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Intelligent Transport Systems (ITS);
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Part 2: Specification of Cooperative Awareness Basic Service

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Foreword

This draft European Standard (EN) has been produced by ETSI Technical Committee Intelligent Transport System (ITS), and is now submitted for the combined Public Enquiry and Vote phase of the ETSI standards EN Approval Procedure.

The present document is part 2 of a multi-part deliverable covering Vehicular Communications; Basic Set of Applications, as identified below:

Part 1: "Functional Requirements";

Part 2: "Specification of Cooperative Awareness Basic Service";

Part 3: "Specification of Decentralized Environmental Notification Basic Service";

The specification of the CA basic service was initially developed by the European Car-to-Car Communication Consortium [i.2]. The service was evaluated by several initiatives such as the C2C-CC demonstration in 2008, ETSI Plugtests events and European projects including PRE-DRIVE C2X, DRIVE C2X, SafeSpot, CVIS, CoVeL, eCoMove, SCOR@F and simTD. These evaluation efforts have provided feedback to ETSI TC ITS.

The present document replaces TS 102 637-2 in whole. It includes improvements and enhancements of the CA basic service specifications in TS 102 637-2 according to the feedback provided by the various initiatives.

Proposed national transposition dates	
Date of latest announcement of this EN (doa):	3 months after ETSI publication
Date of latest publication of new National Standard or endorsement of this EN (dop/e):	6 months after doa
Date of withdrawal of any conflicting National Standard (dow):	18 months after doa

Introduction

Cooperative awareness within road traffic means that road users and roadside infrastructure are informed about each other's position, dynamics and attributes. Road users are all kind of road vehicles like cars, trucks, motorcycles, bicycles or even pedestrians and roadside infrastructure equipment are road signs, traffic lights or barriers and gates. The awareness of each other is the basis for several road safety and traffic efficiency applications with many use cases as described in [i.1]. It is achieved by regular exchange of information among vehicles (V2V, in general all kind of road users) and between vehicles and road side infrastructure (V2I and I2V) based on wireless networks, called V2X network and as such is part of Intelligent Transport Systems (ITS).

The information to be exchanged for cooperative awareness is packed up in the periodically transmitted Cooperative Awareness Message (CAM). The construction, management and processing of CAMs is done by the Cooperative Awareness basic service (CA basic service), which is part of the facilities layer within the ITS communication architecture [1] supporting several ITS applications.

The CA basic service is a mandatory facility for all kind of ITS-Stations (ITS-S), which take part in the road traffic (vehicle ITS-S, personal ITS-S, etc.). The present document focuses on the specifications for CAMs transmitted by all vehicle ITS-Ss participating in the V2X network. Nevertheless, the present document defines the CAM format with flexibility in order to be easily extendable for the support of other types of ITS-Ss or future ITS applications.

The requirements on the performance of the CA basic service, the content of the CAM and the quality of its data elements are derived from the Basic Set of Applications (BSA) as defined in [i.1] and in particular from the road safety applications as defined in [i.8], [i.9], and [i.10].

1 Scope

The present document provides the specifications of the Cooperative Awareness basic service (CA basic service), which is in support of e.g. the BSA road safety application.

This includes definition of the syntax and semantics of the Cooperative Awareness Message (CAM) and detailed specifications on the message handling.

2 References

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

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2.1 Normative references

The following referenced documents are necessary for the application of the present document.

[1] ETSI EN 302 665 (V1.1.1): "Intelligent Transport Systems (ITS); Communications Architecture".

[2] ETSI TS 102 894-2 (V1.1.1): "Intelligent Transport Systems (ITS); Users and applications requirements; Part2: Applications and facilities layer common data dictionary".

[3] SAE J2735 (2009-11-19): "Dedicated Short Range Communications (DSRC) Message Set Dictionary".

NOTE: Available at: http://standards.sae.org/j2735_200911/

[4] Recommendation ITU-T X.691/ISO/IEC 8825-2 (1997-12): "Information technology - ASN.1 encoding rules: Specification of Packed Encoding Rules (PER)".

[5] ETSI EN 302 663 (V1.2.1): "Intelligent Transport Systems (ITS); Access layer specification for Intelligent Transport Systems operating in the 5 GHz frequency band".

2.2 Informative references

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

[i.1] ETSI TR 102 638 (V1.1.1) (2009-06): "Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Definitions".

[i.2] Car2Car Communication Consortium: "Car2Car Communication Consortium Manifesto", Version 1.1. (2007-08).

NOTE: Available at http://www.car-to-car.org/.

[i.3] ETSI TR 102 863 (V1.1.1) (2011-06): "Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Local Dynamic Map (LDM); Rationale for and guidance on standardization".

[i.4] ETSI EN 302 636-3: "Intelligent Transport Systems (ITS); Vehicular Communications; GeoNetworking; Part 3: Network architecture".

[i.5] ETSI EN 302 636-4-1 (V0.0.2): "Intelligent Transport System (ITS); Vehicular communications; GeoNetworking; Part 4: Geographical addressing and forwarding for point-to-point and point-to-multipoint communications; Sub-part 1: Media-Independent Functionality".

[i.6] ETSI TS 102 894-1 (V1.0.2): Intelligent Transport System (ITS); Users & Applications requirements; "Facility layer structure, functional requirements and specifications".

[i.7] ETSI EN 302 636-5-1 (V0.0.4): "Intelligent Transport System (ITS); Vehicular communications; GeoNetworking; Part 5: Transport Protocols; Sub-part 1: Basic Transport Protocol".

[i.8] ETSI TS 101 539-1 (V1.1.1): "Intelligent Transport Systems (ITS); V2X Application; Part 1: Road Hazard Signaling (RHS) application requirements specification".

[i.9] ETSI TS 101 539-2 (V0.0.5): "Intelligent Transport Systems (ITS); V2X Application; Part 2: Intersection Collision Risk Warning (ICRW) Application Specification".

[i.10] ETSI TS 101 539-3 (V0.0.5): "Intelligent Transport Systems (ITS); V2X Application; Part 3: Longitudinal Collision Risk Warning (LCRW) Application Specification".

[i.11] ETSI TS 102 723-5: "Intelligent Transport Systems; OSI cross-layer topics; Part 5: Interface between management entity and facilities layer".

[i.12] ETSI TS 102 723-9: "Intelligent Transport Systems; OSI cross-layer topics; Part 9: Interface between security entity and facilities layer".

[i.13] ETSI TS 102 723-11: "Intelligent Transport Systems; OSI cross-layer topics; Part 11: Interface between networking & transport layer and facilities layer".

[i.14] ETSI TS 102 890-3: "Intelligent Transport Systems (ITS); Facilities layer function; Facility Position and time management".

[i.15] ISO EN 17419: "Intelligent Transport Systems -- Cooperative Systems -- Classification and management of ITS applications in a global context".

[i.16] ETSI TS 102 724 (V1.1.1): "Intelligent Transport Systems (ITS); Harmonized Channel Specifications for Intelligent Transport Systems operating in the 5 GHz frequency band".

[i.17] ETSI TS 103 097 (V1.1.1): "Intelligent Transport Systems (ITS); Security; Security header and certificate formats".

3 Definitions and abbreviations

3.1 Definitions

For the purposes of the present document, the terms and definitions given in EN 302 665 [1], EN 302 663 [5], LDM given in TR 102 863 [i.3] and DE and DF given in SAE J2735 [3] and the following apply:

basic set of applications: group of applications, supported by vehicular communication system

NOTE: The basic set of applications are defined in [i.1].

CA basic service: facility at the ITS-S facilities layer to generate, receive and process the CAM

CAM: ITS facilities layer PDU providing ITS-S status and attributes

CAM protocol: ITS facilities layer protocol that operates the CAM transmission and reception

3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply:

API	Application Programming Interface
ASN.1	Abstract Syntax Notation 1
BSA	Basic Set of Applications
BTP	Basic Transport Protocol
CA	Cooperative Awareness
CAM	Cooperative Awareness Message
DCC	Decentralized Congestion Control
DE	Data Element
DENM	Decentralized Environmental Notification Message
DF	Data Frame
GN	GeoNetworking
HMI	Human Machine Interface
I2V	Infrastructure-to-Vehicle
ID	Identifier
ITS	Intelligent Transportation Systems
ITS-G5A	ITS Frequency band 5,875 GHz to 5,905 GHz dedicated for safety related applications
ITS-S	ITS station
ITS-ST	ITS Station Time
LDM	Local Dynamic Map
MIB	Management Information Base
N&T	Networking & Transport Layer
OSI	Open System Interconnection
PCI	Protocol Control Information
PDU	Packet Data Unit
PER	Packed Encoding Rules
POTI	Position and Time management
SAP	Service Access Point
SHB	Single-Hop Broadcasting
TAI	Temps Atomique International (International Atomic Time)
UTC	Coordinated Universal Time
V2I	Vehicle-to-Infrastructure
V2V	Vehicle-to-Vehicle
V2X	V2V, V2I and/or I2V

4 CA basic service introduction

4.1 Background

Cooperative Awareness Messages (CAMs) are messages exchanged in the ITS network between ITS-Ss to create and maintain awareness of each other and to support cooperative performance in the road network. A CAM contains status and attribute information of the originating ITS-S. The content varies depending on the type of the ITS-S. For vehicle ITS-Ss the status information includes time, position, motion state, activated systems, etc. and the attribute information includes data about the dimension, vehicle type and role in the road traffic, etc. On reception of a CAM the receiving ITS-S is able to gain awareness of the presence, the type and the status of the originating ITS-S. The received information can be used by the receiving ITS-S to support several ITS applications. For example, by comparing the status of the originating ITS-S with its own status, a receiving ITS-S is able to estimate the collision risk with the originating ITS-S and if necessary may inform the driver of the vehicle via the HMI. Multiple ITS applications may rely on the CA basic service. It is assigned to domain application support facilities in [i.6].

Besides the support of applications the awareness of other ITS-S gained by the CA basic service may be used in the networking & transport layer for the position dependent dissemination of messages, e.g. DENM by GeoBroadcasting [i.5]. The generation and transmission of CAM is managed by the CA basic service by implementing the CAM protocol.

4.2 Services provided by CA basic service

The CA basic service is a facilities layer entity that operates the CAM protocol. It provides two services: sending and receiving of CAMs. The CA basic service uses the services provided by the protocol entities of the ITS networking & transport layer to disseminate the CAM.

4.2.1 Sending CAMs

The CAM sending comprises the generation and transmission of CAMs. In the course of CAM generation the originating ITS-S composes the CAM, which is then delivered to the ITS networking & transport layer for dissemination. Generally a short time latency is expected for the CAM dissemination.

The dissemination of CAMs may vary depending on the applied communication system. In the ITS-G5A [5] network CAMs are sent by the originating ITS-S to all ITS-Ss within the direct communication range. This communication range may be influenced in the originating ITS-S by the transmission power.

CAMs are generated periodically with a frequency controlled by the CA basic service in the originating ITS-S. The generation frequency is determined taking into account the change of own ITS-Ss status, e.g. change of position or speed as well as the radio channel load as determined by DCC.

4.2.2 Receiving CAMs

Upon receiving a CAM the CA basic service makes the content of the CAM available to the ITS applications and/or to other facilities within the receiving ITS-S. In one possible implementation, the received CAM data are provided to the Local Dynamic Map (LDM) for further processing and provision to applications.

5 CA basic service functional description

5.1 CA basic service in the ITS architecture

Sending CAMs as part of the CA basic service shall be present in all ITS-S, which take part in the road traffic (vehicle ITS-S, personal ITS-S, etc.).

The CA basic service is a facilities layer entity of the ITS-S architecture as defined in [1]. It may interface with other entities of the facilities layer and with the ITS application layer in order to collect relevant information for CAM generation and to forward the received CAM content for further processing. The CA basic service within the ITS-S architecture and the logical interfaces to other layers and potentially to entities within the facility layer are presented in Figure 1.

In a vehicle ITS-S entities for the collection of data may be the Vehicle Data Provider (VDP) and the Position and Time management (POTI) and for received data the Local Dynamic Map (LDM) as receiving terminal. The VDP is connected with the vehicle network and provides the vehicle status information. The POTI [i.14] provides the position of the ITS-S and time information. The LDM [i.11] is a database for the management of higher layer data in the ITS-S. It may be updated with received CAM data and ITS applications may retrieve information from the LDM for further processing.

The CA basic service interfaces through the NF-SAP with the networking & transport layer (N&T) for exchanging of CAM messages with other ITS-Ss, the SF-SAP with the Security entity to access security services for CAM transmission and CAM reception, the MF-SAP with the Management entity and the FA-SAP with the application layer if received CAM data are provided directly to the applications.

The functionalities of the CA basic service are defined in clause 5.2, the interfaces in Figure 2 are defined in clause 5.3.

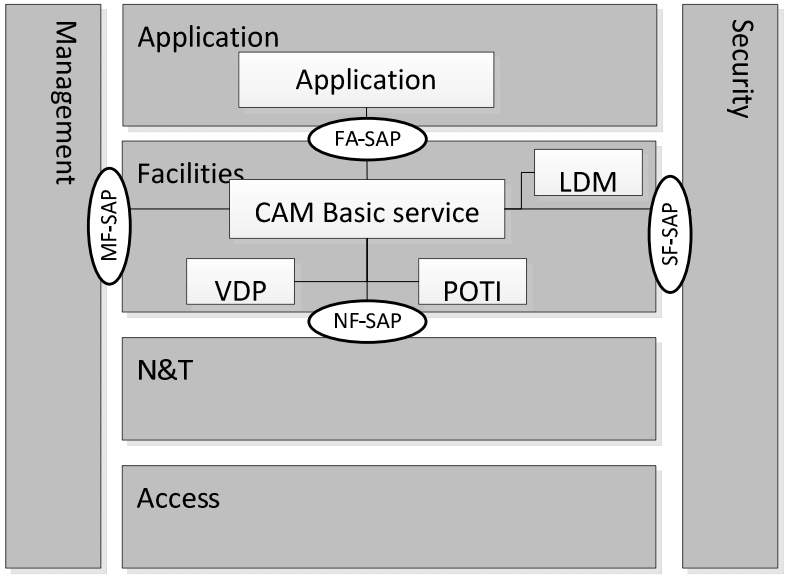

Figure 1: CA basic service within the ITS-S architecture

5.2 CA basic service functional architecture

The CA basic service is part of the Application Support domain of the Facilities Layer according to [i.6]. Figure 2 shows the functional block diagram with the functional blocks of the CA basic service and interfaces to other facilities and layers, which are detailed in the following. The interfaces to other entities and layers are defined in clause 5.3.

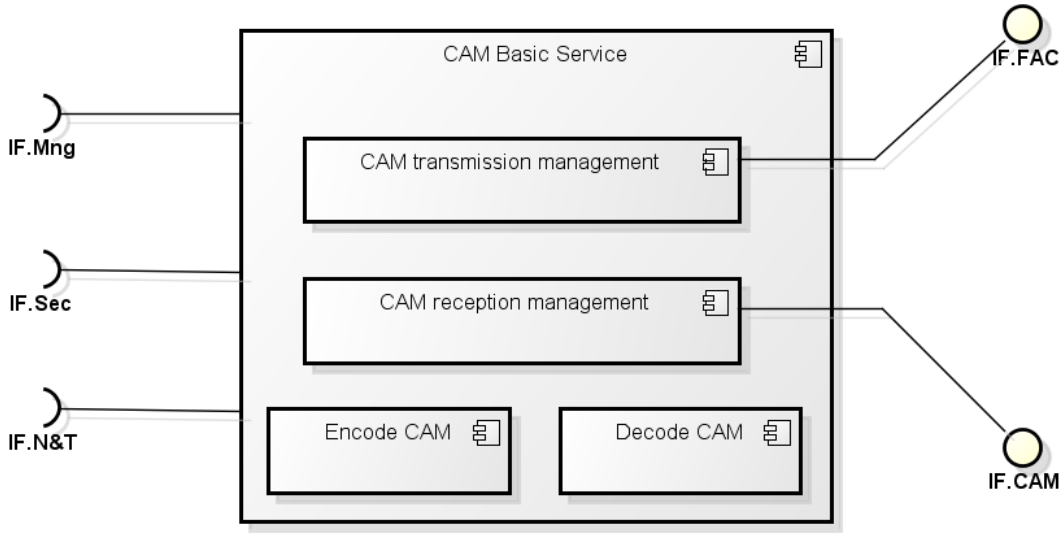

Figure 2: Functional block diagram of the CA basic service

For sending and receiving CAMs, the CA basic service shall provide the following sub-functions:

- Encode CAM:

  This sub-function constructs the CAM according to the format specified in annex A. Always the latest available value of the in-vehicle data shall be included in CAM.

- Decode CAM:

  This sub-function decodes the received CAMs.

- CAM transmission management:

This sub-function implements the protocol operation of the originating ITS-S, as specified in clause C.1, including in particular:

- Activation and termination of CAM transmission operation.
- Determination of the CAM generation frequency.
- Trigger the generation of CAM.

- CAM reception management:

  This sub-function implements the protocol operation of the receiving ITS-S, as specified in clause C.2, including in particular:

  - Trigger the "decode CAM" function at the reception of CAM.
  - Provision of the received CAM information to LDM or ITS applications of the receiving ITS-S.
  - Optionally, checking the information of received CAMs.

5.3 Interfaces of the CA basic service

This clause defines the interfaces between the CA basic service and other entities, layers of the ITS-S as identified in Figure 2.

5.3.1 Interface to ITS applications

An ITS application is an application layer entity that implements the logic for fulfilling one or more ITS use cases. ITS applications are defined in [i.8], [i.9] and [i.10].

For the provision of received data the CA basic service provides the interface IF.CAM to LDM or to ITS application layer, as illustrated in Figure 2.

The interface to the ITS application layer may be implemented as API and data are exchanged between the CA basic service and ITS applications via these API.

In another possible implementation, the interface to the application layer may be implemented as FA-SAP.

NOTE: Specifications of the FA-SAP and the corresponding protocols and APIs are out of scope of the present document.

5.3.2 Interface to data provisioning facilities

For the generation of CAMs, the CA basic service interacts with other facilities layer entities in order to obtain the required data. This set of facilities that provides data for CAM generation is referred to as data provisioning facilities. Data are exchanged between the data provisioning facilities and the CA basic service via the interface IF.FAC

NOTE: Specifications of the interface to the data provisioning facilities and the corresponding protocols are out of scope of the present document.

5.3.3 Interface to the Networking & Transport Layer

The CA basic service exchanges information with ITS Networking & Transport Layer via the interface IF.N&T (Figure 2). A specification of the interface IF.N&T as NF-SAP (Figure 1) is provided in [i.13].

At the originating ITS-S, the CA basic service shall provide the CAM embedded in a Facility-layer Service Data Unit (FL-SDU) together with protocol control information (PCI) [i.7] to the ITS Networking & Transport Layer. At the receiving ITS-S, the ITS networking & transport layer will pass the received CAM to the CA basic service, if available.

The minimum data set that shall be passed between CA basic service and ITS Networking & Transport Layer for the originating and receiving ITS-S is specified in Table 1.

Table 1: Data passed between CA basic service and the ITS Networking & Transport layer

Category	Data	Data requirement	Mandatory/Optional
Data passed from the CA basic service to the ITS networking & transport layer	CAM	{*cam*} as specified in annex A	Mandatory
	PCI	Depending on the protocol stack applied in the networking and transport layer as specified in clauses 5.3.3.1 and 5.3.3.2	Mandatory
Data passed from the ITS networking & transport layer	Received CAM	{*cam*} as specified in annex A	Mandatory

5.3.3.1 Interface to the GeoNetworking/BTP stack

A CAM may rely on the services provided by the GeoNetworking/BTP stack. If this stack is used, the GN packet transport type Single-Hop Broadcasting (SHB) shall be used. In this scenario only nodes in direct communication range may receive the CAM.

PCI being passed from CA basic service to the GeoNetworking/BTP stack shall comply with Table 1 and Table 2.

Table 2: PCI from CA basic service to GeoNetworking/BTP at the originating ITS-S

Category	Data	Data requirement	Mandatory/Optional
Data passed from the CA basic service to GeoNetworking/BTP	Message type	*{cam.header.messageID}* as specified in annex B.	Mandatory
	BTP type	BTP header type B ([i.7] clause 7.2.2).	Optional The data shall be passed if the value is not provided by the ITS-S configuration e.g. defined in a Management Information Base (MIB) or if the value is different from the default value as set in the MIB.
	Destination port	As specified in [i.7] (see note)	Optional The data shall be passed if the value is not provided by the ITS-S configuration e.g. defined in a Management Information Base (MIB) or if the value is different from the default value as set in the MIB.
	Destination port info	Reserved for future use.	Optional The data shall be passed if the value is not provided by the ITS-S configuration e.g. defined in a Management Information Base (MIB) or if the value is different from the default value as set in the MIB.
	GN Packet transport type	GeoNetworking SHB.	Optional The data shall be passed if the value is not provided by the ITS-S configuration e.g. defined in a Management Information Base (MIB) or if the value is different from the default value as set in the MIB.
	Traffic Class	As defined in [i.5].	Mandatory
	GN Maximum packet lifetime	Shall not exceed 1 s.	Mandatory
	Length	Length of the CAM.	Mandatory
NOTE: When a global registration authority for ITS application [i.15] is operational, the BTP destination port registered with this authority shall be used.			

5.3.3.2 Interface to the IPv6 stack and the combined IPv6/GeoNetworking stack

A CAM may use the IPv6 stack or the combined IPv6/GeoNetworking stack for CAM dissemination [i.4].

NOTE: The transmission of CAM over the IPv6 stack is out of scope of the present document.

When the CAM dissemination makes use of the combined IPv6/GeoNetworking stack, the interface between the CA basic service and the combined IPv6/GeoNetworking stack may be identical to the interface between the CA basic service and IPv6 stack.

5.3.4 Interface to the Management entity

The CA basic service may exchange primitives with management entity of the ITS-S via the MF-SAP interface (Figure 1). In an originating ITS-S the CA basic service gets information for setting the T_GenCam_DCC from the management entity defined in clause 6.1.3 via the IF.MnG interface (Figure 2).

NOTE 1: A specification of the MF-SAP and a list of primitives exchanged with the management layer are provided in [i.11].

NOTE 2: Specifications of the MF-SAP and the corresponding protocol are out of scope of the present document.

5.3.5 Interface to the Security entity

The CA basic service may exchange primitives with the Security entity of the ITS-S via the SF-SAP interface (Figure 1) using the IF.SEC interface provided by the Security entity (Figure 2).

NOTE 1: A specification of a list of primitives exchanged with the security layer is provided in [i.12].

NOTE 2: Specifications of the SF-SAP and the corresponding protocol are out of the scope of the present document.

6 CAM dissemination

6.1 CAM dissemination concept

6.1.1 CAM dissemination requirements

Point-to-multipoint communication shall be used for transmitting CAMs [i.4]. In case ITS G5 is used for CAM dissemination, the control channel (G5-CCH) as specified in [5] shall be used. The CAM shall be transmitted only from the originating ITS-S in a single hop to the receiving ITS-Ss located in the direct communication range of the originating ITS-S. A received CAM shall not be forwarded to other ITS-Ss.

6.1.2 CA basic service activation and termination

CA basic service activation may vary for different types of ITS-S, e.g. vehicle ITS-S, Road side ITS-S, Personal ITS-S. As long as the CA basic service is active, the CAM generation shall be triggered and managed by the CA basic service.

For vehicle ITS-S, the CA basic service shall be activated with the ITS-S activation. The CA basic service shall be terminated when the ITS-S is deactivated.

6.1.3 CAM generation frequency management

The CAM generation frequency is managed by the CA basic service, it defines the time interval between two consecutive CAM generations. Considering the requirements as specified in [i.8], [i.9] or [i.10] the upper and lower limits of the transmission interval are set as following:

- The CAM generation interval shall not be inferior to *T_GenCamMin* = 100 ms. This corresponds to the CAM generation rate of 10 Hz.
- The CAM generation interval shall not be superior to *T_GenCamMax* = 1 000 ms. This corresponds to the CAM generation rate of 1 Hz.

Within these limits the CAM generation shall be triggered depending on the originating ITS-S dynamics and the channel congestion status. In case the dynamics of the originating ITS-S lead to a reduced CAM generation interval, this interval should be maintained for a number of consecutive CAMs. The conditions for triggering the CAM generation shall be checked repeatedly every *T_CheckCamGen. T_CheckCamGen* shall be equal or lower than *T_GenCamMin*.

The parameter *T_GenCam_Dcc* shall provide the minimum time interval between two consecutive CAM generations in order to reduce the CAM generation according to the requirements of the Decentralized Congestion Control (DCC) as specified in [i.16]. This allows to adapt the CAM generation rate to the remaining capacity of the radio channel in case of channel congestion. The parameter *T_ GenCam_Dcc* shall be provided by the management entity as specified in clause 5.3.4. in the unit of milliseconds. The value range of T_GenCam_DCC shall be limited to *T_GenCamMin* ≤ T_GenCam_DCC ≤ T_GenCamMax. If the management entity provides this parameter with a value above T_GenCamMax, T_GenCam_DCC shall be set to T_GenCamMax and if the value is below T_GenCamMin or if this parameter is not provided, the *T_GenCam_Dcc* shall be set to *T_GenCamMin.*

NOTE: T_GenCam_Dcc corresponds to T_{off} in the DCC_Profile DP2 standardized in [i.16].

The parameter T_GenCam represents the currently valid upper limit of the CAM generation interval. The default value of T_GenCam shall be T_GenCamMax. T_GenCam shall be set to the time elapsed since the last CAM generation, if a CAM is triggered due to condition 1. After triggering the number of N_GenCam consecutive CAMs due to condition 2, T_GenCam shall be set to T_GenCamMax. The value of the parameter N_GenCam can be dynamically adjusted according to some environmental conditions. The default and maximum value of N_GenCam shall be 3.

In detail the CAM generation trigger conditions shall be as following:

1) The time elapsed since the last CAM generation is equal or larger than *T_GenCam_Dcc* and one of the following ITS-S dynamics related conditions is given:

   - the absolute difference between current direction of the originating ITS-S (towards North) and direction included in previous CAM exceeds 4°;
   - the current position and position included in previous CAM exceeds 4 m;
   - the absolute difference between current speed and speed included in previous CAM exceeds 0,5 m/s.

2) The time elapsed since the last CAM generation is equal or larger than *T_GenCam.* and equal or larger than *T_GenCam_Dcc.*

If one of the above 2 conditions is satisfied, a CAM shall be generated immediately.

When a CAM needs to be generated, the CA basic service shall construct the mandatory containers as specified in clause 7.1. The mandatory containers mainly include the high dynamic information of the originating ITS-S, as *{CAM.cam.basicContainer}* and *{CAM.cam.camParameters.highFrequencyContainer}* as specified in annex A. Optionally, a CAM may include optional data. The optional data mainly includes the status of the originating ITS-S which is less dynamic, as *{CAM.cam.camParameters.lowFrequencyContainer}* and specific information as included for a specific type of originating ITS-S, as *{CAM.cam.camParameters. specialVehicleContainer}* as specified in annex A.

The low frequency container shall be included in the first CAM generation since the CA basic service activation. After that the low frequency container of CAM shall be included if time elapsed since the generation of the last CAM with the low frequency container generation is equal or larger than 500 ms.

The special-vehicle container shall be included in the first CAM generation since the CA basic service activation. After that if a special vehicle container shall be provided by the CAM of an originating ITS-S, it shall be included, if the time elapsed since the generation of the last CAM with a special vehicle container is equal or larger than 500 ms.

6.1.4 CAM time requirement

Besides the CAM generation frequency the time required for the CAM generation and the timeliness of the data taken for the message construction are decisive for the applicability of Data in the receiving ITS-Ss. In order to ensure proper interpretation of CAMs received from different ITS-Ss each CAM shall be time-stamped.

NOTE: An acceptable time synchronization between the different ITS-Ss is expected.

6.1.4.1 CAM generation time

Time required for a CAM generation shall be less than 50 ms. The time required for a CAM generation refers to the time difference between time at which CAM generation is triggered and time at which the CAM is delivered to networking transport layer.

NOTE: The age of the CAM data is out of scope of the present document.

6.1.4.2 CAM Time stamp

The following requirements shall apply:

- Time stamp of a CAM shall be that of the position provided in the CAM.
- The difference between CAM generation time and time stamp shall be inferior to 32 767 ms.

NOTE 1: This requirement is set to avoid time stamp wrap-around situation. The time stamp is specified in annex A.

NOTE 2: For the correct timely interpretation, received CAMs from different ITS-Ss need to be placed in the right order. Given the maximum repetition rate of 10 Hz and that both originating and receiving ITS-Ss have their own ITS-S time (ITS-ST) variation (ITS-SΔT), for each ITS-S, ITS-ST shall comply to: ITS-SΔT n < 0,025 s (or ± 0,012 s). The specification of the ITS-ST precision and synchronization is out of scope of the present document.

6.2 CAM dissemination constraints

6.2.1 General Confidence Constraints

Several data elements of the CAM may vary with regard to accuracy or confidence. For these data elements data frames are specified providing data element together with confidence information as presented in annex B.

6.2.2 General security constraints

Security Constraints for CAM are described in [i.17].

6.2.3 General priority constraints

The priority constraint is given by the Traffic Class as specified within [i.5].

7 CAM Format Specification

7.1 General Structure of a CAM PDU

A CAM is composed of a common ITS PDU header and multiple containers, which together constitute a CAM.

The ITS PDU header is a common header that includes the information of the protocol version, the message type and the ITS-S ID of the originating ITS-S.

For vehicle ITS-Ss a CAM shall consist of at least a basic container and a high frequency container. In addition a low frequency container and other special containers may be added:

- The basic container includes basic information related to the originating ITS-S.
- The high frequency container contains highly dynamic information of the originating ITS-S.
- The low frequency container contains static ant not highly dynamic information of the originating ITS-S.

The special vehicle container contains information specific to the role of the vehicle ITS-S within the road traffic.

The general structure of a CAM is illustrated in Figure 3.

Each container is composed of a sequence of optional or mandatory data elements (DE) and/or data frames (DF). DEs and DFs are mandatory unless specified otherwise. The present document provides CAM content specifications for vehicle ITS-Ss. CAM format and content specifications for other types of ITS-Ss is expected to be added in the future.

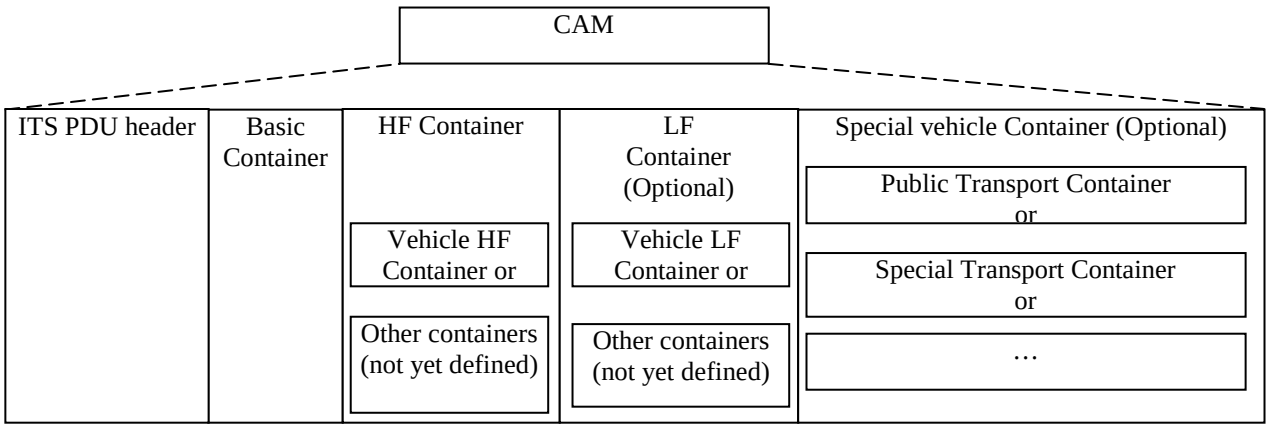

Figure 3: General structure of a CAM

7.1.1 ITS PDU header

The ITS PDU header shall be as specified in [2]. Detailed data presentation rules of the ITS PDU header in the context of CAM shall be as specified in annex B.

7.1.2 Basic container

The basic container provides basic information of the originating ITS-S:

- type of the originating ITS-S;
- the latest geographic position of the originating ITS-S as obtained by the CA basic service at the CAM generation.

The basic container shall be present for CAM generated by all ITS-Ss implementing the CA basic service.

Detailed data presentation rules shall be as specified in annex B.

7.1.3 Vehicle ITS-S containers

All CAMs generated by a vehicle ITS-S shall include at least a high frequency vehicle (Vehicle HF) container, and optionally a low frequency vehicle (Vehicle LF) container. The Vehicle HF container contains all fast-changing (dynamic) status information of the vehicle ITS-S such as heading or speed. The Vehicle LF container contains static or slow-changing vehicle data like the dimension of the vehicle or the status of the exterior lights.

Vehicle ITS-Ss which have a specific role in road traffic like public transport, shall provide further status information in special vehicle containers according to the specification in annex A. The vehicle role is indicated by the data element *{CAM.cam.basicVehicleContainerLowFrequency.vehicleRole}* as specified in annex A. Table 3 shows the list of specified vehicle roles and the related special vehicle container.

Table 3: Special vehicle container according to the vehicle role

Vehicle role description	**CAM data requirement** Value of *{CAM.cam.basicVehicleContainerLowFrequency.vehicleRole} shall be set to*	**Special vehicle container** represented as
public transport when the originating ITS-S is a public transport vehicle in operation	publicTransport(1)	public transport container,*{CAM.cam.specialVehicleContainer.publicTransportContainer}*
special transport when the originating ITS-S is a special transport vehicle in operation (e.g. heavy load)	specialTransport(2)	special transport container, *{CAM.cam.specialVehicleContainer.specialTransportContainer}*
dangerous goods when the originating ITS-S is transporting dangerous goods	dangerousGoods(3)	dangerous goods container, *{CAM.cam.specialVehicleContainer.dangerousGoodsContainer}*
road work when the originating ITS-S is operating road work tasks	roadWork(4)	road work container, *{CAM.cam.specialVehicleContainer.roadWorksContainer }*
Rescue when the originating ITS-S is realizing a rescue operation	rescue(5)	rescue container, *{CAM.cam.specialVehicleContainer. rescueContainer}*
Emergency when the originating ITS-S is an emergency vehicle in operation	emergency(6)	emergency container, represented as *{CAM.cam.specialVehicleContainer.emergencyContainer*
Safety car when the originating ITS-S is accompanying a special transport vehicle, e.g. vehicle following overloaded truck	safetyCar(7)	Safety car container, represented as *{CAM.cam.specialVehicleContainer. safetyCarContainer}*

7.2 CAM format and coding rules

7.2.1 Common data dictionary

The CAM format makes use of the common data dictionary as defined in [2].

Where applicable, DEs and DFs that are not defined in the present document shall be imported from the common data dictionary as specified in [2].

NOTE: Detailed descriptions of all DEs and DFs in the context of CAM are presented in the annex B of the present document.

7.2.2 CAM data presentation

The CAM format is presented in ASN.1. Unaligned packed encoding rules (PER) as defined in [4] shall be used for CAM encoding and decoding.

The ASN.1 representation of CAM shall be as specified in the annex A of the present document.

7.2.3 Future CAM extension

The CAM format as presented in ASN.1 considers a possible extension with additional container. The presence of additional container is indicated with a version number in the CAM PDU description. The current CAM specification shall be assigned to the version number 1. A higher version number shall be assigned to any future extension of the CAM.

Annex A (normative): ASN.1 specification of CAM

The present annex provides the ASN.1 specification of CAM.

NOTE: Some of the optional data elements and data frames conditions for the availability are specified in annex B.

```
CAM-PDU-Descriptions {
 itu-t (0) identified-organization (4) etsi (0) itsDomain (5) wg1 (1) en (302637) cam (2) version
(1)
}

DEFINITIONS AUTOMATIC TAGS ::=

BEGIN

IMPORTS
   ItsPduHeader, CauseCode, ReferencePosition, AccelerationControl, Curvature,
CurvatureCalculationMode, Heading, LaneNumber, PtPriority, EmergencyPriority, PtLineNumber,
PtScheduleDelay, EmbarkationStatus, Speed, DriveDirection, LongitudinalAcceleration,
LateralAcceleration, VerticalAcceleration, StationType, ExteriorLights, DangerousGoodsBasic,
SpecialTransportType, LightBarSirenInUse, VehicleRole, VehicleLength, VehicleWidth, PathHistory,
RoadworksSubCauseCode, ClosedLanes, TrafficRule, SpeedLimit, SteeringWheelAngle FROM ITS-Container {
 itu-t (0) identified-organization (4) etsi (0) itsDomain (5) wg1 (1) ts (102894) cdd (02) version
(1)
};


--  The root data frame for cooperative awareness messages

CAM ::= SEQUENCE {
    header  ItsPduHeader,
    cam CoopAwareness

}


 CoopAwareness ::= SEQUENCE {
   generationDeltaTime GenerationDeltaTime,
   camParameters CamParameters
 }

 CamParameters ::= SEQUENCE {
  basicContainer BasicContainer,
  highFrequencyContainer HighFrequencyContainer,
  lowFrequencyContainer LowFrequencyContainer OPTIONAL,
  specialVehicleContainer SpecialVehicleContainer OPTIONAL,
  ...
 }

 HighFrequencyContainer ::= CHOICE {
  basicVehicleContainerHighFrequency BasicVehicleContainerHighFrequency,
  emptyRSUContainerHighFrequency EmptyRSUContainerHighFrequency,
  ...  -- further type specific RSU containers might be added as extensions
 }

 LowFrequencyContainer ::= CHOICE {
  basicVehicleContainerLowFrequency BasicVehicleContainerLowFrequency,
  ...  -- further type specific RSU containers might be added as extensions
 }

 SpecialVehicleContainer ::= CHOICE {
  publicTransportContainer PublicTransportContainer,
  specialTransportContainer SpecialTransportContainer,
  dangerousGoodsContainer DangerousGoodsContainer,
  roadWorksContainerBasic RoadWorksContainerBasic,
  rescueContainer RescueContainer,
  emergencyContainer EmergencyContainer,
  safetyCarContainer SafetyCarContainer,
  ...
 }
```

```
BasicContainer ::= SEQUENCE {
 stationType StationType,
 referencePosition ReferencePosition
}

BasicVehicleContainerHighFrequency ::= SEQUENCE {
 heading Heading,
 speed Speed,
 driveDirection DriveDirection,
 longitudinalAcceleration LongitudinalAcceleration,
 curvature Curvature,
 curvatureCalculationMode CurvatureCalculationMode,
 yawRate YawRate,
 vehicleLength VehicleLength,
 vehicleWidth VehicleWidth,
 performanceClass PerformanceClass OPTIONAL,
 accelerationControl AccelerationControl OPTIONAL,
 laneNumber LaneNumber OPTIONAL,
 steeringWheelAngle SteeringWheelAngle OPTIONAL,
 lateralAcceleration LateralAcceleration OPTIONAL,
 verticalAcceleration VerticalAcceleration OPTIONAL
}

BasicVehicleContainerLowFrequency  ::= SEQUENCE {
 vehicleRole VehicleRole,
 exteriorLights ExteriorLights,
 pathHistory PathHistory
}

PublicTransportContainer ::= SEQUENCE {
 embarkationStatus EmbarkationStatus,
 ptActivation PtActivation OPTIONAL
}

SpecialTransportContainer ::= SEQUENCE {
 specialTransportType SpecialTransportType,
 lightBarSirenInUse LightBarSirenInUse
}

DangerousGoodsContainer ::= SEQUENCE {
 dangerousGoodsBasic DangerousGoodsBasic
}

RoadWorksContainerBasic ::= SEQUENCE {
 roadworksSubCauseCode RoadworksSubCauseCode OPTIONAL,
 lightBarSirenInUse LightBarSirenInUse,
 closedLanes ClosedLanes OPTIONAL
}

RescueContainer ::= SEQUENCE {
 lightBarSirenInUse LightBarSirenInUse,
 emergencyPriority EmergencyPriority OPTIONAL
}

EmergencyContainer ::= SEQUENCE {
 lightBarSirenInUse LightBarSirenInUse,
 incidentIndication CauseCode OPTIONAL,
 emergencyPriority EmergencyPriority OPTIONAL
}

SafetyCarContainer ::= SEQUENCE {
 lightBarSirenInUse LightBarSirenInUse,
 incidentIndication CauseCode OPTIONAL,
 trafficRule TrafficRule OPTIONAL,
 speedLimit SpeedLimit OPTIONAL
}

EmptyRSUContainerHighFrequency ::= NULL

GenerationDeltaTime ::= INTEGER { oneMilliSec(1) } (0..65535)

END
```

Annex B (normative): Description for data elements and data frames

B.1 header

Description	The ITS PDU header of CAM. This DF include the protocol version of CAM *protocolVersion*, CAM message type identifier *messageID* and station identifier *stationID* of the originating ITS-S. The DE *protocolVersion* is used to select the appropriate protocol decoder at the receiving ITS-S. This DE *messageID* should be harmonized with other V2X message identifier definition.
Data setting and presentation requirements	For the present document, the value of the DE *protocolVersion* shall be set to 1. For CAM, the DE *messageID* shall be set to cam(2). This DF shall be presented as specified in [2] *ItsPduHeader.*

B.2 cam

Description	CAM payload. It includes the time stamp of CAM, mandatory containers basic container and high frequency container, and optional containers low frequency container and special vehicle container. Other containers may be added in the future.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.3 generationDeltaTime

Description	For the usage of the present document, it shall correspond to the time of the reference position in the CAM. The value of the DE shall be wrapped to 65 536. This value shall be set as the remainder of the corresponding value of TimestampIts divided by 65 536 as below: *generationTime* = TimestampIts mod 65 536 TimestampIts represents an integer value of the TAI time in milliseconds since UTC midnight 2004 as defined in [2].
Data setting and presentation requirements	The DE shall be presented as specified in annex A.

B.4 camParameters

Description	The ensemble of CAM mandatory and optional containers. Other containers may be added in the future.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.5 basicContainer

Description	The mandatory basic container of CAM.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.6 highFrequencyContainer

Description	The mandatory high frequency container of CAM. In the scope of the present document, only vehicle high frequency container is defined. Other types of high frequency container (e.g. road side ITS-S) might be added in the future.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.7 lowFrequencyContainer

Description	The optional low frequency container of CAM. Within the scope of the present document, only vehicle low frequency container is defined. Other types of low frequency container (e.g. road side ITS-S) might be added in the future.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.8 specialVehicleContainer

Description	The optional special container of CAM. It shall be present according to the rules as specified in clause 6.1.3. The content of the container shall be set according to the value of the DE *vehicleRole* as specified in Table 3. Other types of special vehicle container might be added in the future.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.9 basicVehicleContainerHighFrequency

Description	The mandatory high frequency container of CAM when the type of the originating ITS-S is vehicle ITS-S.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.10 basicVehicleContainerLowFrequency

Description	The optional low frequency container of CAM when the type of the originating ITS-S is vehicle ITS-S. It shall be present according to the rules as specified in clause 6.1.3.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.11 publicTransportContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to publicTransport(1) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.12 specialTransportContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to specialTransport(2) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.13 dangerousGoodsContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to dangerousGoods(3) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.14 roadWorksContainerBasic

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to roadWork(4) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.15 rescueContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to rescue(5) his container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.16 emergencyContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to emergency(6) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.17 safetyCarContainer

Description	The optional container of CAM included in the special vehicle container. It may be present if the CA basic service of the originating ITS-S is configured to transmit the included content. If DE *vehicleRole* is set to safetyCar(7) this container shall be present.
Data setting and presentation requirements	This DF shall be presented as specified in annex A.

B.18 stationType

Description	Station type of the originating ITS-S.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *StationType*. The value of this DE shall be set to one out of the values 3 to 10, because the current message format as defined in annex A is focusing on vehicle ITS-Ss.

B.19 referencePosition

Description	Position and position accuracy measured at the reference point of the originating ITS-S. The measurement time shall correspond to the *generationDeltaTime.* If the *stationType* of the originating ITS-S is set to one out of the values 3 to 11 the reference point shall be the ground position of the middle point of the front side of the bounding box of the vehicle. The *positionConfidenceEllipse* provides the accuracy of the measured position with the 95 % confidence level. Otherwise, the *positionConfidenceEllipse* shall be set to unavailable. If semiMajorOrientation is set to 0° North, then the semiMajorConfidence corresponds to the position accuracy in the North direction, while the semiMinorConfidence corresponds to the position accuracy in the East direction. This definition implies that the semiMajorConfidence might be smaller than the semiMinorConfidence.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *ReferencePosition.*

B.20 performanceClass

Description	The DE performanceClass characterizes the maximum age of the CAM data elements with regard to the generationDeltaTime. This DE is optional, it shall be present, if the originating ITS-S is not able to meet the highest performance class specified in [2]. The specification of the performanceClass may be extended considering some other performance types e.g. positioning system type being used.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *PerformanceClass.*

B.21 heading

Description	Heading of the vehicle movement of the originating ITS-S with regards to the true north. The confidence of the heading shall correspond to the accuracy of the measured vehicle heading with a confidence level of 95 %. Otherwise, the value of the *headingConfidenc*e shall be set to unavailable.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *Heading.*

B.22 speed

Description	Vehicle speed and confidence of the *vehiclespeed* value of the originating ITS-S. The confidence of the *speed* shall corresponds to the accuracy of the measured vehicle speed with a confidence level of 95 %. Otherwise, the value of the *vehicleSpeedConfidence* shall be set to unavailable.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *Speed.*

B.23 vehicleRole

Description	The role of the vehicle ITS-S that originates the CAM. The setting rules for this value are out of the scope of the present document.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *VehicleRole.*

B.24 laneNumber

Description	The DE laneNumber of the *referencePosition* of a vehicle, counted from the outside border of the road, in the direction of the traffic flow. This DE is optional; it shall be present when the data is available at the originating ITS-S. (See note)
Data setting and presentation requirements	The DE shall be presented as specified in [2] *LaneNumber.*
NOTE: Additional information is needed to unambiguously identify the lane number and to allow the correlation to a map.	

B.25 driveDirection

Description	Drive direction (Forward or Backward) of the vehicle of the originating ITS-S.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *DriveDirection.*

B.26 longitudinalAcceleration

Description	Vehicle longitudinal acceleration of the originating ITS-S. It shall include the measured vehicle longitudinal acceleration and its accuracy value with the confidence level of 95 %. Otherwise, the *longitudinalAccelerationConfidence* shall be set to unavailable.
Data setting and presentation requirements	The data element shall be presented as specified in [2] *LongitudinalAcceleration.*

B.27 accelerationControl

Description	Current status of the vehicle mechanisms controlling the longitudinal movement of the vehicle ITS-S that originates the CAM.
Data setting and presentation requirements	The data element shall be presented as specified in [2] *AccelerationControl.*

B.28 lateralAcceleration

Description	Vehicle lateral acceleration of the originating ITS-S. It shall include the measured vehicle lateral acceleration and its accuracy value with the confidence level of 95 %. This DE is optional; it shall be present if the data is available at the originating ITS-S.
Data setting and presentation requirements	The presentation and data setting rules shall be as specified in [2] *LateralAcceleration.*

B.29 verticalAcceleration

Description	Vertical Acceleration as measured at the vehicle ITS-S that originates the CAM. This DE is optional; it shall be present if the data is available at the originating ITS-S.
Data setting and presentation requirements	The presentation and data setting rules shall be as specified in [2] *VerticalAcceleration.*

B.30 embarkationStatus

Description	This DE is included in *publicTransportContainer*. It indicates whether the passenger embarkation is ongoing currently.
Data setting and presentation requirements	The presentation and data setting rules shall be as specified in [2] *EmbarkationStatus.* It shall be set to TRUE when the embarkation is ongoing. Otherwise, it shall be set to FALSE.

B.31 curvature

Description	This DF is related to the actual trajectory of the vehicle. It includes: • *curvatureValue* denoted as inverse of the vehicle current curve radius and the turning direction of the curve with regards to the driving direction of the vehicle. Positive values indicates a right turn curve to the right of the vehicle ITS-S that originates the CAM. • *curvatureConfidence* denoted as the deviation percentage of the provided curvatureValue.
Data setting and presentation requirements	The DF shall be presented as specified in [2] *Curvature.*

B.32 curvatureCalculationMode

Description	Flag indicating whether vehicle yaw-rate is used in the calculation of the curvature of the vehicle ITS-S that originates the CAM.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *CurvatureCalculationMode.*

B.33 yawRate

Description	This DF includes: • *yawRateValue* denotes the vehicle rotation around the center of mass of the empty vehicle. The leading sign denotes the direction of rotation. The value is negative if the motion is clockwise when viewing from the top. • *yawRateConfidence* denotes the confidence level for the 95 % confidence level for the measured *yawRateValue.* Otherwise, the value of *yawRateConfidence* shall be set to unavailable.
Data setting and presentation requirements	The DF shall be presented as specified in [2] *YawRate.*

B.34 steeringWheelAngle

Description	Steering wheel angle and accuracy as measured at the vehicle ITS-S that originates the CAM. It shall include the following information: • *steeringWheelAngleValue* denotes Steering wheel angle as measured at the vehicle ITS-S that originates the CAM. • *steeringWheelAngleConfidence* denotes the accuracy of the measured *steeringWheelAngleValue* for the 95 % confidence level. Otherwise, the value of *steeringWheelAngleValue* shall be set to unavailable.
Data setting and presentation requirements	This DF shall be presented as specified in [2] *SteeringWheelAngle.*

B.35 vehicleLength

Description	This DF includes: • *vehicleLengthValue*: Length, measured as distance between the middle point of front bumper and middle point of vehicle back, of the vehicle ITS-S that originates the CAM. If a trailer is attached and the length is known the *vehicleLengthValue* shall include the trailer length. • *vehicleLengthConfidenceIndication*: indication of whether trailer is detected to be present and whether the length of the trailer is known.
Data setting and presentation requirements	The DF shall be presented as specified in *[2] VehicleLength.*

B.36 vehicleWidth

Description	Vehicle width, measured of the vehicle ITS-S that originates the CAM, including side mirrors.
Data setting and presentation requirements	The DE shall be presented as specified in *[2] VehicleWidth.*

B.37 exteriorLights

Description	Status of the most important exterior lights switches of the vehicle ITS-S that originates the CAM.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *ExteriorLights.*

B.38 pathHistory

Description	The DF consists of a list of *PathPoint*, which represents the vehicle's recent movement over some past time and/or distance. In the present document up to 23 *PathPoint* may be added in this DF. The generation of each *pathPoint* shall be as specified in [3].
Data setting and presentation requirements	The *PathPoint* closest to the current position of originating ITS-S shall be put as the first point, it presents a offset delta position with regards to the *referencePosition*. Other *PathPoints* shall be structured in ascending order according to the distance to the *referencePosition* along the path. Each *PathPoint* presents a offset delta position with regards to the previous *PathPoint*. For CAM the DE *PathDeltaTime* shall present the time difference when two consecutive *PathPoint* are measured. The DF shall be presented as specified in [2] *PathHistory.*

B.39 ptActivation

Description	This DF is used by public transport vehicles for controlling traffic lights, barriers, bollards, etc.
Data setting and presentation requirements	The DF shall be presented as specified in [2] *PtActivation.*

B.40 specialTransportType

Description	This DE is included in the *specialTransportContainer*. It indicates whether the originating ITS-S is mounted on a special transport vehicle with heavy or oversized load or both.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *SpecialTransportType.*

B.41 dangerousGoodsBasic

Description	This DE is included in *dangerousGoodsContainer*. Identifier of the Dangerous Goods type transported by vehicle that originates the CAM.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *DangerousGoodsBasic.*

B.42 roadworksSubCauseCode

Description	This DE is included in *roadWorksContainerBasic*, in case the originating ITS-S is mounted to a vehicle ITS-S participating to roadwork. It provides information on the type of roadwork that is currently undertaking. This DE is optional; it shall be present if the data is available in originating ITS-S.
Data setting and presentation requirements	The data element shall be presented as specified in [2] *RoadworksSubCauseCode.*

B.43 closedLanes

Description	This DE is included in *roadWorksContainerBasic* in case the originating ITS-S is mounted to a vehicle ITS-S participating to roadwork. It provides information about the opening/closure status of the lanes ahead. Lanes are counted from the outside boarder of the road. If a lane is closed to traffic, the corresponding bit shall be set to 1. This DE is optional; it shall be present if the data is available in the originating ITS-S.
Data setting and presentation requirements	The DE shall be presented as specified in *[2] ClosedLanes.*

B.44 trafficRule

Description	This DE is included in *SafetyCarContainer*, it indicates whether the overtaking is allowed to bypass a safety car that originates CAM. This DE is optional; it shall be present if the data is available in originating ITS-S.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *TrafficRule.*

B.45 speedLimit

Description	This DE is included in SafetyCarContainer; it indicates whether a speed limit is applied to vehicles following the safety car. This DE is optional; it shall be present if the data is available in originating ITS-S.
Data setting and presentation requirements	The data element shall be presented as specified in [2] *SpeedLimit.*

B.45 lightBarSireneInUse

Description	This DE indicates whether lightbar or siren is in use by the vehicle at the originating ITS-S . This DE is optional; it shall be present if the data is available at originating ITS-S.
Data setting and presentation requirements	The DE shall be presented as specified in [2] *LightBareSinreInUse.*

B.46 incidentIndication

Description	This DF is included in *emergencyContainer* and *safetyCarContainer* in case the originating ITS-S is mounted on a vehicle operating some emergency missions or safety mission (e.g. protecting convey of dangerous goods). It describe the event type of the emergency or safety mission. This DF is optional; it shall be present when the data is available at the originating ITS-S
Data setting and presentation requirements	The DF shall be presented as specified in [2] *CauseCode.*

B.47 emergencyPriority

Description	Right of way indicator of the vehicle ITS-S that originates the CAM PDU. It could be originated by authorized vehicles only, e.g. rescue, police, etc.
Data setting and presentation requirements	The data element shall be presented as specified in [2] *EmergencyPriority.*

Annex C (informative): Protocol operation of the CA basic service

Annex C provides a timer controlled approach for the protocol operation as one potential variant compliant to the present document. It is distinguished between the originating ITS-S operation and the receiving ITS-S operation considered in the following clauses.

Following specification of the protocol operation is organized in three parts:

1) Protocol data setting rules specify the setting of the relevant data elements used by the protocol.

2) The general protocol operation specifies the sequence of protocol operations.

3) Exception handling specifies additional protocol operations that extend the general protocol operation. They are applied when special conditions, referred to exceptions (for example inconsistent data) occur.

An ITS-S maintains a local data structure, referred to as "ITS-S message table". This data structure holds information about sent or received CAM messages.

It is out of scope of the present document to describe how this data structure is implemented.

C.1 Originating ITS-S operation

C.1.1 Protocol data setting rules

The data setting for the originating ITS-S operation are specified in annex B.

C.1.1.1 T_CheckCamGen

The timer *T_CheckCamGen* schedules the time at which the CAM generation conditions are checked by the CA basic service, its time out value is specified in clause 6.1.3.

C.1.1.2 Originating ITS-S message table

The CA basic service stores at least the following information for the CAM originating ITS-S operation:

- CAM generation time;
- ITS-S position as included in CAM;
- ITS-S speed as included in CAM;
- ITS-S direction as included in CAM.

C.1.2 General protocol operation

The originating ITS-S protocol starts when the CA basic service is activated as specified in clause 6.1.1. An originating ITS-S may execute the following operations:

1) set *T_ CheckCamGen* and start the timer;

2) when the timer *T_CheckGenCam* expires, check the CAM generation conditions:

   a) if any of the condition is satisfied, continues the operation;

   b) if none of the condition is satisfied, skip step 3) to step 7);

3) collect data for mandatory containers;

4) check if optional containers are to be added for CAM generation:

   a) if yes, check the ITS-S type and ITS-S role and collect data for optional containers;

   b) if no, continues the operation;

5) encode CAM;

6) pass CAM to the ITS networking & transport layer;

7) save data required as specified in clause C.1.1.2 for next CAM generation;

8) restart the timer *T_ CheckCamGen.*

C.1.3 Exception handling

The originating ITS-S is expected to apply the exception handling rules given in this clause.

C.1.3.1 CAM construction exception

If the CA basic service could not construct a CAM successfully in step 5) as defined in clause C.1.2, the CA basic service is expected to omit steps 6) to 8) and is expected to restart the timer *T_CheckCamGen*.

NOTE 1: The failure of the CAM construction may happen, if the CA basic service was not able to collect all required data for the CAM construction, or the collected data are not compliant to the CAM format as specified in annex A (e.g. the value of a data is out of authorized range of the ASN.1 definition).

NOTE 2: If the CAM construction failure was due to a data provided by other entities via the interface IF.FAC, CA basic service may provide a failure notification to the corresponding data provision facilities via the IF.FAC.

C.2 Receiving ITS-S operation

C.2.1 Protocol data setting rules

No protocol data need to be set for the receiving ITS-S.

C.2.2 General protocol operation

The ITS-S receiver protocol starts when the CA basic service receives a CAM and executes the following operations:

1) decode received CAM;

2) make CAM data available by e.g. passing to the ITS application layer or to the LDM;

3) end of operation, wait for the next CAM reception.

C.2.3 Exception handling

C.2.3.1 CAM decoding exception.

If the CA basic service could not decode a CAM successfully in step 1) as defined in clause 8.2.2, the CA basic service omits steps 2 and 3.

NOTE: The failure of the CAM decoding may happen, if the CA basic service checks that the data included in a received CAM is not compliant to the CAM format as specified in annex A (e.g. the value of a data is out of authorized range of the ASN.1 definition).

Annex D (informative): Flow chart for CAM generation frequency management

Figures D.1 to D.3 illustrate the CAM frequency management specified in clause 6.1.3.

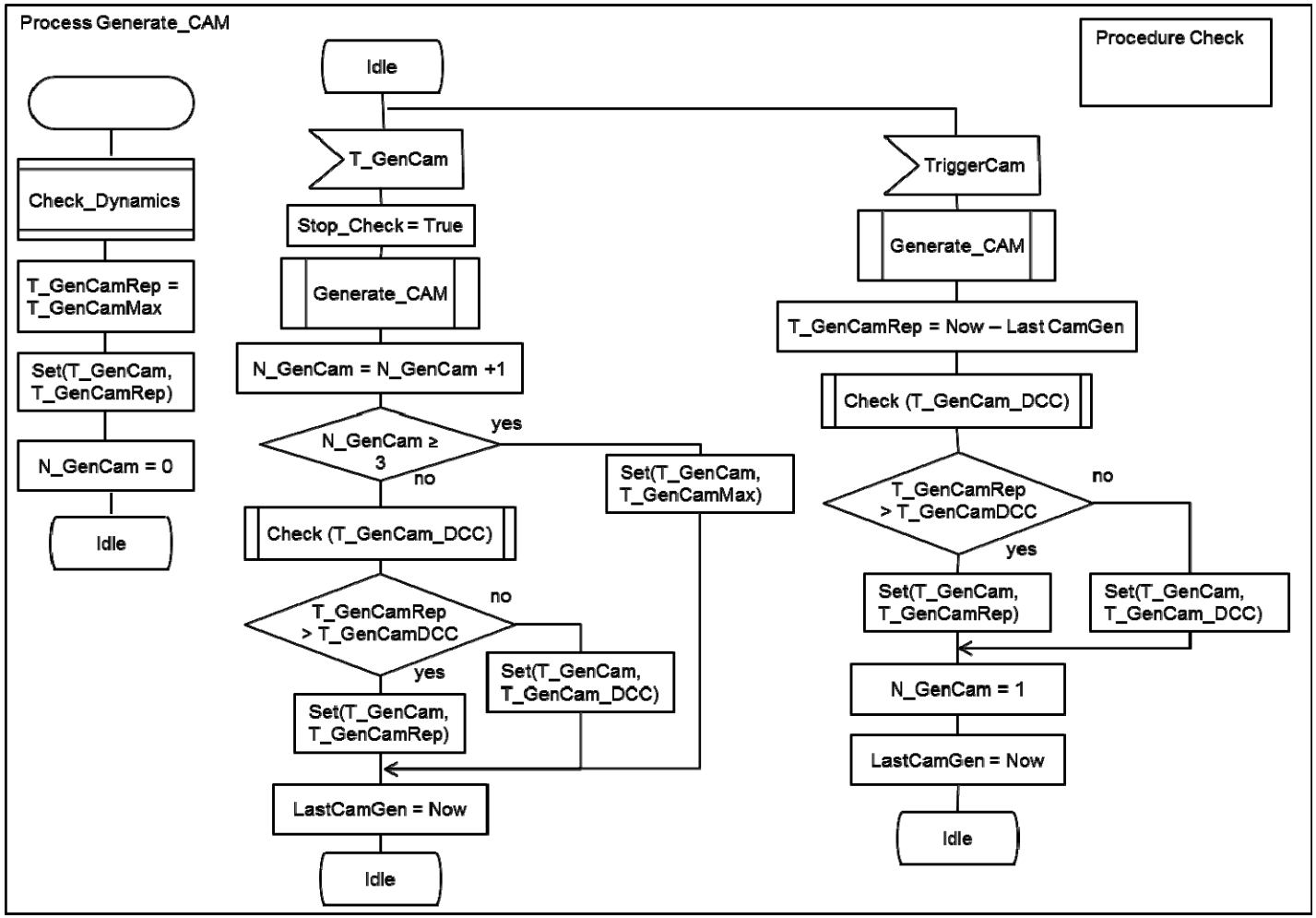
Process Generate_CAM
Check_Dynamics
T_GenCamRep = T_GenCamMax
Set(T_GenCam, T_GenCamRep)
N_GenCam = 0
Idle
Idle
T_GenCam
Stop_Check = True
Generate_CAM
N_GenCam = N_GenCam +1
N_GenCam ≥ 3
yes
no
Set(T_GenCam, T_GenCamMax)
Check (T_GenCam_DCC)
T_GenCamRep > T_GenCamDCC
no
yes
Set(T_GenCam, T_GenCam_DCC)
Set(T_GenCam, T_GenCamRep)
LastCamGen = Now
Idle
Procedure Check
TriggerCam
Generate_CAM
T_GenCamRep = Now – Last CamGen
Check (T_GenCam_DCC)
T_GenCamRep > T_GenCamDCC
no
yes
Set(T_GenCam, T_GenCamRep)
Set(T_GenCam, T_GenCam_DCC)
N_GenCam = 1
LastCamGen = Now
Idle

Figure D.1

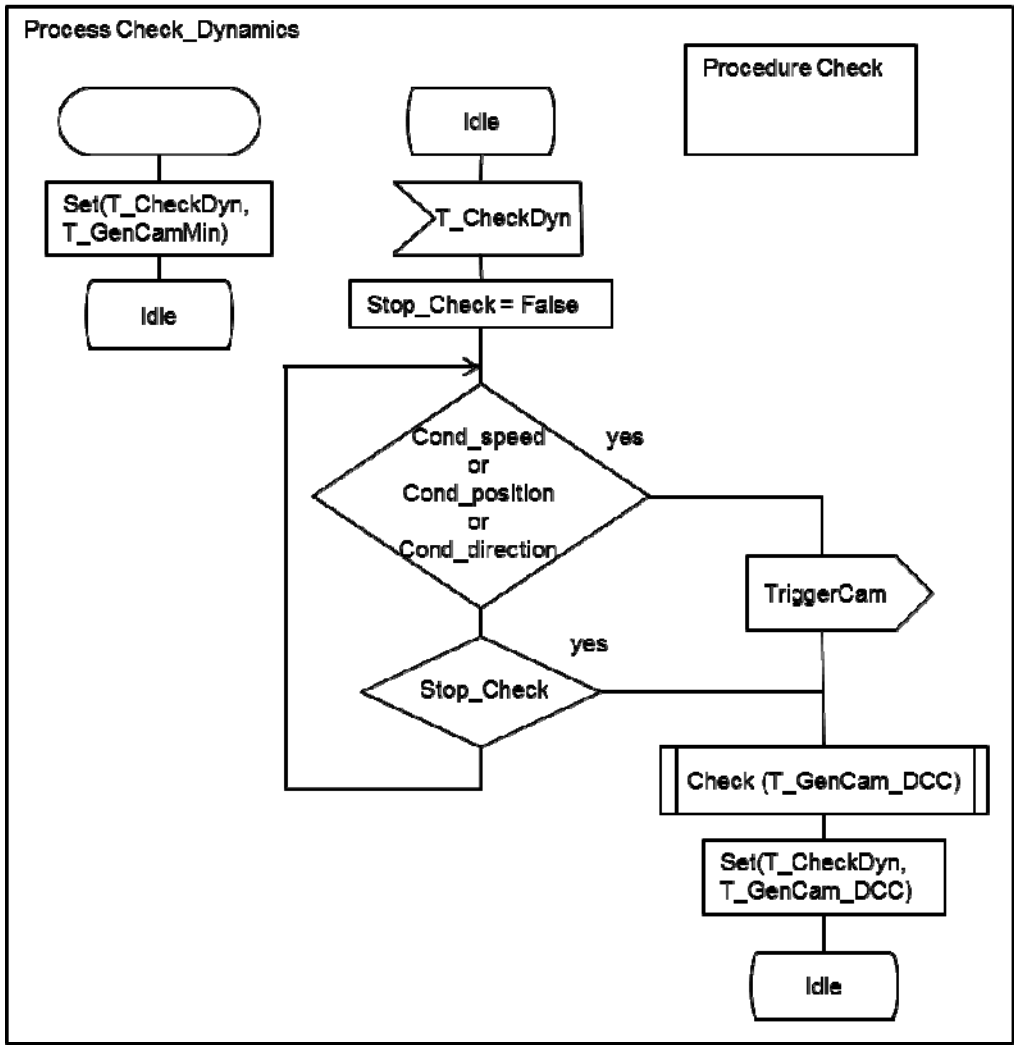
Process Check_Dynamics
Procedure Check
Idle
Set(T_CheckDyn, T_GenCamMin)
T_CheckDyn
Idle
Stop_Check = False
Cond_speed or Cond_position or Cond_direction
yes
TriggerCam
yes
Stop_Check
Check (T_GenCam_DCC)
Set(T_CheckDyn, T_GenCam_DCC)
Idle

Figure D.2

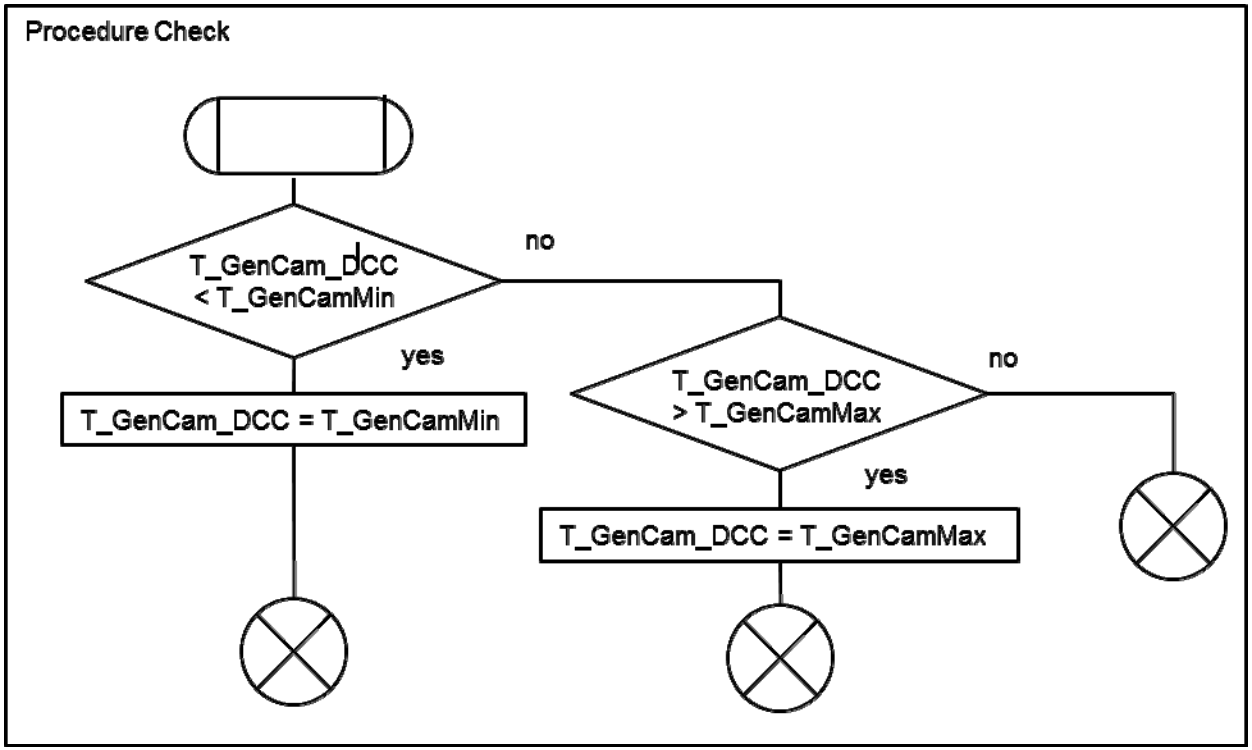
Procedure Check
T_GenCam_DCC
< T_GenCamMin
no
yes
T_GenCam_DCC = T_GenCamMin
T_GenCam_DCC
> T_GenCamMax
no
yes
T_GenCam_DCC = T_GenCamMax

Figure D.3

Annex E (informative): Extended CAM generation

Annex D describes an additional trigger condition for the CAM message generation, which enables ITS applications to increase the CAM generation frequency.

Depending on the requirements of an ITS application it may provide the parameter *T_GenCam_App* representing the needed CAM generation interval. *T_GenCam_App* should be provided in the unit of milliseconds and with a value range of $T\_GenCamMin \leq T\_GenCam\_App \leq T\_GenCamMax$. In case an ITS application provides this parameter with a value below *T_GenCamMin*, *T_GenCam_App* would be set to *T_GenCamMin* and if the value is above *T_GenCamMax* or this parameter is not provided, the *T_GenCam_App* would be set to *T_GenCamMax*. In case several ITS applications require different values the lowest generation interval would be applied.

In addition to the CAM trigger conditions defined in clause 6.1.3 following condition would apply:

1) the time since last CAM generation is equal or larger than *T_GenCam_App* and equal or larger than *T_GenCam_Dcc*

In case the requested CAM generation frequency will not be achieved, the CA basic service should return a failure notification to the requesting application.

History

Document history		
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