmental impact - ATS	n/a.	The present document does not give presumption of conformity.	The present document does not give presumption of conformity.
5.2	Minimize environmental impact - materials	The present document does not give presumption of conformity.	The present document does not give presumption of conformity.	n/a.

Table A.6

6	**ER 6 Principles governing the logical architecture of systems**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems shall be designed and progressively integrated with the objective of achieving a coherent and increasingly harmonized, evolutionary and validated logical architecture within the EATMN."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
6.1	Designed and progressively integrated.	n/a.	Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 2.1 Objectives Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] Clause 3.5 Guidance Service to Vehicle Drivers (Optional)

Table A.7

7	**ER 7 Principles governing the construction of systems**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems shall be designed, built and maintained on the grounds of sound engineering principles, in particular those relating to modularity, enabling interchangeability of constituents, high availability, and redundancy and fault tolerance of critical constituents."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
7.1	Modularity, interchangeability.	n/a.	Covered by EN 303 213-1 [5] Operational Concept and Requirements for A-SMGCS Implementation Level 2 [2] clause 2.1 clause 3.5 ED-87B [1], clause 2.5.2
7.2	High availability, Redundancy and fault tolerance.	n/a.	Covered by EN 303 213-1 [5]

A.2 Interoperability Regulation Annex II Essential Requirements; Part B: Specific requirements

A.2.1 Systems and procedures for airspace management

Table A.8

1.1	**ER 1.1 Seamless operation**			
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Information relating to pre-tactical and tactical aspects of airspace availability shall be provided to all interested parties in a correct and timely way so as to ensure an efficient allocation and use of airspace by all airspace users. This should take into account national security requirements."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
1.1.1	Pre-tactical aspects of airspace availability	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
1.1.2	Tactical aspects of airspace availability	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
1.1.3	Correct and timely way	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
1.1.4	National security requirements	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)

A.2.2 Systems and procedures for air traffic flow management

Table A.9

2.1	**ER 2.1 Seamless operation**			
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems and procedures for air traffic flow management shall support the sharing of correct, coherent and relevant strategic, pre-tactical and tactical, as applicable, flight information covering all phases of flight and offer dialogue capabilities with a view to achieving optimized use of airspace."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
2.1.1	Strategic	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
2.1.2	Pre-tactical	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
2.1.3	Tactical	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)

A.2.3 Systems and procedures for air traffic services

A.2.3.1 Flight data processing systems

Table A.10

3.1.1	**ER 3.1.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Flight data processing systems shall be interoperable in terms of the timely sharing of correct and consistent information, and a common operational understanding of that information, in order to ensure a coherent and consistent planning process and resource-efficient tactical coordination throughout the EATMN during all phases of flight. In order to ensure safe, smooth and expeditious processing throughout the EATMN, flight data processing performances shall be equivalent and appropriate for a given environment (surface, terminal manoeuvring area (TMA), en-route), with known traffic characteristics and exploited under an agreed and validated operational concept, in particular in terms of accuracy and error tolerance of processing results."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.1.1.1	Timely sharing	n/a.	Not covered by EN 303 213 (parts 1 to 4)
3.1.1.2	Performance appropriate for environment	n/a.	Not covered by EN 303 213 (parts 1 to 4)
3.1.1.3	Accuracy and error tolerance	n/a.	Not covered by EN 303 213 (parts 1 to 4)

Table A.11

3.1.2	**ER 3.1.2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Flight data processing systems shall accommodate the progressive implementation of advanced, agreed and validated concepts of operation for all phases of flight, in particular as envisaged in the ATM MasterPlan. The characteristics of automation-intensive tools must be such as to enable coherent and efficient pre-tactical and tactical processing of flight information in parts of the EATMN. Airborne and ground systems and their constituents supporting new, agreed and validated concepts of operation shall be designed, built, maintained and operated, using appropriate and validated procedures, in such a way as to be interoperable in terms of timely sharing of correct and consistent information and a common understanding of the current and predicted operational situation."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.1.2.1	Airborne systems - design	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.2	Airborne systems - built	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.3	Airborne systems - maintained	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.4	Airborne systems - operated	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.5	Ground systems - design	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.6	Ground systems - built	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.7	Ground systems - maintained	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)
3.1.2.8	Ground systems - operated	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)

A.2.3.2 Surveillance data processing systems

Table A.12

3.2.1	**ER 3.2.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Surveillance data processing systems shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to provide the required performance and quality of service within a given environment (surface, TMA, en-route) with known traffic characteristics, in particular in terms of accuracy and reliability of computed results, correctness, integrity, availability, continuity and timeliness of information at the control position. Surveillance data processing systems shall accommodate the timely sharing of relevant, accurate, consistent and coherent information between them to ensure optimized operations through different parts of the EATMN."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.2.1.1	Designed	n/a.	ED-87B [1] Clause 3.3.2.2 Accuracy and Resolution
3.2.1.2	Built	n/a.	ED-87B [1] Clause 4.6.2 Probability of Detection Test Clause 4.6.3 Probability of False Detection Test Clause 4.6.4 Probability of Identification Test Clause 4.6.5 Probability of False Identification Test Clause 4.6.6 Reported Position Accuracy Test Clause 4.6.7 Reported Velocity Accuracy Test Clause 4.6.8 Target Report Update Rate Test Clause 4.6.9 Position Renewal Time-Out Period Test Clause 4.6.10 Identification Renewal Time-Out Period Test Clause 4.6.11 Track Continuity Test Clause 4.7 Monitoring/alerting element tests
3.2.1.3	Maintained	n/a.	The present document does not give presumption of conformity.
3.2.1.4	Operated	n/a.	The present document does not give presumption of conformity.

Table A.13

3.2.2	**ER 3.2.2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] [1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Surveillance data processing systems shall accommodate the progressive availability of new sources of surveillance information in such a way as to improve the overall quality of service, in particular as envisaged in the ATM MasterPlan."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.2.2.1	Availability of new sources	n/a.	Covered by EN 303 213-1 [5]

A.2.3.3 Human-machine interface systems

Table A.14

3.3.1	**ER 3.3.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Human-machine interfaces of ground air traffic management systems shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to offer to all control staff a progressively harmonized working environment, including functions and ergonomics, meeting the required performance for a given environment (surface, TMA, en-route), with known traffic characteristics."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.3.1.1	Designed	n/a.	ED-87B [1] Clause 2.5.2 Human-Machine Interface
3.3.1.2	Built	n/a.	ED-87B [1] Clause 4.7 Monitoring/alerting element tests
3.3.1.3	Maintained	n/a.	The present document does not give presumption of conformity.
3.3.1.4	Operated	n/a.	The present document does not give presumption of conformity.

Table A.15

3.3.2	**ER 3.3.2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Human-machine interface systems shall accommodate the progressive introduction of new, agreed and validated concepts of operation and increased automation, in such a way as to ensure that the tasks assigned to the control staff remain compatible with human capabilities, in both the normal and degraded modes of operation."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
3.3.2.1	Human capabilities	n/a.	ED-87B [1] Clause 2.5.2 Human Machine Interface

A.2.4 Communications systems and procedures for ground-to-ground, air-to-ground and air-to-air communications

Table A.16

4.1	**ER 4.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Communication systems shall be designed, built, maintained and operated using the appropriate and validated procedures, in such a way as to achieve the required performances within a given volume of airspace or for a specific application, in particular in terms of communication processing time, integrity, availability and continuity of function. The communications network within the EATMN shall be such as to meet the requirements of quality of service, coverage and redundancy."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
4.1.1	Designed	n/a.	Not covered by EN 303 213 (parts 1 to 4)
4.1.2	Built	n/a.	Not covered by EN 303 213 (parts 1 to 4)
4.1.3	Maintained	n/a.	Not covered by EN 303 213 (parts 1 to 4)
4.1.4	Operated	n/a.	Not covered by EN 303 213 (parts 1 to 4)
4.1.5	Quality of service, coverage, redundancy	n/a.	Not covered by EN 303 213 (parts 1 to 4)

Table A.17

4.2	**ER 4.2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Communication systems shall support the implementation of advanced, agreed and validated concepts of operation for all phases of flight, in particular as envisaged in the ATM MasterPlan."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
4.2.1	Support the implementation	n/a.	Not covered by EN 303 213 (parts 1 to 4)

A.2.5 Navigation systems and procedures

Table A.18

5.1	**ER 5.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Navigation systems shall be designed, built, maintained and operated using appropriate and validated procedures in such a way as to achieve the required horizontal and vertical navigation performance, in particular in terms of accuracy and functional capability, for a given environment (surface, TMA, en-route), with known traffic characteristics and exploited under an agreed and validated operational concept."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
5.1.1	Designed	n/a.	Not covered by EN 303 213 (parts 1 to 4)
5.1.2	Built	n/a.	Not covered by EN 303 213 (parts 1 to 4)
5.1.3	Maintained	n/a.	Not covered by EN 303 213 (parts 1 to 4)
5.1.4	Operated	n/a.	Not covered by EN 303 213 (parts 1 to 4)

A.2.6 Surveillance systems and procedures

Table A.19

6.1	**ER 6.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Surveillance systems shall be designed, built, maintained and operated using appropriate and validated procedures in such a way as to provide the required performance applicable in a given environment (surface, TMA, en-route) with known traffic characteristics and exploited under an agreed and validated operational concept, in particular in terms of accuracy, coverage, range and quality of service. The surveillance network within the EATMN shall be such as to meet the requirements of accuracy, timeliness, coverage and redundancy. The surveillance network shall enable surveillance data to be shared in order to enhance operations throughout the EATMN."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
6.1.1	Designed	n/a.	Not covered by EN 303 213 (parts 1 to 4)
6.1.2	Built	n/a.	Not covered by EN 303 213 (parts 1 to 4)
6.1.3	Maintained	n/a.	Not covered by EN 303 213 (parts 1 to 4)
6.1.4	Operated	n/a.	Not covered by EN 303 213 (parts 1 to 4)

A.2.7 Systems and procedures for aeronautical information services

Table A.20

7.1	**ER 7.1 Seamless operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Accurate, timely and consistent aeronautical information shall be provided progressively in an electronic form, based on a commonly agreed and standardized data set. Accurate and consistent aeronautical information, in particular concerning airborne and ground-based constituents or systems, shall be made available in a timely manner."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
7.1.1	Accurate, timely and consistent	n/a.	Not covered by EN 303 213 (parts 1 to 4)
7.1.2	Standardized data set	n/a.	Not covered by EN 303 213 (parts 1 to 4)

Table A.21

7.2	**ER 7.2 Support for new concepts of operation**		
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Increasingly accurate, complete and up-to-date aeronautical information shall be made available and used in a timely manner in order to support continuous improvement of the efficiency of airspace and airport use."		
	Keywords	**Evidence on constituent level**	**Evidence on system level**
7.2.1	Increasingly accurate, complete and up-to-date	n/a.	Not covered by EN 303 213 (parts 1 to 4)

A.2.8 Systems and procedures for the use of meteorological information

Table A.22

8.1	**ER 8.1 Seamless operation**			
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems and procedures for the use of meteorological information shall improve the consistency and timeliness of its provision and the quality of its presentation, using an agreed data set."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
8.1.1	Consistency and timeliness	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)

Table A.23

8.2	**ER 8.2 Support for new concepts of operation**			
	Regulation (EC) 552/2004 [i.1] as amended by Regulation (EC) 1070/2009 [i.5] requires that: "Systems and procedures for the use of meteorological information shall improve the promptness of its availability and the speed with which it may be used, in order to support continuous improvement of the efficiency of airspace and airport use."			
	Keywords	**Evidence on constituent level**	**Evidence on system level**	**Evidence at procedure level**
8.2.1	Promptness, speed	n/a.	Not covered by EN 303 213 (parts 1 to 4)	Not covered by EN 303 213 (parts 1 to 4)

Annex B (informative): The EN title in the official languages

Language	EN title
Bulgarian	Усъвършенствана система за ръководство наземно движение и управление (A-SMGCS). Част 2: Спецификация на Общността за прилагане на Регламент ЕС 552/2004 за оперативна съвместимост в Единно европейско небе за A-SMGCS, ниво 2, включващо външни интерфейси
Czech	Pokročilý naváděcí a řídicí systém pohybu po pojezdové ploše (A-SMGCS) - Část 2: Specifikace Společenství pro aplikaci podle předpisu EC 552/2004 o interoperabilitě v rámci Jednotného evropského nebe pro A-SMGCS úroveň 2 včetně vnějších rozhraní
Danish	Avanceret styrings og kontrol system af bevægelse på jordoverfladen (A-SMGCS)—Del 2: Fællesskabets specifikation for anvendelse under Den fælles europæiske luftrums interoperabilitets regulering EC 552/2004 for A-SMGCS niveau 2 inklusive eksterne grænseflader
Dutch	Geavanceerd begeleiding- en controlesysteem voor verplaatsingen over land (A-SMGCS); Deel 2: Gemeenschappelijke specificatie voor toepassing onder de enkele Europese luchtruim interoperabiliteitsbepaling EC 552/2004 voor A-SMGCS niveau 2 inclusief externe interfaces
English	Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 2: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 2 including external interfaces
Estonian	Lennuvälja maapealse liikluse juhtimise täiustatud süsteem (A-SMGCS); Osa 2: Ühenduse Spetsifikatsioon, rakendamiseks vastavalt Ühtse Euroopa Taeva (SES) Koostalitlusvõime Määrusele EU 552/2004 teise taseme (Level 2) A-SMGCS jaoks, mis hõlmab ka väliseid liideseid
Finnish	Kehittyneet kenttäalueen liikenteen ohjaus- ja valvontajärjestelmät (A-SMGCS); Osa 2: Yhteisön eritelmä, jota sovelletaan yhtenäisen eurooppalaisen ilmatilan toteuttamiseksi annetun yhteentoimivuusasetuksen EY 552/2004 nojalla A-SMGCS-järjestelmien tasoon 2 mukaan lukien ulkoiset rajapinnat
French	Système avancé de guidage et de commande des mouvements en surface (A-SMGCS)- Partie 2 : Spécification de la Communauté en vue de l'appllication du règlement EC 552/2004 sur l'interopérabilité pour le niveau 2 du A-SMGCS incluant les interfaces externes
German	Erweitertes Bodenverkehrsleit- und Kontrollsystem (A-SMGCS) – Teil 2: Gemeinschaftliche Spezifikation zur Anwendung gemäß SES-Interoperabilitätsverordnung EG 552/2004 für A-SMGCS Stufe 2 einschließlich externer Schnittstellen
Greek	Προηγμένο Σύστημα Καθοδήγησης και Ελέγχου Κίνησης Επιφανείας (A-SMGCS) – Μέρος 2: Κοινοτική Προδιαγραφή για εφαρμογή στο πλαίσιο του Κανονισμού Διαλειτουργικότητας Ενιαίου Ευρωπαϊκού Ουρανού ΕΚ 552/2004 για το A-SMGCS Επίπεδο 2 συμπεριλαμβανομένων των εξωτερικών διεπαφών
Hungarian	Felszíni mozgást ellenőrző és vezérlő továbbfejlesztett rendszer (A-SMGCS). 2. rész: Az egységes európai égbolt (Single European Sky) átjárhatóságát szabályozó EK 552/2004 rendelet alá tartozó, külső interfészeket is tartalmazó 2. szintű A-SMGCS alkalmazások közösségi előírása
Icelandic	Þróuð leiðsögu- og stjórnkerfi fyrir umferð á jörðu niðri (A-SMGCS); Hluti 2: Samræmdar tækniforsendur Evrópubandalagsins skv. Reglugerð EC 552/2004 um rekstrarsamhæfi í samevrópsku loftrrými fyrir annað stig A-SMGCS, þ.m.t. ytri skilfleti
Italian	Guida Avanzata ai Movimenti di Superficie e Sistema di Controllo (A-SMGCS); Parte 2: Specifica Comunitaria per il Livello 2 della A-SMGCS, inclusiva delle interfacce esterne, per applicazioni nell'ambito del Regolamento EC 552/2004 sulla Interoperabilità nel Cielo Unico Europeo
Latvian	Uzlabota kustības uz zemes vadības un kontroles sistēma (A-SMGCS); 2.daļa: Kopienas specifikācija pielietošanai 2. līmeņa A-SMGCS, ieskaitot ārējās saskarnes, saskaņā ar Vienotās Eiropas gaisa telpas savietojamības regulu EC 552/2004
Lithuanian	Patobulintoji antžeminio eismo valdymo ir kontrolės sistema (A-SMGCS). 2 dalis. Bendrijos specifikacija dėl bendro Europos dangaus srities sąveikos Reglamento EC 552/2004, taikoma 2-ojo lygio A-SMGCS sistemai, įskaitant išorinius sietuvus
Maltese	Sistema Avvanzata għall-Iggwidar u Kontroll ta' Moviment fis-Superfiċje (A-SMGCS); Parti 2: Speċifikazzjoni Komunitarja għal applikazzjoni taħt ir-Regolament Singolu Ewropew dwar Interoperabilità fl-użu tal-Ajru KE 552/2004 għal A-SMGCS Level 2 inklużi interfaces esterni
Norwegian	Avansert styrings- og kontrollsystem for bakketrafikk (A-SMGCS); Del 2: Fellesskapsspesifikasjon for samvirkingsevne i samsvar med Samvirkingsforordningen (EF) nr. 552/2004 for A-SMGCS nivå 2 inkludert eksterne grensesnitt
Polish	Zaawansowany system zarządzania i kontroli ruchu naziemnego na lotnisku (A-SMGCS) - Część 2: Specyfikacja Wspólnoty zapewniająca spełnienie wymagań interoperacyjności Jednolitej Europejskiej Przestrzeni Powietrznej, zawartych w Przepisie EC 552/2004 dla A-SMGCS Poziomu 2 łącznie z interfejsami zewnętrznymi
Portuguese	Sistema Avançado para Guiamento e Controlo de Movimento à Superfície (A-SMGCS); Parte 2: Especificações Comunitárias para aplicação de acordo com o Regulamento (CE) 552/2004 do céu único europeu relativo a A-SMGCS Nível 2, incluindo interfaces externos

Language	EN title
Romanian	Sistem avansat de comandă şi ghidare pentru deplasare pe suprafaţă (A-SMGCS). Partea 2: Specificaţie comunitară de aplicare conform regulamentului CE 552/2004 de interoperabilitate pe Cer Unic European pentru A-SMGCS de nivel 2, inclusiv interfeţele externe
Slovak	Zdokonalený systém navádzania a riadenia pohybu na prevádzkových plochách (A-SMGCS). Časť 2: Špecifikácia Spoločenstva vzťahujúca sa na aplikácie podľa nariadenia ES 552/2004 o interoperabilite jednotného európskeho vzdušného priestoru pre úroveň 2 A-SMGCS vrátane vonkajších rozhraní
Slovenian	Napredni sistem za vodenje in nadzor gibanja po zemlji (A-SMGCS) - 2. del: Specifikacija Skupnosti za uporabo po Uredbi ES 552/2004 o medobratovalnosti na enotnem evropskem nebu za A-SMGCS, 2. raven, vključno z zunanjimi vmesniki
Spanish	Sistema avanzado de control y guía del movimiento en superficie (A-SMGCS). Parte 2: Especificación comunitaria para aplicación bajo el Reglamento CE/552/2004, relativo a la interoperabilidad del cielo único europeo, para A-SMGCS nivel 2, incluyendo las interfaces externas
Swedish	Avancerat lednings- och styrsystem för markrörelser (A-SMGCS-2); Del 2: Europeisk Norm (EN) i anslutning till ”Single European Sky Interoperability Regulation” EC 552/2004 för A-SMGCS nivå 2, inklusive externa anpassningsenheter (interfaces)

Annex C (informative): Bibliography

- Directive 1999/5/EC of the European Parliament and of the Council of 9 March 1999 on radio equipment and telecommunications terminal equipment and the mutual recognition of their conformity.
- ETSI EN 303 213-5: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 5: Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for transmitters used in multilateration equipment".
- ETSI EN 303 213-6: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 6: Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for deployed surface movement radar sensors".
- ICAO Annex 14: "Aerodrome Design and Operations, volume 1".
- ICAO Annex 10: "Aeronautical communications".
- ICAO Document 9476: "Manual of Surface Movements and Guidance Control Systems (SMGCS)".
- Council Resolution of 7 May 1985 on a new approach to technical harmonization and standards, OJ C 136, 04.06.1985.
- ETSI EG 201 399: "Electromagnetic compatibility and Radio spectrum Matters (ERM); A guide to the production of candidate Harmonized Standards for application under the R&TTE Directive".
- ETSI TR 102 579: "Electromagnetic compatibility and Radio spectrum Matters (ERM); Report providing guidance for the production of Community Specifications for application under the Single European Sky Interoperability Regulation EC 552/2004".
- EUROCONTROL 07/01/11-06 (Edition 2.0, December 2006): "Functional Specification for A-SMGCS Implementation Level 1".
- EUROCONTROL 06/11/27-18 (V1.1, November 2006): "Human Factor Case for A-SMGCS".
- EUROCONTROL: "European Action Plan for the Prevention of Runway Incursions".

History

Document history				
V1.1.1	December 2009	Public Enquiry	PE 20100420:	2009-12-21 to 2010-04-20
V1.1.1	August 2010	Vote	V 20101015:	2010-08-16 to 2010-10-15
V1.1.1	October 2010	Publication		