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Electromagnetic compatibility and Radio spectrum Matters (ERM); Portable Very High Frequency (VHF) radiotelephone equipment for the maritime mobile service operating in the VHF bands with integrated handheld class D DSC; Part 1: Technical characteristics and methods of measurement

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# Foreword

This European Standard (EN) has been produced by ETSI Technical Committee Electromagnetic compatibility and Radio spectrum Matters (ERM).

The present document is part 1 of a multi-part deliverable covering the Electromagnetic compatibility and Radio spectrum Matters (ERM); Portable Very High Frequency (VHF) radiotelephone equipment for the maritime mobile service operating in the VHF bands with integrated handheld class D DSC, as identified below:

#### Part 1: "Technical characteristics and methods of measurement";

Part 2: "Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive";

Part 3: "Harmonized EN covering the essential requirements of article 3.3(e) of the R&TTE Directive".

National transposition dates		
Date of adoption of this EN:	10 November 2011	
Date of latest announcement of this EN (doa):	29 February 2012	
Date of latest publication of new National Standard or endorsement of this EN (dop/e):	31 August 2012	
Date of withdrawal of any conflicting National Standard (dow):	31 August 2012	

# 1 Scope

The present document states the minimum technical characteristics and methods of measurement required for portable Very High Frequency (VHF) radiotelephones with integrated handheld class D DSC operating in certain frequency bands allocated to the maritime mobile service using either 25 kHz channels or 25 KHz and 12,5 kHz channels.

The present document also specifies technical characteristics, methods of measurement and required test results.

# 2 References

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at <a href="http://docbox.etsi.org/Reference">http://docbox.etsi.org/Reference</a>.

NOTE: While any hyperlinks included in this clause were valid at the time of publication ETSI cannot guarantee their long term validity.

### 2.1 Normative references

The following referenced documents are necessary for the application of the present document.

[1]	ITU Radio Regulations (2008), appendix 18: "Table of transmitting frequencies in the VHF maritime mobile band".
[2]	ITU-T Recommendation E.161 (2001): "Arrangement of digits, letters and symbols on telephones and other devices that can be used for gaining access to a telephone network".
[3]	ITU-R Recommendation M.493-13 (2009): "Digital selective-calling system for use in the maritime mobile service".
[4]	ITU-R Recommendation M.541-9 (2004): "Operational procedures for the use of digital selective- calling equipment in the maritime mobile service".
[5]	ETSI EN 300 225: "Electromagnetic compatibility and Radio spectrum Matters (ERM); Technical characteristics and methods of measurement for survival craft portable VHF radiotelephone apparatus".
[6]	ITU-T Recommendation O.41 (1994): "Psophometer for use on telephone-type circuits".
[7]	ITU-R Recommendation SM.332-4: "Selectivity of receivers".
[8]	ETSI TR 100 028-1 (V1.4.1): "Electromagnetic compatibility and Radio spectrum Matters (ERM); Uncertainties in the measurement of mobile radio equipment characteristics; Part 1".
[9]	ITU-R Recommendation M.1084-4 (2001): "Interim solutions for improved efficiency in the use of the band 156-174 MHz by stations in the maritime mobile service".
[10]	ANSI C63.5 (2006): "American National Standard for Calibration of Antennas Used for Radiated Emission Measurements in Electro Magnetic Interference".
[11]	IEC 60489-3 (Second edition (1988) appendix F): "Methods of measurement for radio equipment used in the mobile services; Part 3: Receivers for A3E or F3E emissions".
[12]	ETSI TR 102 273 (V1.2.1): "Electromagnetic compatibility and Radio spectrum Matters (ERM); Improvement on Radiated Methods of Measurement (using test site) and evaluation of the

corresponding measurement uncertainties".

 [13] ETSI EN 300 338-5: "Electromagnetic compatibility and Radio spectrum Matters (ERM); Technical characteristics and methods of measurement for equipment for generation, transmission and reception of Digital Selective Calling (DSC) in the maritime MF, MF/HF and/or VHF mobile service; Part 5: Handheld VHF Class D DSC".

# 2.2 Informative references

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

Not applicable.

# 3 Definitions, symbols and abbreviations

### 3.1 Definitions

For the purposes of the present document, the following terms and definitions apply:

block: to inhibit a function by making it inaccessible from the user interface

detachable antenna: antenna fixed to the equipment by means of an antenna connector and detachable by the user

G3E: phase-modulation (frequency modulation with a pre-emphasis of 6 dB/octave) for speech

integral antenna: antenna that is permanently fixed to the equipment and not detachable by the user

modulation index: ratio between the frequency deviation and the modulation frequency

performance check: check of:

- the transmitter carrier power and frequency; and
- receiver sensitivity

# 3.2 Symbols

For the purposes of the present document, the following symbols apply:

dBA Relative to  $2 \times 10^{-5}$  Pa

### 3.3 Abbreviations

For the purposes of the present document, the following abbreviations apply:

ad	amplitude difference
CSP	Channel SPacing
DSC	Digital Selective Calling
emf	electromotive force
EUT	Equipment Under Test
fd	frequency difference
IF	Intermediate Frequency
OATS	Open Area Test Site
rms	root mean square
SINAD	(Signal + Noise + Distortion)/(Noise + Distortion)
VHF	Very High Frequency

# 4 General and operational requirements

# 4.1 Construction

The manufacturer shall declare that compliance to the requirements of clause 4 is achieved and shall provide relevant documentation.

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The mechanical and electrical construction and finish of the equipment shall conform in all respects to good engineering practice, and the equipment shall be suitable for use on board ships.

All controls shall be of sufficient size to enable the usual control functions to be easily performed and the number of controls should be the minimum necessary for simple and satisfactory operation.

All parts of the equipment to be checked during inspection or maintenance operations shall be readily accessible. The components shall be readily identifiable.

Technical documentation shall be supplied with the equipment.

The VHF maritime mobile service uses both single-frequency and two-frequency channels. For two-frequency channels there shall be a separation of 4,6 MHz between the transmitting frequency and the receiving frequency (see Radio Regulations appendix 18 [1]).

The equipment shall incorporate an integrated GPS or GNSS receiver.

The equipment shall have a minimum protection level of IP54.

The equipment shall be capable of operating on single frequency and two-frequency channels with manual control (simplex).

The equipment shall be of a colour which distinguishes it from the portable VHF equipment specified in EN 300 225 [5].

The equipment shall be able to operate on all channels defined in Radio Regulations, appendix 18 [1], noting in particular footnotes m) and e).

Additional VHF channels for maritime use outside those defined by Appendix 18 to the Radio Regulations may also be provided where permitted by relevant administrations. These channels shall be clearly identified for use as relating to the relevant administration(s) and accessed through a positive action(s) for enabling use of these channel(s) but means shall be provided to block any or all of these additional channels if required by the relevant administration(s).

If 12,5 kHz channels are implemented in the equipment it shall be in accordance with ITU-R Recommendation M.1084-4 [9].

The equipment shall be so designed that use of channel 70 for purposes other than DSC is prevented (see ITU-R Recommendations M.493-13 [3] and M.541-9 [4]), and that use of channels AIS1 and AIS2 for purposes other than AIS is prevented.

Scan or multiple watch may be provided but means shall be provided to block or unblock these functions.

If the equipment is fitted with an auxiliary antenna connector, simultaneous connection of both the auxiliary antenna and the normal antenna shall be prevented.

It shall not be possible to transmit while any frequency synthesizer used within the transmitter is out of lock.

It shall not be possible to transmit during channel switching operations.

### 4.2 Controls and indicators

The equipment shall have a channel selector and shall indicate the designator, as shown in Radio Regulations, appendix 18 [1], of the channel at which the equipment is set. The channel designator shall be legible irrespective of the external lighting conditions.

Channel 16 shall be distinctively marked. Selection of channel 16, shall be preferably by readily accessible means (e.g. a distinctively marked key). Selection of channel 16 by any means shall automatically set the transmitter output power to maximum. This power level may subsequently be reduced by manual user control if required.

Where an input panel on the equipment for entering the digits 0 to 9 is provided, this shall conform to ITU-T Recommendation E.161 [2].

The equipment shall have the following additional controls and indicators:

- on/off switch for the equipment with a visual indication that the equipment is in operation;
- a manual, non-locking push to talk switch to operate the transmitter with a visual indication that the transmitter is activated and facilities to limit the transmission time to a maximum of 5 minutes. A short audible alarm and a visual indication may be provided to show when the transmission will be automatically terminated within the next 10 s. It shall be possible to reoperate the push to talk switch and reactivate the transmitter after a 10 s period;
- a switch for reducing transmitter output power to no more than 1 W where the RF output power is more than 1 W;
- an audio frequency power volume control;
- a squelch control;
- a visual indication that the transmitter is activated.

The equipment shall also meet the following requirements:

- the user shall not have access to any control which, if wrongly set, might impair the technical characteristics of the equipment.

### 4.3 Microphone and loudspeaker

The equipment shall be fitted with an integral microphone and an integral loudspeaker.

During transmission the receiver output shall be muted.

# 4.4 Safety precautions

Measures shall be taken to protect the equipment against the effects of overcurrent or overvoltage.

Measures shall be taken to prevent damage to the equipment that might arise from an accidental reversal of polarity of the electrical power source.

No damage to the equipment shall occur when the antenna terminals are placed on open circuit or short circuit while transmitting for a period of at least 5 minutes in each case.

In order to provide protection against damage due to the build up of static voltages at the antenna terminals, there shall be a dc path from the antenna terminals to chassis not exceeding 100 k $\Omega$ .

The information in any volatile memory device shall be protected from interruptions in the power supply of up to 60 s duration.

# 4.5 Labelling

All controls, instruments, indicators and terminals shall be clearly labelled.

Details of any external power supply from which the equipment is intended to operate shall be clearly indicated on the equipment.

The equipment shall be clearly and indelibly marked on the exterior with the identification of the manufacturer, type designation of the equipment, the serial number of the unit.

The compass safe distance shall be stated on the equipment.

# 5 Technical requirements

### 5.1 Switching time

The channel switching arrangement shall be such that the time necessary to change over from using one of the channels to using any other channel does not exceed 5 s.

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The time necessary to change over from transmission to reception or vice versa, shall not exceed 0,3 s.

# 5.2 Class of emission and modulation characteristics

The equipment shall use phase modulation, G3E (frequency modulation with a pre-emphasis of 6 dB/octave) for speech and G2B for DSC signalling.

The equipment shall be designed to operate satisfactorily with channel separations of either 25 kHz or 12,5 kHz and 25 kHz.

### 5.3 Battery capacity

The equipment shall have a minimum operating time of 4 hours with a 80, 10, 10 duty cycle (80 % Standby, 10 % Tx and 10 % Rx) at normal temperature (clause 6.10.1).

The minimum operating time shall be met when:

- the battery is fully charged; or
- when new dry cells are installed (when appropriate).

# 5.4 DSC functionality

The equipment shall comply with EN 300 338-5 [13] for all aspects of DSC functionality.

# 6 General conditions of measurement

### 6.1 Arrangements for RF connections to the equipment

### 6.1.1 RF connections to integral antenna equipment

For equipment without an antenna connector, the manufacturer shall prepare the equipment with a temporary 50  $\Omega$  connector to be used as the RF input/output port.

### 6.1.2 RF connection to equipment with a detachable antenna

Equipment having an antenna connector shall be tested using the antenna connector as the RF input/output port.

In the case where equipment has more than one antenna connector, the connector normally used to connect the portable antenna to the equipment shall be used.

# 6.2 Arrangements for test signals applied to the receiver input

Test signal sources shall be connected to the receiver input in such a way that the impedance presented to the receiver input is 50  $\Omega$ , irrespective of whether one or more test signals are applied to the receiver simultaneously.

The levels of the test signals shall be expressed in terms of the emf at the terminals to be connected to the receiver.

The nominal frequency of the receiver is the carrier frequency of the selected channel.

DSC test signals (clause 9.14) shall be DSC calls in accordance with ITU-R Recommendation M.493-13 [3] with a signal level of +6 dB $\mu$ V (emf). The standard test signal for a VHF DSC decoder shall be a phase-modulated signal at VHF channel 70 with modulation index = 2. The modulating signal shall have a nominal frequency of 1 700 Hz and a frequency shift of ±400 Hz with a modulation rate of 1 200 baud.

# 6.3 Squelch

Unless otherwise specified, the receiver squelch facility shall be made inoperative for the duration of the conformance tests.

### 6.4 Normal test modulation

For normal test modulation, the modulation frequency shall be:

- 25 kHz channels: 1 kHz and the frequency deviation shall be ±3 kHz.
- 12,5 kHz channels: 1 kHz and the frequency deviation shall be  $\pm 1,5$  kHz.

For DSC conformance testing and maintenance purposes, the equipment shall have facilities not accessible to the operator to generate a continuous B or Y signal and dot pattern.

Additionally for conformance testing, the VHF equipment shall have facilities not accessible to the operator for generating an unmodulated carrier.

# 6.5 Artificial antenna

When tests are carried out with an artificial antenna, this shall be a non-reactive, non-radiating 50  $\Omega$  load.

# 6.6 Arrangements for test signals applied to the transmitter input

For the purpose of the present document, the audio frequency modulating signal applied to the transmitter shall be produced by a signal generator applied to the connection terminals replacing the microphone transducer.

# 6.7 Test channels

Conformance tests for 25 kHz channel operation shall be made on channel 16.

Conformance tests for 12,5 kHz channel operation shall be made on channel 276.

Conformance tests for DSC shall be made on channel 70.

# 6.8 Measurement uncertainty and interpretation of the measured results

### 6.8.1 Measurement uncertainty

Table 1: Absolute measuremen	t uncertainties:	maximum	values
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Parameter	Maximum uncertainty
RF frequency	±1 x 10 <sup>-7</sup>
RF power	±0,75 dB
Maximum frequency deviation: - within 300 Hz to 6 kHz of modulation frequency - within 6 kHz to 25 kHz of modulation frequency	±5 % ±3 dB
Deviation limitation	±5 %
Adjacent channel power	±5 dB
Conducted spurious emission of transmitter	±4 dB
Audio output power	±0,5 dB
Amplitude characteristics of receiver limiter	±1,5 dB
Sensitivity at 20 dB SINAD	±3 dB
Conducted emission of receiver	±3 dB
Two-signal measurement	±4 dB
Three-signal measurement	±3 dB
Radiated emission of transmitter	±6 dB
Radiated emission of receiver	±6 dB
Transmitter transient time	±20 %
Transmitter transient frequency	±250 Hz
Receiver desensitization (duplex operation)	±0,5 dB

### 6.8.2 Interpretation of the measurement results

The interpretation of the results recorded in a test report for the measurements described in the present document shall be as follows:

- the measured value related to the corresponding limit will be used to decide whether an equipment meets the requirements of the present document;
- the value of the measurement uncertainty for the measurement of each parameter shall be included in the test report;
- the recorded value of the measurement uncertainty shall be, for each measurement, equal to or lower than the figures in table 1.

For the test methods, according to the present document, the measurement uncertainty figures shall be calculated in accordance with TR 100 028-1 [8] and shall correspond to an expansion factor (coverage factor) k = 1,96 or k = 2 (which provide confidence levels of respectively 95 % and 95,45 % in the case where the distributions characterizing the actual measurement uncertainties are normal (Gaussian)).

Table 1 is based on such expansion factors.

# 6.9 Test conditions, power sources and ambient temperatures

### 6.9.1 Normal and extreme test conditions

Conformance tests shall be performed under normal test conditions and also, where stated, under extreme test conditions (clauses 6.11.1 and 6.11.2 applied simultaneously).

#### 6.9.2 Test power source

During conformance testing, the equipment shall be supplied from a test power source capable of producing normal and extreme test voltages as specified in clauses 6.10.2 and 6.11.2.

The internal impedance of the test power source shall be low enough for its effect on the test results to be negligible. For the purpose of testing the power source voltage shall be measured at the input terminals of the equipment.

During testing, the power source voltages shall be maintained within a tolerance of  $\pm 3$  % relative to the voltage level at the beginning of each test.

### 6.10 Normal test conditions

#### 6.10.1 Normal temperature and humidity

The normal temperature and humidity conditions for tests shall be a combination of temperature and humidity within the following ranges:

- temperature:  $+15 \degree C$  to  $+35 \degree C$ ;
- relative humidity: 20 % to 75 %.

When the relative humidity is lower than 20 %, it shall be stated in the test report.

#### 6.10.2 Normal power sources

#### 6.10.2.1 Battery power source

Where the equipment is designed to operate from a battery, the normal test voltage shall be the nominal voltage of the battery as declared by the manufacturer.

#### 6.10.2.2 Other power sources

For operation from other power sources the normal test voltage shall be that declared by the manufacturer.

### 6.11 Extreme test conditions

Unless otherwise stated the extreme tests conditions means that the Equipment Under Test (EUT) shall be tested at the upper temperature and at the upper limit of the supply voltage applied simultaneously, and at the low temperature and the lower limit of the supply voltage applied simultaneously.

#### 6.11.1 Extreme temperatures

For tests at extreme temperatures, measurements shall be made in accordance with clause 6.12, at a lower temperature of -15  $^{\circ}$ C and an upper temperature of +55  $^{\circ}$ C.

#### 6.11.2 Extreme values of test power sources

#### 6.11.2.1 Battery power source

The upper extreme test voltage shall be the terminal voltage of the battery (fresh primary battery or fully charged secondary battery) when loaded by the equipment at normal temperature in the receive condition with the squelch operated to mute the audio.

The lower extreme test voltage shall be 0,85 times the value determined above.

Where equipment can be powered by batteries of differing terminal voltage then the upper extreme test voltage shall be determined using the highest terminal voltage battery and the lower extreme test voltage shall be 0,85 times the upper extreme of the lowest terminal voltage battery.

#### 6.11.2.2 Other power sources

For operation from other power sources the extreme test voltages shall be that declared by the equipment manufacturer.

# 6.12 Procedure for tests at extreme temperatures

The equipment shall be switched off during the temperature stabilizing periods.

Before conducting tests at the upper temperature, the equipment shall be placed in the test chamber and left until thermal equilibrium is reached. The equipment shall then be switched on in the high power transmit condition at the normal voltage until the transmit timeout timer is activated and the equipment is returned to standby mode. The equipment shall then meet the relevant clauses of the present document.

For tests at the lower temperature, the equipment shall be left in the test chamber until thermal equilibrium is reached and shall then be switched to the standby or receive position for one minute. The equipment shall then meet the relevant clauses of the present document.

# 7 Environmental tests

### 7.1 Procedure

Environmental tests shall be carried out before testing the same equipment to the other requirements of the present document. Unless otherwise stated, the equipment shall be connected to an electrical power source during the periods for which it is specified that electrical tests shall be carried out. These tests shall be performed using the normal test voltage.

# 7.2 Performance check

A performance check shall be a check of transmitter frequency error, clause 8.1, transmitter carrier power, clause 8.2 and maximum usable sensitivity, clause 9.3. These performance checks shall only be performed under normal test conditions.

# 7.3 Drop test

### 7.3.1 Definition

This test simulates the effects of a free fall of the equipment onto the deck of a ship resulting from mishandling.

### 7.3.2 Method of measurement

The test shall consist of a series of 6 drops, one on each surface of the equipment.

The test shall be carried out under normal temperature and humidity.

The test surface shall consist of a piece of solid hard wood with a thickness of at least 150 mm and a mass of 30 kg or more.

The height of the lowest part of the equipment relative to the test surface at the moment of release shall be  $(1\ 000 \pm 10)$  mm.

The equipment shall be subjected to this test configured for use as in operational circumstances.

At the end of the test the equipment shall be subjected to a performance check and shall then be examined for external indications of damage. The findings shall be noted in the test report.

### 7.3.3 Requirement

The equipment shall meet the requirements of the performance check.

There shall be no harmful deterioration of the equipment visible.

The distress alert function shall not be activated.

The protection of the distress alert button shall function as required after the test.

# 7.4 Temperature tests

### 7.4.1 Definition

The immunity against the effects of temperature is the ability of the equipment to maintain the specified mechanical and electrical performance after the following tests has been carried out.

### 7.4.2 Dry heat

#### 7.4.2.1 Definition

This test determines the ability of equipment to be operated at high ambient temperatures and to operate through temperature changes.

#### 7.4.2.2 Method of measurement

The EUT shall be placed in a chamber at normal room temperature and relative humidity. The EUT and, if appropriate, any climatic control devices with which it is provided shall then be switched on. The temperature shall then be raised to and maintained at  $(+55 \pm 3)$  °C.

At the end of a soak period of 10 hours to 16 hours at  $(+55 \pm 3)$  °C, the EUT shall be subjected to the performance check. The temperature of the chamber shall be maintained at  $(+55 \pm 3)$  °C during the whole performance check period. At the end of the test, the EUT shall be returned to normal environmental conditions or to those required at the start of the next test. The maximum rate of raising or reducing the temperature of the chamber in which the equipment is being tested shall be 1 °C/minute.

#### 7.4.2.3 Requirement

The equipment shall meet the requirements of the performance check.

### 7.4.3 Damp heat

#### 7.4.3.1 Definition

This test determines the ability of equipment to be operated under conditions of high humidity.

#### 7.4.3.2 Method of measurement

The EUT shall be placed in a chamber at normal room temperature and relative humidity. The temperature shall then be raised to  $(+40 \pm 2)$  °C, and the relative humidity raised to  $(93 \pm 3)$  % over a period of  $(3 \pm 0,5)$  hour. These conditions shall be maintained for a period of 10 hours to 16 hours. Any climatic control devices provided in the EUT may be switched on at the conclusion of this period. The EUT shall be switched on 30 minutes later, or after such period as agreed by the manufacturer, and shall be kept operational for at least 2 hours during which period the EUT shall be subjected to the performance check once. The temperature and relative humidity of the chamber shall be maintained as specified during the whole test period. At the end of the test period and with the EUT still in the chamber, the chamber shall be brought to room temperature in not less than 1 hour. At the end of the test the EUT shall be returned to normal environmental conditions or to those required at the start of the next test. The maximum rate of raising or reducing the temperature of the chamber in which the equipment is being tested shall be 1 °C/minute.

#### 7.4.3.3 Requirement

The equipment shall meet the requirements of the performance check.

#### 7.4.4 Low temperature cycle

#### 7.4.4.1 Definition

These tests determine the ability of equipment to be operated at low temperatures. They also allow equipment to demonstrate an ability to start up at low ambient temperatures.

#### 7.4.4.2 Method of measurement

The EUT shall be placed in a chamber at normal room temperature and relative humidity. The temperature shall then be reduced to and maintained at  $(-15 \pm 3)$  °C, for a period of 10 hours to 16 hours. Any climatic control devices provided in the EUT may be switched on at the conclusion of this period. The EUT shall be switched on 30 minutes later, and shall be kept operational for at least 2 hours during which period the EUT shall be subjected to the performance check once. The temperature of the chamber shall be maintained at  $(-15 \pm 3)$  °C during the whole test period. At the end of the test the EUT shall be returned to normal environmental conditions or to those required at the start of the next test. The maximum rate of raising or reducing the temperature of the chamber in which the equipment is being tested shall be 1 °C/minute.

#### 7.4.4.3 Requirement

The equipment shall meet the requirements of the performance check.

# 8 Transmitter

All tests on the transmitter shall be carried out with the output power switch set at its maximum except where otherwise stated.

### 8.1 Frequency error

### 8.1.1 Definition

The frequency error is the difference between the measured carrier frequency and its nominal value.

### 8.1.2 Method of measurement

The carrier frequency shall be measured in the absence of modulation, with the transmitter connected to an artificial antenna (clause 6.5). Measurements shall be made under normal test conditions (clause 6.10) and under extreme test conditions (clause 6.11).

This test shall be carried out with the output power switch being set at both maximum and minimum.

### 8.1.3 Limits

The frequency error shall be within  $\pm 1,5$  kHz.

# 8.2 Carrier power

### 8.2.1 Definitions

The carrier power is the mean power delivered to the artificial antenna during one radio frequency cycle in the absence of modulation.

The rated output power is the carrier power declared by the manufacturer.

#### 8.2.2 Method of measurement

The transmitter shall be connected to an artificial antenna (clause 6.5) and the power delivered to this artificial antenna shall be measured. The measurements shall be made under normal test conditions (clause 6.10) and also under extreme test conditions (clause 6.11) on the highest frequency channel, the lowest frequency channel and on channel 16.

#### 8.2.3 Limits, Normal and extreme test conditions

The carrier power on the appendix 18 channels, Radio Regulations, appendix 18 [1], with the output power switch (clause 4.2) set at maximum, shall be between 3 W and 6 W.

With the output power switch at minimum, the carrier power shall remain between 0,1 W and 1 W.

### 8.3 Frequency deviation

### 8.3.1 Definition

For the purpose of the present document, the frequency deviation is the difference between the instantaneous frequency of the modulated radio frequency signal and the carrier frequency.

### 8.3.2 Maximum permissible frequency deviation

#### 8.3.2.1 Method of measurement

The frequency deviation shall be measured at the output with the transmitter connected to an artificial antenna (clause 6.5), by means of a deviation meter capable of measuring the maximum deviation, including that due to any harmonics and intermodulation products which may be generated in the transmitter.

The modulation frequency shall be varied between 300 Hz and 3 kHz. The level of this test signal shall be 20 dB above the level which produces normal test modulation (clause 6.4). This test shall be repeated with the output power switch set at maximum and minimum.

#### 8.3.2.2 Limits

The maximum permissible frequency deviation shall be:

- 25 kHz channels:  $\pm$ 5 kHz.
- 12,5 kHz channels:  $\pm 2,5$  kHz.

### 8.3.3 Reduction of frequency deviation at modulation frequencies above 3 kHz

#### 8.3.3.1 Method of measurement

The transmitter shall be operated under normal test conditions (clause 6.10) connected to a load as specified in clause 6.5. The transmitter shall be modulated by the normal test modulation (clause 6.4). With the input level of the modulation signal being kept constant, the modulation frequency shall be varied between 3 kHz (see note) and a frequency equal to the channel separation for which the equipment is intended and the frequency deviation shall be measured.

NOTE: 2,55 kHz for transmitters intended for 12,5 kHz channel separation.

#### 8.3.3.2 Limits

The frequency deviation at modulation frequencies between 3,0 kHz (for equipment operating with 25 kHz channel separations) or 2,55 kHz (for equipment operating with 12,5 kHz channel separation) and 6,0 kHz shall not exceed the frequency deviation at a modulation frequency of 3,0 kHz / 2,55 kHz. At 6,0 kHz the deviation shall be not more than 30,0 % of the maximum permissible frequency deviation.

The frequency deviation at modulation frequencies between 6,0 kHz and a frequency equal to the channel separation for which the equipment is intended shall not exceed that given by a linear representation of the frequency deviation (dB) relative to the modulation frequency, starting at the 6,0 kHz limit and having a slope of -14,0 dB per octave. These limits are illustrated in figure 1.

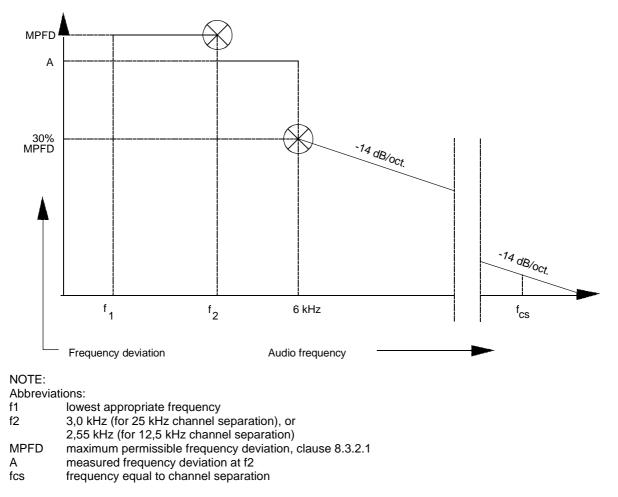


Figure 1: Frequency deviation

# 8.4 Sensitivity of the modulator, including microphone

### 8.4.1 Definition

This characteristic expresses the capability of the transmitter to produce sufficient modulation when an audio frequency signal corresponding to the normal mean speech level is applied to the microphone.

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### 8.4.2 Method of measurement

A 25 kHz channel shall be selected and the transmitter activated. An acoustic signal with a frequency of 1 kHz and sound level of 94 dBA shall be applied to the microphone. The resulting deviation shall be measured.

### 8.4.3 Limits

The resulting frequency deviation shall be between  $\pm 1,5$  kHz and  $\pm 3$  kHz.

### 8.5 Audio frequency response

### 8.5.1 Definition

The audio frequency response is the frequency deviation of the transmitter as a function of the modulating frequency.

### 8.5.2 Method of measurement

A modulating signal at a frequency of 1 kHz shall be applied to the transmitter and the deviation shall be measured at the output. The audio input level shall be adjusted so that the frequency deviation is  $\pm 1$  kHz. This is the reference point in figure 2 (1 kHz corresponds to 0 dB).

The modulation frequency shall then be varied between 300 Hz and 3 kHz (see note), with the level of the audio frequency signal being kept constant and equal to the value specified above.

The test shall be carried out on one channel only (see clause 6.6).

NOTE: 2,55 kHz for transmitters intended for 12,5 kHz channel separation.

The test shall be carried out on one channel only (see clause 6.7).

### 8.5.3 Limit

The audio frequency response shall be within +1 dB and -3 dB of a 6 dB/octave line passing through the reference point (see figure 2). The upper limit frequency shall be 2,55 kHz for 12,5 kHz channels.

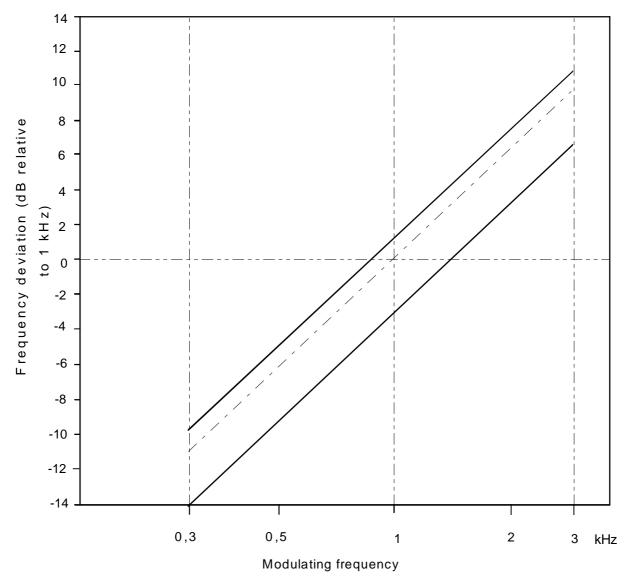


Figure 2: Audio frequency response

# 8.6 Audio frequency harmonic distortion of the emission

### 8.6.1 Definition

The harmonic distortion of the emission modulated by an audio frequency signal is defined as the ratio, expressed as a percentage, of the root mean square (rms) voltage of all the harmonic components of the fundamental modulation frequency to the total rms voltage of the modulation signal after linear demodulation.

### 8.6.2 Method of measurement

The RF signal produced by the transmitter shall be applied via an appropriate coupling device to a linear demodulator with a de-emphasis network of 6 dB per octave. This test shall be carried out on a 25 kHz channel with the output power switch at both maximum and minimum.

#### 8.6.2.1 Normal test conditions

Under normal test conditions (clause 6.10) the RF signal shall be modulated successively at frequencies of 300 Hz, 500 Hz and 1 kHz with a constant modulation index of 3.

The distortion of the audio frequency signal shall be measured at all the frequencies specified above.

#### 8.6.2.2 Extreme test conditions

Under extreme test conditions (clauses 6.11.1 and 6.11.2 applied simultaneously), the measurements shall be carried out at 1 kHz with a frequency deviation of  $\pm$ 3 kHz.

#### 8.6.3 Limits

The harmonic distortion shall not exceed 10 %.

### 8.7 Adjacent channel power

#### 8.7.1 Definition

The adjacent channel power is that part of the total power output of a transmitter under defined conditions of modulation, which falls within a specified passband centred on the nominal frequency of either of the adjacent channels. This power is the sum of the mean power produced by the modulation, hum and noise of the transmitter.

### 8.7.2 Method of measurement

The test shall be made on the lowest frequency channel, the highest frequency channel and on channel 16.

The adjacent channel power can be measured with a power measuring receiver which conforms to annex A (referred to in this clause and annex A as the "receiver") see also ITU-R Recommendation SM.332-4 [7]:

- a) The transmitter shall be operated at the carrier power determined in clause 8.2 under normal test conditions. The output of the transmitter shall be linked to the input of the "receiver" by a connecting device such that the impedance presented to the transmitter is 50  $\Omega$  and the level at the "receiver" input is appropriate.
- b) With the transmitter unmodulated, the tuning of the "receiver" shall be adjusted so that a maximum response is obtained. This is the 0 dB response point. The "receiver" attenuator setting and the reading of the meter shall be recorded.

The measurement may be made with the transmitter modulated with normal test modulation, in which case this fact shall be recorded with the test results.

- c) The tuning of the "receiver" shall be adjusted away from the carrier so that the "receiver" -6 dB response nearest to the transmitter carrier frequency is located at a displacement from the nominal carrier frequency of 17 kHz for 25 kHz channels or 8,25 kHz for 12,5 kHz channels.
- d) The transmitter shall be modulated with 1,25 kHz at a level which is 20 dB higher than that required to produce  $\pm 3$  kHz deviation for 25 kHz channels or  $\pm 1,5$  kHz deviation for 12,5 kHz channels.
- e) The "receiver" variable attenuator shall be adjusted to obtain the same meter reading as in step b) or a known relation to it.
- f) The ratio of adjacent channel power to carrier power is the difference between the attenuator settings in steps b) and e), corrected for any differences in the reading of the meter.
- g) The measurement shall be repeated with the "receiver" tuned to the other side of the carrier.

#### 8.7.3 Limits

The adjacent channel power shall not exceed a value of:

- 25 kHz channel: 70 dB below the carrier power of the transmitter without any need to be below  $0,2 \mu W$ .
- 12,5 kHz channel: 60 dB below the carrier power of the transmitter without any need to be below  $0,2 \mu W$ .

# 8.8 Conducted spurious emissions conveyed to the antenna

#### 8.8.1 Definition

Conducted spurious emissions are emissions on a frequency or frequencies which are outside the necessary bandwidth and the level of which may be reduced without affecting the corresponding transmission of information. Spurious emissions include harmonic emissions, parasitic emissions, intermodulation products and frequency conversion products, but exclude out of band emissions.

### 8.8.2 Method of measurement

Conducted spurious emissions shall be measured with the unmodulated transmitter connected to the artificial antenna (clause 6.5).

The measurements shall be made over a range from 9 kHz to 2 GHz, excluding the channel on which the transmitter is operating and its adjacent channels.

The measurements for each spurious emission shall be made using a tuned radio measuring instrument or a spectrum analyser.

### 8.8.3 Limit

The power of any conducted spurious emission on any discrete frequency shall not exceed 0,25  $\mu$ W.

# 8.9 Cabinet radiation and conducted spurious emissions other than those conveyed to the antenna

#### 8.9.1 Definitions

Cabinet radiation consists of emissions at frequencies, other than those of the carrier and the sideband components resulting from the wanted modulation process, which are radiated by the equipment cabinet and structures.

Conducted spurious emissions other than those conveyed to the antenna are emissions at frequencies, other than those of the carrier and the sideband components resulting from the wanted modulation process, which are produced by conduction in the wiring and accessories used with the equipment.

Integral antenna equipment shall be tested with the normal antenna fitted and the carrier frequency emission shall be filtered as described in the method of measurement.

### 8.9.2 Method of measurement

On a test site, selected from annex B, the equipment shall be placed at the specified height on a non-conducting support and in a position which is closest to normal use as declared by the manufacturer.

The transmitter antenna connector shall be connected to an artificial antenna, clause 6.5.

The test antenna shall be orientated for vertical polarization and the length of the test antenna shall be chosen to correspond to the instantaneous frequency of the measuring receiver, or a suitable broadband antenna may be used.

The output of the test antenna shall be connected to a measuring receiver.

For integral antenna equipment testing, a filter shall be inserted between the test antenna and the measuring receiver. For the measurement of spurious emissions below the second harmonic of the carrier frequency the filter used shall be a high Q (notch) filter centred on the transmitter carrier frequency and attenuating this signal by at least 30 dB. For the measurement of spurious emissions at and above the second harmonic of the carrier frequency the filter used shall be a high pass filter with a stop band rejection exceeding 40 dB and the cut off frequency of this high pass filter shall be approximately 1,5 times the transmitter carrier frequency. The transmitter shall be switched on without modulation, and the measuring receiver shall be tuned over the frequency range 30 MHz to 2 GHz, except for the channel on which the transmitter is intended to operate and its adjacent channels.

At each frequency at which a spurious component is detected:

- a) the test antenna shall be raised and lowered through the specified range of heights until a maximum signal level is detected on the measuring receiver;
- b) the transmitter shall be rotated through 360° in the horizontal plane, until the maximum signal level is detected by the measuring receiver;
- c) the maximum signal level detected by the measuring receiver shall be noted;
- d) the transmitter shall be replaced by a substitution antenna as defined in annex B;
- e) the substitution antenna shall be orientated for vertical polarization and the length of the substitution antenna shall be adjusted to correspond to the frequency of the spurious component detected;
- f) the substitution antenna shall be connected to a calibrated signal generator;
- g) the frequency of the calibrated signal generator shall be set to the frequency of the spurious component detected;
- h) the input attenuator setting of the measuring receiver shall be adjusted in order to increase the sensitivity of the measuring receiver, if necessary;
- i) the test antenna shall be raised and lowered through the specified range of heights to ensure that the maximum signal is received;
- j) the input signal to the substitution antenna shall be adjusted to the level that produces a level detected by the measuring receiver that is equal to the level noted while the spurious component was measured, corrected for the change of input attenuator setting of the measuring receiver;
- k) the input level to the substitution antenna shall be recorded as power level, corrected for the change of input attenuator setting of the measuring receiver;
- 1) the measurement shall also be taken with the test antenna and the substitution antenna orientated for horizontal polarization;
- m) the effective radiated power of the spurious component is the larger of the two power levels recorded for that spurious component at the input to the substitution antenna, corrected to compensate for the gain of the antenna if necessary;
- n) the measurements shall be repeated with the transmitter in stand-by mode.

### 8.9.3 Limits

With the transmitter in stand-by mode the cabinet radiation and spurious emissions shall not exceed 2 nW.

With the transmitter in operation the cabinet radiation and spurious emissions shall not exceed  $0,25 \mu$ W.

### 8.10 Residual modulation of the transmitter

#### 8.10.1 Definition

The residual modulation of the transmitter is the ratio, in dB, of the demodulated RF signal in the absence of wanted modulation, to the demodulated RF signal produced when the normal test modulation is applied.

### 8.10.2 Method of measurement

The normal test modulation defined in clause 6.4 shall be applied to the transmitter. The high frequency signal produced by the transmitter shall be applied, via an appropriate coupling device, to a linear demodulator with a de-emphasis network of 6 dB per octave. The time constant of this de-emphasis network shall be at least 750  $\mu$ s.

Precautions shall be taken to avoid the effects of emphasizing the low audio frequencies produced by internal noise.

The signal shall be measured at the demodulator output using an rms voltmeter.

The modulation shall then be switched off and the level of the residual audio frequency signal at the output shall be measured again.

### 8.10.3 Limit

The residual modulation shall not exceed -40 dB on either 25 kHz or 12,5 kHz channels.

# 8.11 Transient frequency behaviour of the transmitter

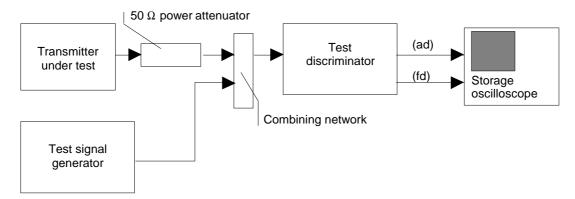
### 8.11.1 Definitions

The transient frequency behaviour of the transmitter is the variation in time of the difference between the instantaneous transmitter frequency and the nominal frequency of the transmitter when the RF output power is switched on and off:

- t<sub>on</sub>: according to the method of measurement described in clause 8.11.2 the switch-on instant t<sub>on</sub> of a transmitter is defined by the condition when the output power, measured at the antenna terminal, exceeds 0,1 % of the nominal power;
- t<sub>1</sub>: period of time starting at t<sub>on</sub> and finishing according to table 2;
- $t_2$ : period of time starting at the end of  $t_1$  and finishing according to table 2;
- t<sub>off</sub>: switch-off instant defined by the condition when the nominal power falls below 0,1 % of the nominal power;
- t<sub>3</sub>: period of time finishing at t<sub>off</sub> and starting according to table 2.

	t <sub>1</sub> (ms)	5,0
	t <sub>2</sub> (ms)	20,0
	t <sub>3</sub> (ms)	5,0
NOTE:	NOTE: During the periods t <sub>1</sub> and t <sub>3</sub> the frequency difference shall not exceed the value of 25 kHz. During the period t <sub>2</sub> the frequency difference shall not exceed the value of 12,5 kHz.	

#### Table 2



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#### Figure 3: Measurement arrangement

Two signals shall be connected to the test discriminator via a combining network.

The transmitter shall be connected to a 50  $\Omega$  power attenuator.

The output of the power attenuator shall be connected to the test discriminator via one input of the combining network.

A test signal generator shall be connected to the second input of the combining network.

The test signal shall be adjusted to the nominal frequency of the transmitter.

The test signal shall be modulated by a frequency of 1 kHz with a deviation of ±25 kHz.

The test signal level shall be adjusted to correspond to 0,1 % of the power of the transmitter under test measured at the input of the test discriminator. This level shall be maintained throughout the measurement.

The amplitude difference (ad) and the frequency difference (fd) output of the test discriminator shall be connected to a storage oscilloscope.

The storage oscilloscope shall be set to display the channel corresponding to the frequency difference (fd) input up to  $\pm 1$  channel frequency difference, corresponding to the relevant channel separation from the nominal frequency.

The storage oscilloscope shall be set to a sweep rate of 10 ms/division and set so that the triggering occurs at 1 division from the left edge of the display.

The display shows the 1 kHz test signal continuously.

The storage oscilloscope shall then be set to trigger on the channel corresponding to the amplitude difference (ad) input at a low input level, rising.

The transmitter shall then be switched on, without modulation, to produce the trigger pulse and a picture on the display.

The result of the change in the ratio of power between the test signal and the transmitter output, due to the capture ratio of the test discriminator, produces two separate sides on the picture, one showing the 1 kHz test signal, the other the frequency difference of the transmitter versus time:

- the moment when the 1 kHz test signal is completely suppressed is considered to provide t<sub>on</sub>;
- the periods of time  $t_1$  and  $t_2$  as defined in the table shall be used to define the appropriate template;
- the result shall be recorded as frequency difference versus time;
- the transmitter shall remain switched on.

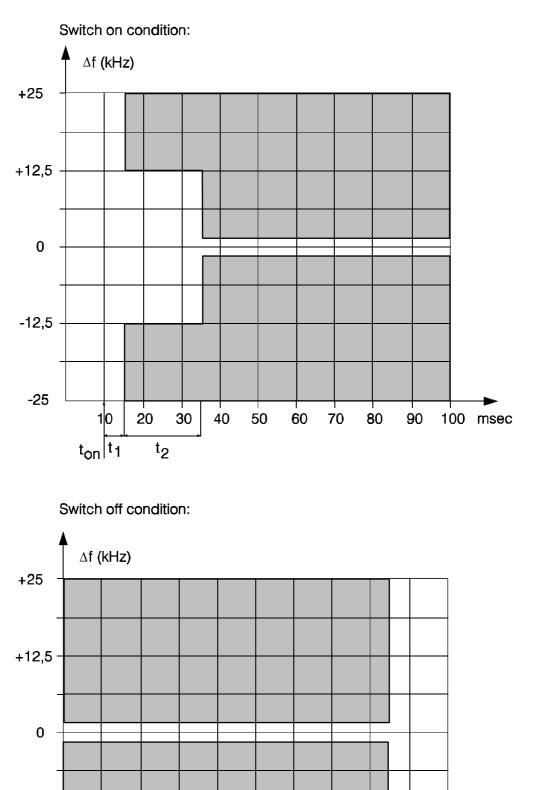
The storage oscilloscope shall be set to trigger on the channel corresponding to the amplitude difference (ad) input at a high input level, decaying and set so that the triggering occurs at 1 division from the right edge of the display:

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- the transmitter shall then be switched off;
- the moment when the 1 kHz test signal starts to rise is considered to provide toff;
- the period of time t<sub>3</sub> as defined in table 2 shall be used to define the appropriate template;
- the result shall be recorded as frequency difference versus time.

### 8.11.3 Limits

- During the period of time t<sub>1</sub> the frequency difference shall not exceed the value of 25 kHz.
- During the period of time t<sub>2</sub> the frequency difference shall not exceed the value of 12,5 kHz.
- The frequency difference, after t<sub>2</sub>, shall not exceed the value of 1,5 kHz.
- Before the start of t<sub>3</sub> the frequency difference shall not exceed the value of 1,5 kHz.
- During the period of time t<sub>3</sub> the frequency difference shall not exceed the value of 25 kHz.





t<sub>3</sub>t<sub>off</sub>

100 msec

-12,5

-25

# 8.12 Frequency error (demodulated DSC signal)

### 8.12.1 Definition

The frequency error for the B- and the Y-state is the difference between the measured frequency from the demodulator and the nominal values.

### 8.12.2 Method of measurement

The transmitter shall be connected to the artificial antenna as specified in clause 6.5 and a suitable FM demodulator. The transmitter shall be set to channel 70.

The transmitter shall be set to transmit a continuous B- or Y- state.

The measurement shall be performed by measuring the demodulated output, for both the continuous B- and Y-state.

The measurements shall be carried out under normal test conditions (see clause 6.13) and extreme test conditions (see clauses 6.14.1 and 6.14.2 applied simultaneously).

### 8.12.3 Limits

The measured frequency from the demodulator at any time for the B-state shall be within 2 100 Hz  $\pm$  10 Hz and for the Y-state within 1 300 Hz  $\pm$  10 Hz.

# 8.13 Modulation index for DSC

### 8.13.1 Definition

This test measures the modulation index in the B and Y states.

### 8.13.2 Method of measurement

The transmitter shall be set to transmit continuous B and then Y signals. The frequency deviations shall be measured.

### 8.13.3 Limits

The modulation index shall be 2,0  $\pm$  10 %.

# 8.14 Modulation rate for DSC

### 8.14.1 Definition

The modulation rate is the bit stream speed measured in bit/s.

### 8.14.2 Method of measurement

The transmitter shall be set to transmit continuous dot pattern.

The RF output terminal of the transmitter, suitably attenuated, shall be connected via a linear FM demodulator to a calibrated FSK demodulator. The output of the FSK demodulator shall be limited in bandwidth by a low pass filter with a cut-off frequency of 1 kHz and a slope of 12 dB/octave.

The frequency of the output shall be measured.

### 8.14.3 Limits

The frequency shall be 600 Hz  $\pm$  30 ppm corresponding to a modulation rate of 1 200 baud.

# 8.15 Testing of free channel transmission on DSC channel 70

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### 8.15.1 Definition

This test verifies that the transmitter has a facility to prevent transmission of DSC calls if channel 70 is busy, except in case of distress and safety calls.

### 8.15.2 Method of measurement

The output of the transmitter shall be suitably connected to a calibrated apparatus for decoding and printing out the information content of the call sequences generated by the equipment.

The receiver input is connected to a signal generator. The signal generator is set to the frequency of channel 70 (156,525 MHz) and the RF signal shall be modulated by a DSC dot pattern signal, see clause 6.4. The test is performed at an RF level; of  $+6 \text{ dB}\mu\text{V}$  (emf).

If the receiver input and transmitter output are combined in the same port it is necessary to combine the calibrated apparatus for decoding and printing out the information content of the call sequences and the signal generator through a suitable combining network, see clause 6.2. It may be necessary to protect the signal generator against the power output from the equipment through an attenuator.

For each available DSC call type:

- The signal generator output shall be turned on.
- The transmitter shall be set to transmit that DSC call.
- The signal generator output shall be turned off.

### 8.15.3 Requirement

If the format specifier is distress or the category is either distress, (and if available in the equipment), urgency or safety in the transmitted DSC call, the call shall be transmitted while the signal generator output is still on.

Otherwise the call shall not be transmitted until the signal generator output has been turned off.

# 9 Receiver

# 9.1 Harmonic distortion and rated audio frequency output power

### 9.1.1 Definition

The harmonic distortion at the receiver output is defined as the ratio, expressed as a percentage, of the total rms voltage of all the harmonic components of the modulation audio frequency to the total rms voltage of the signal delivered by the receiver.

The rated audio frequency output power is the value stated by the manufacturer to be the maximum power available at the output, for which all the requirements of the present document are met.

### 9.1.2 Methods of measurement

Test signals at a level of  $+100 \text{ dB}\mu\text{V}$ , at a carrier frequency equal to the nominal frequency of the receiver and modulated by the normal test modulation (clause 6.4) shall be applied in succession to the receiver input under the conditions specified in clause 6.1.

For each measurement, the receiver's audio frequency volume control shall be set so as to obtain, in a resistive load which simulates the receiver's operating load, the rated audio frequency output power (clause 9.1.1). The value of this load shall be stated by the manufacturer.

Under normal test conditions (clause 6.10) the test signal shall be modulated successively at 300 Hz, 500 Hz and 1 kHz with a constant modulation index of 3 (ratio between the frequency deviation and the modulation frequency). The harmonic distortion and audio frequency output power shall be measured at all the frequencies specified above.

Under extreme test conditions (clauses 6.11.1 and 6.11.2 applied simultaneously), the tests shall be made at the receiver's nominal frequency and at the nominal frequency  $\pm 1,5$  kHz. For these tests, the modulation shall be 1 kHz and the frequency deviation shall be  $\pm 3$  kHz.

#### 9.1.3 Limits

The rated audio frequency output power shall be at least 0,2 W in the loudspeaker.

The harmonic distortion shall not exceed 10 %.

### 9.2 Audio frequency response

### 9.2.1 Definition

The audio frequency response is the variation in the receiver's audio frequency output level as a function of the modulating frequency of a received radio frequency signal modulated with constant deviation.

### 9.2.2 Method of measurement

A test signal of  $+60 \text{ dB}\mu\text{V}$  (emf), at a carrier frequency equal to the nominal frequency of the receiver and modulated with normal test modulation (clause 6.4), shall be applied to the receiver antenna port under the conditions specified in clause 6.2.

The receiver's audio frequency power control shall be set so as to produce a power level of at least 50 % of the rated output power (clause 9.1). This setting shall remain unchanged during the test.

The frequency deviation shall then be reduced to 1 kHz and the audio output is the reference point in figure 5 (1 kHz corresponds to 0 dB).

The frequency deviation shall remain constant while the modulation frequency is varied between 300 Hz and 3 kHz and the output level shall then be measured.

The measurement shall be repeated with a test signal at frequencies 1,5 kHz above and below the nominal frequency of the receiver.

The test shall be carried out on one channel only (see clause 6.7).

### 9.2.3 Limits

The audio frequency response shall not deviate by more than +1 dB or -3 dB from a characteristic giving the output level as a function of the audio frequency, decreasing by 6 dB per octave and passing through the measured point at 1 kHz (figure 5).

Certified Intrinsically Safe equipment need not comply with the limits below 700 Hz.

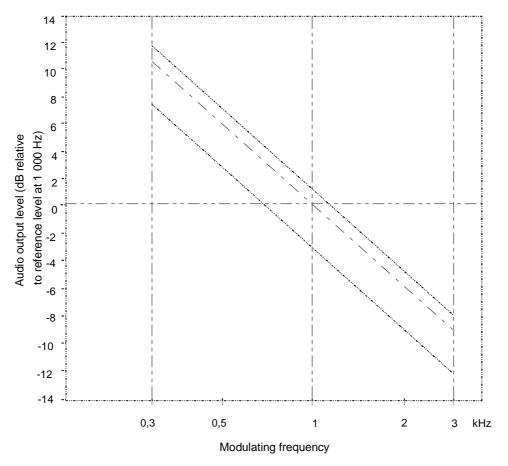


Figure 5: Audio frequency response

### 9.3 Maximum usable sensitivity

#### 9.3.1 Definition

The maximum usable sensitivity of the receiver is the minimum level of the signal (emf) at the nominal frequency of the receiver which, when applied to the receiver input with normal test modulation (clause 6.4), will produce:

- in all cases, an audio frequency output power of at least 50 % of the rated output power (clause 9.1); and
- a SINAD ratio of 20 dB, measured at the receiver output through a psophometric telephone filtering network such as described in ITU-T Recommendation 0.41 [6].

#### 9.3.2 Method of measurement

The test shall be performed on the lowest frequency channel, the highest frequency channel and on channel 16.

A test signal at a carrier frequency equal to the nominal frequency of the receiver, modulated by the normal test modulation (clause 6.4) shall be applied to the receiver input. An audio frequency load and a measuring instrument for measuring the SINAD ratio (through a psophometric network as specified in clause 9.3.1) shall be connected to the receiver output terminals.

The level of the test signal shall be adjusted until a SINAD ratio of 20 dB is obtained, using the psophometric network and with the receiver's audio frequency power control adjusted to produce at least 50 % of the rated output power. Under these conditions, the level of the test signal at the input is the value of the maximum usable sensitivity.

The measurements shall be taken under normal test conditions (clause 6.10) and under extreme test conditions (clauses 6.11.1 and 6.11.2 applied simultaneously).

A receiver output power variation of  $\pm 3$  dB relative to 50 % of the rated output power may be allowed for sensitivity measurements under extreme test conditions.

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#### 9.3.3 Limits

The maximum usable sensitivity for either 25 kHz or 12,5 kHz channels shall not exceed +6 dB $\mu$ V (emf) under normal test conditions and +12 dB $\mu$ V (emf) under extreme test conditions.

# 9.4 Co-channel rejection

### 9.4.1 Definition

The co-channel rejection is a measure of the capability of the receiver to receive a wanted modulated signal without exceeding a given degradation due to the presence of an unwanted modulated signal, both signals being at the nominal frequency of the receiver.

### 9.4.2 Method of measurement

The two input signals shall be connected to the receiver via a combining network (clause 6.2). The wanted signal shall have normal test modulation (clause 6.4). The unwanted signal shall be modulated by 400 Hz with a deviation of  $\pm 3$  kHz (see note). Both input signals shall be at the nominal frequency of the receiver under test and the measurement repeated for displacements of the unwanted signal of up to  $\pm 3$  kHz.

The wanted input signal level shall be set to the value corresponding to the maximum usable sensitivity as measured in clause 9.3. The amplitude of the unwanted input signal shall then be adjusted until the SINAD ratio (psophometrically weighted) at the output of the receiver is reduced to 14 dB.

The co-channel rejection ratio shall be expressed as the ratio in dB of the level of the unwanted signal to the level of the wanted signal at the receiver input for which the specified reduction in SINAD ratio occurs.

NOTE: For 12,5 kHz channels the frequency deviation and the displacement of the unwanted signal is ±1,5 kHz.

### 9.4.3 Limit

The co-channel rejection ratio, at any frequency of the unwanted signal within the specified range, shall be between:

- -10 dB and 0 dB for 25 kHz channels;
- -12 dB and 0 dB for 12,5 kHz channels.

# 9.5 Adjacent channel selectivity

#### 9.5.1 Definition

The adjacent channel selectivity is a measure of the capability of the receiver to receive a wanted modulated signal without exceeding a given degradation due to the presence of an unwanted modulated signal which differs in frequency from the wanted signal by the nominal channel spacing.

### 9.5.2 Method of measurement

The test shall be performed on the lowest frequency channel, the highest frequency channel and on channel 16.

The two input signals shall be applied to the receiver input via a combining network (clause 6.2). The wanted signal shall be at the nominal frequency of the receiver and shall have normal test modulation (clause 6.4). The unwanted signal shall be modulated by 400 Hz with a deviation of  $\pm 3$  kHz for 25 kHz channels or  $\pm 1.5$  kHz for 12.5 kHz channels, and shall be at the frequency of the channel immediately above that of the wanted signal.

The wanted input signal level shall be set to the value corresponding to the maximum usable sensitivity as measured in clause 9.3. The amplitude of the unwanted input signal shall then be adjusted until the SINAD ratio at the receiver output, psophometrically weighted, is reduced to 14 dB. The measurement shall be repeated with an unwanted signal at the frequency of the channel below that of the wanted signal.

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The adjacent channel selectivity shall be expressed as the lower value of the ratios in dB for the upper and lower adjacent channels of the level of the unwanted signal to the level of the wanted signal.

The test shall then be repeated under extreme test conditions (clauses 6.11.1 and 6.11.2 applied simultaneously) with the wanted signal set to the value corresponding to the maximum usable sensitivity under these conditions.

### 9.5.3 Limits

25 kHz channels: The adjacent channel selectivity shall be not less than 70 dB under normal test conditions and not less than 60 dB under extreme test conditions.

12,5 kHz channels: The adjacent channel selectivity shall be not less than 60 dB under normal test conditions and not less than 50 dB under extreme test conditions.

# 9.6 Spurious response rejection

### 9.6.1 Definition

The spurious response rejection is a measure of the capability of the receiver to discriminate between the wanted modulated signal at the nominal frequency and an unwanted signal at any other frequency at which a response is obtained.

### 9.6.2 Method of measurement

Two input signals shall be applied to the receiver input via a combining network (clause 6.2). The wanted signal shall be at the nominal frequency of the receiver and shall have normal test modulation (clause 6.4).

The unwanted signal shall be modulated by 400 Hz with a deviation of  $\pm 3$  kHz.

The wanted input signal level shall be set to the value corresponding to the maximum usable sensitivity as measured in clause 9.3. The amplitude of the unwanted input signal shall be adjusted to an emf of +86 dB $\mu$ V. The frequency shall then be swept over the frequency range from 100 kHz to 2 000 MHz.

At any frequency at which a response is obtained, the input level shall be adjusted until the SINAD ratio psophometrically weighted, is reduced to 14 dB.

The spurious response rejection ratio shall be expressed as the ratio in dB between the unwanted signal and the wanted signal at the receiver input when the specified reduction in the SINAD ratio is obtained.

### 9.6.3 Limit

At any frequency separated from the nominal frequency of the receiver by more than 25 kHz, the spurious response rejection ratio shall be not less than 70 dB.

### 9.7 Intermodulation response

#### 9.7.1 Definition

The intermodulation response is a measure of the capability of a receiver to receive a wanted modulated signal without exceeding a given degradation due to the presence of two or more unwanted signals with a specific frequency relationship to the wanted signal frequency.

### 9.7.2 Method of measurement

Three signal generators, A, B and C shall be connected to the receiver via a combining network (clause 6.2). The wanted signal, represented by signal generator A shall be at the nominal frequency of the receiver and shall have normal test modulation (clause 6.4). The unwanted signal from signal generator B shall be unmodulated and adjusted to the frequency 50 kHz above (or below) the nominal frequency of the receiver. The second unwanted signal from signal generator C shall be modulated by 400 Hz with a deviation of  $\pm 3$  kHz, and adjusted to a frequency 100 kHz above (or below) the nominal frequency.

The wanted input signal shall be set to a value corresponding to the maximum usable sensitivity as measured in clause 9.3. The amplitude of the two unwanted signals shall be maintained equal and shall be adjusted until the SINAD ratio at the receiver output, psophometrically weighted, is reduced to 14 dB. The frequency of signal generator B shall be adjusted slightly to produce the maximum degradation of the SINAD ratio. The level of the two unwanted test signals shall be readjusted to restore the SINAD ratio of 14 dB. The intermodulation response ratio shall be expressed as the ratio in dB between the two unwanted signals and the wanted signal at the receiver input, when the specified reduction in the SINAD ratio is obtained.

### 9.7.3 Limit

The intermodulation response ratio shall not be less than 68 dB.

# 9.8 Blocking or desensitization

### 9.8.1 Definition

Blocking is a change (generally a reduction) in the wanted output power of the receiver or a reduction of the SINAD ratio due to an unwanted signal on another frequency.

### 9.8.2 Method of measurement

Two input signals shall be applied to the receiver via a combining network (clause 6.2). The modulated wanted signal shall be at the nominal frequency of the receiver and shall have normal test modulation (clause 6.4). Initially the unwanted signal shall be switched off and the wanted signal set to the value corresponding to the maximum usable sensitivity.

The output power of the wanted signal shall be adjusted, where possible, to 50 % of the rated output power and in the case of stepped volume controls, to the first step that provides an output power of at least 50 % of the rated output power. The unwanted signal shall be unmodulated and the frequency shall be swept between +1 MHz and +10 MHz, and also between -1 MHz and -10 MHz, relative to the nominal frequency of the receiver. For practical reasons the measurements will be carried out at frequency offsets of the unwanted signal at approximately 1 MHz, 2 MHz, 5 MHz and 10 MHz.

The input level of the unwanted signal, at all frequencies in the specified ranges, shall be so adjusted that the unwanted signal causes:

- a) a reduction of 3 dB in the output level of the wanted signal; or
- b) a reduction to 14 dB of the SINAD ratio at the receiver output using a psophometric telephone filtering network such as described in ITU-T Recommendation O.41 [6] whichever occurs first. This level shall be noted.

### 9.8.3 Limit

The blocking level for any frequency within the specified ranges, shall be not less than 90 dB $\mu$ V (emf), except at frequencies on which spurious responses are found (clause 9.6).

## 9.9 Conducted spurious emissions

#### 9.9.1 Definition

Conducted spurious emissions from the receiver are components at any frequency, present at the receiver input port.

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#### 9.9.2 Method of measurement

The level of spurious emissions shall be measured as the power level at the antenna.

Conducted spurious radiations shall be measured as the power level of any discrete signal at the input terminals of the receiver. The receiver input terminals are connected to a spectrum analyser or selective voltmeter having an input impedance of 50  $\Omega$  and the receiver is switched on.

If the detecting device is not calibrated in terms of power input, the level of any detected components shall be determined by a substitution method using a signal generator.

The measurements shall extend over the frequency range of 9 kHz to 2 GHz.

#### 9.9.3 Limit

The power of any spurious radiation shall not exceed 2 nW at any frequency in the range between 9 kHz and 2 GHz.

## 9.10 Radiated spurious emissions

#### 9.10.1 Definition

Radiated spurious emissions from the receiver are components at any frequency radiated by the equipment cabinet and the structure.

Integral antenna equipment shall be tested with the normal antenna fitted.

### 9.10.2 Method of measurements

On a test site, selected from annex B, the equipment shall be placed at the specified height on a non-conducting support and in a position which is closest to normal use as declared by the manufacturer.

The test antenna shall be orientated for vertical polarization and the length of the test antenna shall be chosen to correspond to the instantaneous frequency of the measuring receiver, or a suitable broadband antenna may be used.

The output of the test antenna shall be connected to a measuring receiver.

The receiver shall be switched on without modulation, and measuring receiver shall be tuned over the frequency range 30 MHz to 2 GHz.

At each frequency at which a spurious component is detected:

- a) the test antenna shall be raised and lowered through the specified range of heights until a maximum signal level is detected on the measuring receiver;
- b) the receiver shall be rotated through 360° in the horizontal plane, until the maximum signal level is detected by the measuring receiver;
- c) the maximum signal level detected by the measuring receiver shall be noted;
- d) the receiver shall be replaced by a substitution antenna as defined in annex B;
- e) the substitution antenna shall be orientated for vertical polarization and the length of the substitution antenna shall be adjusted to correspond to the frequency of the spurious component detected;

- f) the substitution antenna shall be connected to a calibrated signal generator;
- g) the frequency of the calibrated signal generator shall be set to the frequency of the spurious component detected;

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- h) the input attenuator setting of the measuring receiver shall be adjusted in order to increase the sensitivity of the measuring receiver, if necessary;
- i) the test antenna shall be raised and lowered through the specified range of heights to ensure that the maximum signal is received;
- j) the input signal to the substitution antenna shall be adjusted to the level that produces a level detected by the measuring receiver that is equal to the level noted while the spurious component was measured, corrected for the change of input attenuator setting of the measuring receiver;
- k) the input level to the substitution antenna shall be recorded as power level, corrected for the change of input attenuator setting of the measuring receiver;
- 1) the measurement shall also be taken with the test antenna and the substitution antenna orientated for horizontal polarization;
- m) the effective radiated power of the spurious component is the larger of the two power levels recorded for that spurious component at the input to the substitution antenna, corrected to compensate for the gain of the antenna if necessary.

#### 9.10.3 Limit

The power of any spurious radiation shall not exceed 2 nW at any frequency in the range between 30 MHz and 2 GHz.

### 9.11 Receiver noise and hum level

#### 9.11.1 Definition

The receiver noise and hum level is defined as the ratio, in dB, of the audio frequency power of the noise and hum resulting from spurious effects of the power supply system or from other causes, to the audio frequency power produced by a high frequency signal of average level, modulated by the normal test modulation and applied to the receiver input.

#### 9.11.2 Method of measurement

A test signal with a level of  $+30 \text{ dB}\mu\text{V}$  (emf) at a carrier frequency equal to the nominal frequency of the receiver, and modulated by the normal test modulation specified in clause 6.4, shall be applied to the receiver input. An audio frequency load shall be connected to the output terminals of the receiver. The audio frequency power control shall be set so as to produce the rated output power level conforming to clause 9.1.

The output signal shall be measured by an rms voltmeter having a -6 dB bandwidth of at least 20 kHz. The modulation shall then be switched off and the audio frequency output level measured again.

#### 9.11.3 Limit

The receiver noise and hum level shall not exceed -40 dB, relative to the modulated signal.

### 9.12 Squelch operation

#### 9.12.1 Definition

The purpose of the squelch facility is to mute the receiver audio output signal when the level of the signal at the receiver input is less than a given value.

The following procedure shall be followed.

a) All equipment:

With the squelch facility switched off, a test signal of  $+30 \text{ dB}\mu\text{V}$ , at a carrier frequency equal to the nominal frequency of the receiver and modulated by the normal test modulation specified in clause 6.4, shall be applied to the input terminals of the receiver. An audio frequency load and a psophometric filtering network (clause 9.3.1) shall be connected to the output terminals of the receiver. The receiver's audio frequency power control shall be set so as to produce the rated output power defined in clause 9.1.

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The output signal shall be measured with the aid of an rms voltmeter.

The input signal shall then be suppressed, the squelch facility switched on and the audio frequency output level measured again.

b) Equipment with a preset or automatic squelch:

With the squelch facility switched off again, a test signal modulated by the normal test modulation shall be applied to the receiver input at a level of +6 dB $\mu$ V (emf) and the receiver shall be set to produce at least 50 % of the rated output power. The level of the input signal shall then be reduced and the squelch facility shall be switched on. The input signal shall then be increased until the above-mentioned output power is reached. The SINAD ratio and the input level shall then be measured.

c) Equipment with a user operated continuously variable squelch:

With the squelch facility switched off, a test signal with normal test modulation shall be applied to the receiver input at a level of +6 dB $\mu$ V (emf), and the receiver shall be set to produce at least 50 % of the rated audio output power. The level of the input signal shall then be reduced and the squelch facility shall be switched on. The squelch shall then be at its maximum position and the level of the input signal increased until the output power returns to at least 50 % of the rated audio output power.

#### 9.12.3 Limits

Under the conditions specified in a) clause 9.11.2, the audio frequency output power shall not exceed -40 dB relative to the rated output power.

Under the conditions specified in b) clause 9.11.2, the input level shall not exceed +6 dBµV (emf).

Under the conditions specified in c) clause 9.11.2, the input signal shall not exceed +6 dB $\mu$ V (emf) when the control is set at maximum.

### 9.13 Squelch hysteresis

#### 9.13.1 Definition

Squelch hysteresis is the difference in dB between the receiver input signal levels at which the squelch opens and closes.

#### 9.13.2 Method of measurement

If there is any squelch control on the exterior of the equipment it shall be placed in its maximum muted position. With the squelch facility switched on, an unmodulated input signal at a carrier frequency equal to the nominal frequency of the receiver shall be applied to the input of the receiver at a level sufficiently low to avoid opening the squelch. The input signal shall be increased to the level just opening the squelch. This input level shall be recorded. With the squelch still open, the level of the input signal shall be slowly decreased until the squelch mutes the receiver audio output again, the hysteresis being the difference between this level and the previously recorded level.

#### 9.13.3 Limit

The squelch hysteresis shall be between 3 dB and 6 dB.

## 9.14 Receiver scanning efficiency

#### 9.14.1 Definition

This test is to establish the probability of correctly receiving a DSC call on channel 70 while the receiver is scanning between channel 70 and another channel.

#### 9.14.2 Method of measurement

Send 100 DSC calls to equipment.

#### 9.14.3 Limit

Equipment shall correctly receive at least 95 % of DSC calls used whilst scanning.

## Annex A (normative): Measuring receiver for adjacent channel power measurement

## A.1 Power measuring receiver specification

The power measuring receiver consists of a mixer, an Intermediate Frequency (IF) filter, an oscillator, an amplifier, a variable attenuator and an rms value indicator. Instead of the variable attenuator with the rms value indicator it is also possible to use an rms voltmeter calibrated in dB. The technical characteristics of the power measuring receiver are given in figure A.1 (see also ITU-R Recommendation SM.332-4 [7]).

## A.1.1 IF filter

The IF filter shall be within the limits of the following selectivity characteristics.

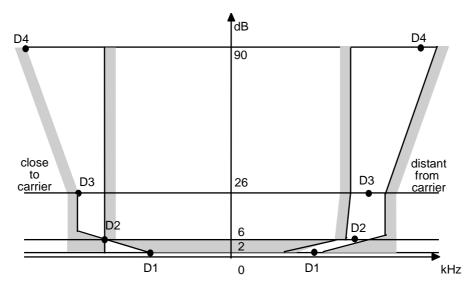


Figure A.1: IF filter characteristics

The selectivity characteristics shall keep the frequency separations shown in table A.1 from the nominal centre frequency of the adjacent channel.

Table A.1: Sele	tivity characteristic
-----------------	-----------------------

Channel separation (kHz)	Frequency separation of filter curve from nominal centre frequency of adjacent channel (kHz)			
	D1	D2	D3	D4
12,5	3	4,25	5,5	9,5
25	5	8,0	9,25	13,25

The attenuation points shall not exceed following tolerances shown in table A.2.

Table A.2: Tolerance of attenuation points close to carrier

Channel separation	Tolerance range (kHz)			
(kHz)	D1	D2	D3	D4
12,5	+1,35	±0,1	-1,35	-5,35
25	+3,1	±0,1	-1,35	-5,35

Channel separation	tion Tolerance range (kHz)			
(kHz)	D1	D2	D3	D4
12,5	±2,0	±2,0	±2,0	+2,0
				-6,0
25	±3,5	±3,5	±3,5	+3,5
				-7,5

#### Table A.3: Tolerance of attenuation points distant from the carrier

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The minimum attenuation of the filter outside the 90 dB attenuation points shall be equal to or greater than 90 dB.

## A.1.2 Attenuation indicator

The attenuation indicator shall have a minimum range of 80 dB and a reading accuracy of 1 dB. With a view to future regulations an attenuation of 90 dB or more is recommended.

### A.1.3 Rms value indicator

The instrument shall accurately indicate non-sinusoidal signals in ratio of up to 10:1 between peak value and rms value.

## A.1.4 Oscillator and amplifier

The oscillator and the amplifier shall be designed in such a way that the measurement of the adjacent channel power of a low-noise unmodulated transmitter, whose self-noise has a negligible influence on the measurement result, yields a measured value of less than -90 dB.

## Annex B (normative): Radiated measurement

## B.1 Test sites and general arrangements for measurements involving the use of radiated fields

This normative annex introduces three most commonly available test sites, an anechoic chamber, an anechoic chamber with a ground plane and an Open Area Test Site (OATS), which may be used for radiated tests. These test sites are generally referred to as free field test sites. Both absolute and relative measurements can be performed in these sites. Where absolute measurements are to be carried out, the chamber should be verified. A detailed verification procedure is described in TR 102 273 [12], relevant parts 2, 3 and 4.

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NOTE: To ensure reproducibility and traceability of radiated measurements only these test sites should be used in test measurements.

#### B.1.1 Anechoic chamber

An anechoic chamber is an enclosure, usually shielded, whose internal walls, floor and ceiling are covered with radio absorbing material, normally of the pyramidal urethane foam type. The chamber usually contains an antenna support at one end and a turntable at the other. A typical anechoic chamber is shown in figure B.1.

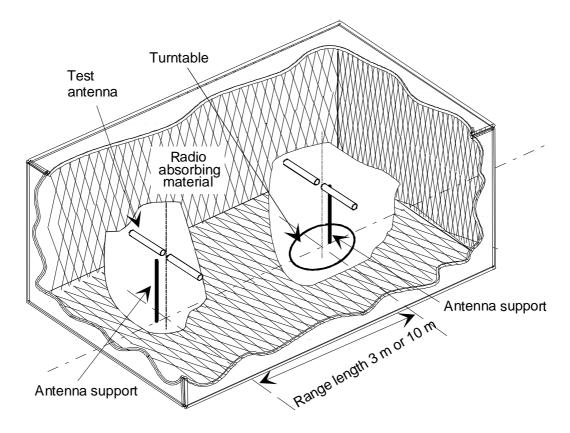


Figure B.1: A typical anechoic chamber

The chamber shielding and radio absorbing material work together to provide a controlled environment for testing purposes. This type of test chamber attempts to simulate free space conditions.

The shielding provides a test space, with reduced levels of interference from ambient signals and other outside effects, whilst the radio absorbing material minimizes unwanted reflections from the walls and ceiling which can influence the measurements. In practice it is relatively easy for shielding to provide high levels (80 dB to 140 dB) of ambient interference rejection, normally making ambient interference negligible.

A turntable is capable of rotation through 360° in the horizontal plane and it is used to support the test sample (EUT) at a suitable height (e.g. 1 m) above the ground plane. The chamber shall be large enough to allow the measuring distance of at least 3 m or  $2(d_1+d_2)^2 / \lambda$  (m), whichever is greater (see clause B.2.5). The distance used in actual measurements shall be recorded with the test results.

The anechoic chamber generally has several advantages over other test facilities. There is minimal ambient interference, minimal floor, ceiling and wall reflections and it is independent of the weather. It does however have some disadvantages which include limited measuring distance and limited lower frequency usage due to the size of the pyramidal absorbers. To improve low frequency performance, a combination structure of ferrite tiles and urethane foam absorbers is commonly used.

All types of emission, sensitivity and immunity testing can be carried out within an anechoic chamber without limitation.

### B.1.2 Anechoic chamber with a ground plane

An anechoic chamber with a ground plane is an enclosure, usually shielded, whose internal walls and ceiling are covered with radio absorbing material, normally of the pyramidal urethane foam type. The floor, which is metallic, is not covered and forms the ground plane. The chamber usually contains an antenna mast at one end and a turntable at the other. A typical anechoic chamber with a ground plane is shown in figure B.2.

This type of test chamber attempts to simulate an ideal OATS whose primary characteristic is a perfectly conducting ground plane of infinite extent.

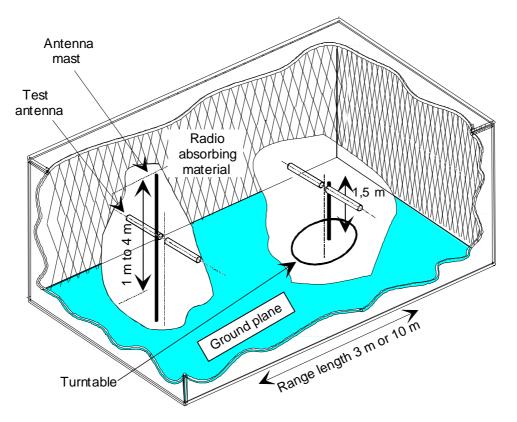


Figure B.2: A typical anechoic chamber with a ground plane

In this facility the ground plane creates the wanted reflection path, such that the signal received by the receiving antenna is the sum of the signals from both the direct and reflected transmission paths. This creates a unique received signal level for each height of the transmitting antenna (or EUT) and the receiving antenna above the ground plane.

The antenna mast provides a variable height facility (from 1 m to 4 m) so that the position of the test antenna can be optimized for maximum coupled signal between antennas or between an EUT and the test antenna.

A turntable is capable of rotation through 360° in the horizontal plane and it is used to support the test sample (EUT) at a specified height, usually 1,5 m above the ground plane. The chamber shall be large enough to allow the measuring distance of at least 3 m or  $2(d_1+d_2)^2 / \lambda$  (m), whichever is greater (see clause B.2.5). The distance used in actual measurements shall be recorded with the test results.

Emission testing involves firstly "peaking" the field strength from the EUT by raising and lowering the receiving antenna on the mast (to obtain the maximum constructive interference of the direct and reflected signals from the EUT) and then rotating the turntable for a "peak" in the azimuth plane. At this height of the test antenna on the mast, the amplitude of the received signal is noted. Secondly the EUT is replaced by a substitution antenna (positioned at the EUT's phase or volume centre) which is connected to a signal generator. The signal is again "peaked" and the signal generator output adjusted until the level, noted in stage one, is again measured on the receiving device.

Receiver sensitivity tests over a ground plane also involve "peaking" the field strength by raising and lowering the test antenna on the mast to obtain the maximum constructive interference of the direct and reflected signals, this time using a measuring antenna which has been positioned where the phase or volume centre of the EUT will be during testing. A transform factor is derived. The test antenna remains at the same height for stage two, during which the measuring antenna is replaced by the EUT. The amplitude of the transmitted signal is reduced to determine the field strength level at which a specified response is obtained from the EUT.

### B.1.3 OATS

An OATS comprises a turntable at one end and an antenna mast of variable height at the other end above a ground plane which, in the ideal case, is perfectly conducting and of infinite extent. In practice, whilst good conductivity can be achieved, the ground plane size has to be limited. A typical OATS is shown in figure B.3.

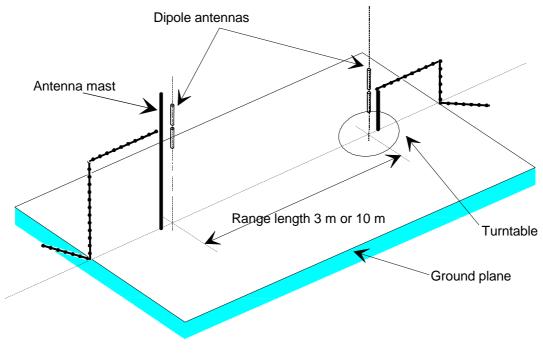


Figure B.3: A typical OATS

The ground plane creates a wanted reflection path, such that the signal received by the receiving antenna is the sum of the signals received from the direct and reflected transmission paths. The phasing of these two signals creates a unique received level for each height of the transmitting antenna (or EUT) and the receiving antenna above the ground plane.

Site qualification concerning antenna positions, turntable, measurement distance and other arrangements are same as for anechoic chamber with a ground plane. In radiated measurements an OATS is also used by the same way as anechoic chamber with a ground plane.

Typical measuring arrangement common for ground plane test sites is presented in figure B.4.

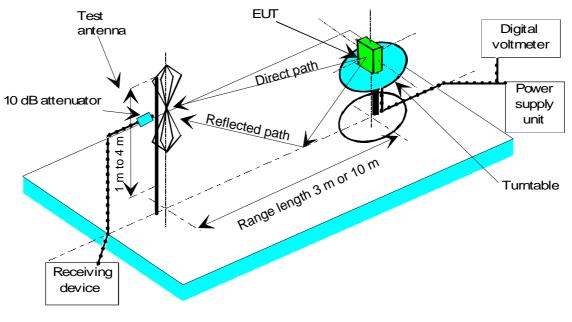


Figure B.4: Measuring arrangement on ground plane test site (OATS set-up for spurious emission testing)

### B.1.4 Test antenna

A test antenna is always used in radiated test methods. In emission tests (i.e. frequency error, effective radiated power, spurious emissions and adjacent channel power) the test antenna is used to detect the field from the EUT in one stage of the measurement and from the substitution antenna in the other stage. When the test site is used for the measurement of receiver characteristics (i.e. sensitivity and various immunity parameters) the antenna is used as the transmitting device.

The test antenna should be mounted on a support capable of allowing the antenna to be used in either horizontal or vertical polarization which, on ground plane sites (i.e. anechoic chambers with ground planes and OATS), should additionally allow the height of its centre above the ground to be varied over the specified range (usually 1 m to 4 m).

In the frequency band 30 MHz to 1 000 MHz, dipole antennas (constructed in accordance with ANSI C63.5 [10]) are generally recommended. For frequencies of 80 MHz and above, the dipoles should have their arm lengths set for resonance at the frequency of test. Below 80 MHz, shortened arm lengths are recommended. For spurious emission testing, however, a combination of bicones and log periodic dipole array antennas (commonly termed "log periodics") could be used to cover the entire 30 MHz to 1 000 MHz band. Above 1 000 MHz, waveguide horns are recommended although, again, log periodics could be used.

NOTE: The gain of a horn antenna is generally expressed relative to an isotropic radiator.

### B.1.5 Substitution antenna

The substitution antenna is used to replace the EUT for tests in which a transmitting parameter (i.e. frequency error, effective radiated power, spurious emissions and adjacent channel power) is being measured. For measurements in the frequency band 30 MHz to 1 000 MHz, the substitution antenna should be a dipole antenna (constructed in accordance with ANSI C63.5 [10]). For frequencies of 80 MHz and above, the dipoles should have their arm lengths set for resonance at the frequency of test. Below 80 MHz, shortened arm lengths are recommended. For measurements above 1 000 MHz, a waveguide horn is recommended. The centre of this antenna should coincide with either the phase centre or volume centre (as specified in the test method) of the EUT it has replaced.

## B.1.6 Measuring antenna

The measuring antenna is used in tests on an EUT in which a receiving parameter (i.e. sensitivity and various immunity tests) is being measured. Its purpose is to enable a measurement of the electric filed strength in the vicinity of the EUT. For measurements in the frequency band 30 MHz to 1 000 MHz, the measuring antenna should be a dipole antenna (constructed in accordance with ANSI C63.5 [10]). For frequencies of 80 MHz and above, the dipoles should have their arm lengths set for resonance at the frequency of test. Below 80 MHz, shortened arm lengths are recommended. The centre of this antenna should coincide with either the phase centre or volume centre (as specified in the test method) of the EUT.

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## B.2 Guidance on the use of radiation test sites

This clause details procedures, test equipment arrangements and verification that should be carried out before any of the radiated test are undertaken. These schemes are common to all types of test sites described in this annex.

## B.2.1 Verification of the test site

No test should be carried out on a test site which does not possess a valid certificate of verification. The verification procedures for the different types of test sites described in this annex (i.e. anechoic chamber, anechoic chamber with a ground plane and OATS) are given in TR 102 273 [12], parts 2, 3 and 4, respectively.

## B.2.2 Preparation of the EUT

The manufacturer should supply information about the EUT covering the operating frequency, polarization, supply voltage(s) and the reference face. Additional information, specific to the type of EUT should include, where relevant, carrier power, CSP, whether different operating modes are available (e.g. high and low power modes) and if operation is continuous or is subject to a maximum test duty cycle (e.g. 1 m on, 4 m off).

Where necessary, a mounting bracket of minimal size should be available for mounting the EUT on the turntable. This bracket should be made from low conductivity, low relative dielectric constant (i.e. less than 1,5) material(s) such as expanded polystyrene, balsawood, etc.

## B.2.3 Power supplies to the EUT

All tests should be performed using power supplies wherever possible, including tests on EUT designed for battery-only use. In all cases, power leads should be connected to the EUT's supply terminals (and monitored with a digital voltmeter) but the battery should remain present, electrically isolated from the rest of the equipment, possibly by putting tape over its contacts.

The presence of these power cables can, however, affect the measured performance of the EUT. For this reason, they should be made to be "transparent" as far as the testing is concerned. This can be achieved by routing them away from the EUT and down to the either the screen, ground plane or facility wall (as appropriate) by the shortest possible paths. Precautions should be taken to minimize pick-up on these leads (e.g. the leads could be twisted together, loaded with ferrite beads at 0,15 m spacing or otherwise loaded).

Details shall be included in the test report.

## B.2.4 Volume control setting for analogue speech tests

Unless otherwise stated, in all receiver measurements for analogue speech the receiver volume control where possible, should be adjusted to give at least 50 % of the rated audio output power. In the case of stepped volume controls, to volume control should be set to the first step that provides an output power of at least 50 % of the rated audio output power. This control should not be readjusted between normal and extreme test conditions in tests.

### B.2.5 Range length

The range length for all these types of test facility should be adequate to allow for testing in the far-field of the EUT i.e. it should be equal to or exceed:

$$\frac{2(d_1+d_2)^2}{\lambda}$$

where:

- $d_1$  is the largest dimension of the EUT/dipole after substitution (m);
- $d_2$  is the largest dimension of the test antenna (m);
- $\lambda$  is the test frequency wavelength (m).

It should be noted that in the substitution part of this measurement, where both test and substitution antennas are half wavelength dipoles, this minimum range length for far-field testing would be:

2λ

It should be noted in the test report when either of these conditions is not met so that the additional measurement uncertainty can be incorporated into the results.

- NOTE 1: For the fully anechoic chamber, no part of the volume of the EUT should, at any angle of rotation of the turntable, fall outside the "quiet zone" of the chamber at the nominal frequency of the test.
- NOTE 2: The "quiet zone" is a volume within the anechoic chamber (without a ground plane) in which a specified performance has either been proven by test, or is guaranteed by the designer/manufacture. The specified performance is usually the reflectivity of the absorbing panels or a directly related parameter (e.g. signal uniformity in amplitude and phase). It should be noted however that the defining levels of the quiet zone tend to vary.
- NOTE 3: For the anechoic chamber with a ground plane, a full height scanning capability, i.e. 1 m to 4 m, should be available for which no part of the test antenna should come within 1 m of the absorbing panels. For both types of **anechoic chamber**, the reflectivity of the absorbing panels should not be worse than -5 dB.
- NOTE 4: For both the anechoic chamber with a ground plane and the OATS, no part of any antenna should come within 0,25 m of the ground plane at any time throughout the tests. Where any of these conditions cannot be met, measurements should not be carried out.

### B.2.6 Site preparation

The cables for both ends of the test site should be routed horizontally away from the testing area for a minimum of 2 m (unless, in the case both types of **anechoic chamber**, a back wall is reached) and then allowed to drop vertically and out through either the ground plane or screen (as appropriate) to the test equipment. Precautions should be taken to minimize pick up on these leads (e.g. dressing with ferrite beads, or other loading). The cables, their routing and dressing should be identical to the verification set-up.

NOTE: For ground reflection test sites (i.e. anechoic chambers with ground planes and OATS) which incorporate a cable drum with the antenna mast, the 2 m requirement may be impossible to comply with.

Calibration data for all items of test equipment should be available and valid. For test, substitution and measuring antennas, the data should include gain relative to an isotropic radiator (or antenna factor) for the frequency of test. Also, the VSWR of the substitution and measuring antennas should be known.

The calibration data on all cables and attenuators should include insertion loss and VSWR throughout the entire frequency range of the tests. All VSWR and insertion loss figures should be recorded in the log book results sheet for the specific test.

Where correction factors/tables are required, these should be immediately available.

For all items of test equipment, the maximum errors they exhibit should be known along with the distribution of the error e.g.:

- cable loss:  $\pm 0.5$  dB with a rectangular distribution;
- measuring receiver: 1,0 dB (standard deviation) signal level accuracy with a Gaussian error distribution.

At the start of measurements, system checks should be made on the items of test equipment used on the test site.

## B.3 Coupling of signals

## B.3.1 General

The presence of leads in the radiated field may cause a disturbance of that field and lead to additional measurement uncertainty. These disturbances can be minimized by using suitable coupling methods, offering signal isolation and minimum field disturbance (e.g. optical and acoustic coupling).

## B.3.2 Data signals

Isolation can be provided by the use of optical, ultra sonic or infra red means. Field disturbance can be minimized by using a suitable fibre optic connection. Ultra sonic or infra red radiated connections require suitable measures for the minimization of ambient noise.

## B.3.3 Speech and analogue signals

Where an audio output socket is not available an acoustic coupler should be used.

When using the acoustic coupler, care should be exercised that possible ambient noise does not influence the test result.

#### B.3.3.1 Acoustic coupler description

The acoustic coupler comprises a plastic funnel, an acoustic pipe and a microphone with a suitable amplifier. The materials used to fabricate the funnel and pipe should be of low conductivity and of low relative dielectric constant (i.e. less than 1,5):

- the acoustic pipe should be long enough to reach from the EUT to the microphone which should be located in a position that will not disturb the RF field. The acoustic pipe should have an inner diameter of about 6 mm and a wall thickness of about 1,5 mm and should be sufficiently flexible so as not to hinder the rotation of the turntable;
- the plastic funnel should have a diameter appropriate to the size of the loudspeaker in the EUT, with soft foam rubber glued to its edge, it should be fitted to one end of the acoustic pipe and the microphone should be fitted to the other end. It is very important to fix the centre of the funnel in a reproducible position relative to the EUT, since the position of the centre has a strong influence on the frequency response that will be measured. This can be achieved by placing the EUT in a close fitting acoustic mounting jig, supplied by the manufacturer, of which the funnel is an integral part;
- the microphone should have a response characteristic flat within 1 dB over a frequency range of 50 Hz to 20 kHz, a linear dynamic range of at least 50 dB. The sensitivity of the microphone and the receiver audio output level should be suitable to measure a signal to noise ratio of at least 40 dB at the nominal audio output level of the EUT. Its size should be sufficiently small to couple to the acoustic pipe;
- the frequency correcting network should correct the frequency response of the acoustic coupler so that the acoustic SINAD measurement is valid (see IEC 60489-3, appendix F [11]).

### B.3.3.2 Calibration

The aim of the calibration of the acoustic coupler is to determine the acoustic SINAD ratio which is equivalent to the SINAD ratio at the receiver output.

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# History

Document history		
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