Short Range Devices (SRD);
Ground- and Wall- Probing Radio
determination (GPR/WPR) devices;
Harmonised Standard for access to radio spectrum
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History
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Foreword

This Harmonised European Standard (EN) has been produced by ETSI Technical Committee Electromagnetic compatibility and Radio spectrum Matters (ERM).

The present document has been prepared under the Commission's standardisation request C(2015) 5376 final [i.5] to provide one voluntary means of conforming to the essential requirements of Directive 2014/53/EU on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC [i.1].

Once the present document is cited in the Official Journal of the European Union under that Directive, compliance with the normative clauses of the present document given in table A.1 confers, within the limits of the scope of the present document, a presumption of conformity with the corresponding essential requirements of that Directive and associated EFTA regulations.

<table>
<thead>
<tr>
<th>National transposition dates</th>
</tr>
</thead>
<tbody>
<tr>
<td>Date of adoption of this EN:</td>
</tr>
<tr>
<td>Date of latest announcement of this EN (doa):</td>
</tr>
<tr>
<td>Date of latest publication of new National Standard or endorsement of this EN (dop/e):</td>
</tr>
<tr>
<td>Date of withdrawal of any conflicting National Standard (dow):</td>
</tr>
</tbody>
</table>

Modal verbs terminology

In the present document "shall", "shall not", "should", "should not", "may", "need not", "will", "will not", "can" and "cannot" are to be interpreted as described in clause 3.2 of the ETSI Drafting Rules (Verbal forms for the expression of provisions).

"must" and "must not" are NOT allowed in ETSI deliverables except when used in direct citation.
Introduction

GPR and WPR radars are imaging systems designed to operate while in contact with, or in close proximity to the ground or the wall, and their emissions are directed into the ground or wall (e.g. measured by a proximity sensor or imposed by the mechanical design).

The GPR/WPR applications in the present document are not intended for communications purposes, and the intended signal is not radiated into free space. The emissions into the air resulting from the operation of GPR/WPR imaging systems are defined as those emissions radiated in all directions above the ground from the GPR/WPR equipment, including direct emissions from the housing/structure of the equipment and emissions reflected or passing through the media under inspection (referred in ECC/DEC/(06)/08 [1,2] and in the present document as "undesired emissions"); they are therefore dependent on the operational conditions and are meaningful only if the GPR/WPR are coupled with the material being investigated. Figure 1 shows the scenario to be considered for the emissions radiated into the air by GPR/WPR.

Figure 1: Hatched area around the GPR/WPR shows the emissions to be considered in this clause
1 Scope

The present document specifies the requirements for Ground- and Wall- Probing Radar imaging systems applications. Ground Probing Radars (GPR) and Wall Probing Radars (WPR) are used in survey and detection applications. These do not include radars operated from aircraft or spacecraft.

The present document applies to:

1) Ground Probing Radars (GPR) operating in the frequency range 30 MHz to 12.4 GHz radiating directly downwards into the ground.

2) Wall Probing Radars (WPR) operating in the frequency range 30 MHz to 12.4 GHz radiating directly into a "wall". The "wall" is a building material structure, the side of a bridge, the wall of a mine or another physical structure that absorbs a significant part of the signal transmitted by the radar.

These equipment can either:

1) be fitted with integral antennas and without antenna connector; or

2) use different imaging heads (antennas) with an antenna connector, to allow operation at different operating bandwidths frequencies.

NOTE 1: Equipment covered by the present document operates in accordance with ECC/DEC(06)08 [i.2].

These radio equipment types are capable of operating in all or part of the frequency bands given in table 1.

Table 1: Permitted ranges of operation

<table>
<thead>
<tr>
<th></th>
<th>Transmit</th>
<th>Receive</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>30 MHz to 12.4 GHz</td>
<td>30 MHz to 12.4 GHz</td>
</tr>
</tbody>
</table>

NOTE 1: Limits in table 2, clause 4.3.4 are to be met.

NOTE 2: The frequency usage conditions for GPR/WPR are not fully harmonised in the EU and CEPT. Some National Regulatory Authorities (NRAs) may not have a general frequency allocation for GPR/WPT and may have established individual licensing requirements (e.g. registration of the user). Annex 2 of ECC/DEC/(06)08 [i.2] gives some guidance to administrations.

NOTE 2: The relationship between the present document and essential requirements of article 3.2 of Directive 2014/53/EU [i.1] is given in annex A.

2 References

2.1 Normative references

References are specific, identified by date of publication and/or edition number or version number. Only the cited version applies.

Referenced documents which are not found to be publicly available in the expected location might be found at https://docbox.etsi.org/Reference/.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are necessary for the application of the present document.

[1] ETSI EN 303 883 (V1.1.1) (09-2016): "Short Range Devices (SRD) using Ultra Wide Band (UWB); Measurement Techniques".
2.2 Informative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the referenced document (including any amendments) applies.

NOTE: While any hyperlinks included in this clause were valid at the time of publication, ETSI cannot guarantee their long term validity.

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.


[i.2] ECC/DEC/(06)08: "ECC Decision of 1 December 2006 on the conditions for use of the radio spectrum by Ground- and Wall- Probing Radar (GPR/WPR) imaging systems".

[i.3] ETSI TS 103 051 (V1.1.1) (08-2011): "Electromagnetic compatibility and Radio spectrum Matters (ERM); Expanded measurement uncertainty for the measurement of radiated electromagnetic fields".

[i.4] Void.


[i.6] ETSI EG 203 336 (V1.1.1) (08-2015): "Electromagnetic compatibility and Radio spectrum Matters (ERM); Guide for the selection of technical parameters for the production of Harmonised Standards covering article 3.1(b) and article 3.2 of Directive 2014/53/EU".

[i.7] Recommendation ITU-R SM.1755: "Characteristics of ultra-wideband technology".

3 Definition of terms, symbols and abbreviations

3.1 Terms

For the purposes of the present document, the terms given in ETSI EN 303 883 [1] and the following apply:

footsize: outside dimension of the DUT in the horizontal plane

large GPR/WPR: GPR/WPR with the largest dimension in the horizontal plane 1 metre or more

Pulse Repetition Frequency (PRF): inverse of the Pulse Repetition Interval (PRI), averaged over a sufficiently long time to cover all PRI variations

Pulse Repetition Interval (PRI): time between the rising edges of the transmitted (pulsed) output power

radiated measurements: measurements which involve the absolute measurement of a radiated electromagnetic field
**small GPR/WPR:** GPR/WPR with all dimensions in the horizontal plane below 1 metre

**time window:** length of time that the GPR/WPR receiver is activated to collect reflections from a single transmitted signal

**undesired emissions:** emissions radiated in all directions above the ground from the GPR/WPR equipment, including direct emissions from the housing/structure of the equipment and emissions reflected or passing through the media under inspection (see ETSI EG 203 336 [i.6])

**user manual:** end user documentation to be included with the device

### 3.2 Symbols

For the purposes of the present document, the symbols given in ETSI EN 303 883 [1] and the following apply:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>dB</td>
<td>DeciBel</td>
</tr>
<tr>
<td>dBi</td>
<td>Gain in decibels relative to an isotropic antenna</td>
</tr>
<tr>
<td>D1</td>
<td>Difference between M and N</td>
</tr>
<tr>
<td>D2</td>
<td>Difference between M and I</td>
</tr>
<tr>
<td>E</td>
<td>Electrical field strength</td>
</tr>
<tr>
<td>fC</td>
<td>Frequency at which the emission is the peak power at maximum</td>
</tr>
<tr>
<td>Ι</td>
<td>Signal recorded by the receiver in presence of the interferer</td>
</tr>
<tr>
<td>λ</td>
<td>Wavelength</td>
</tr>
<tr>
<td>M</td>
<td>Maximum signal for the receiver in the linear region of operation</td>
</tr>
<tr>
<td>N</td>
<td>Receiver noise level</td>
</tr>
</tbody>
</table>

### 3.3 Abbreviations

For the purposes of the present document, the abbreviations given in ETSI EN 303 883 [1] and the following apply:

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CEPT</td>
<td>European Conference of Postal and Telecommunications administrations</td>
</tr>
<tr>
<td>DT</td>
<td>DwellTime</td>
</tr>
<tr>
<td>DUT</td>
<td>Device Under Test</td>
</tr>
<tr>
<td>GPR</td>
<td>Ground Probing Radar, Ground Penetrating Radar</td>
</tr>
<tr>
<td>RNSS</td>
<td>Radio Navigation Satellite Service</td>
</tr>
<tr>
<td>RX</td>
<td>Receiver</td>
</tr>
<tr>
<td>SA</td>
<td>Spectrum Analyser</td>
</tr>
<tr>
<td>ST</td>
<td>ScanTime</td>
</tr>
<tr>
<td>TX</td>
<td>Transmitter</td>
</tr>
<tr>
<td>WPR</td>
<td>Wall Probing Radar</td>
</tr>
</tbody>
</table>

### 4 Technical requirements specifications

#### 4.1 Environmental conditions

The technical requirements of the present document apply under the environmental profile for operation of the equipment, which shall be declared by the manufacturer. The equipment shall comply with all the technical requirements of the present document which are identified as applicable in annex A at all times when operating within the boundary limits of the declared operational environmental profile.

#### 4.2 General

UWB devices in the scope of the present document can operate in a broad permitted range of frequencies from 30 MHz to 12.4 GHz, as defined in table 1.
In order to clearly identify the required limits and thus measurement procedures it is essential to define the operating bandwidth of the UWB equipment under test. The operating bandwidth of the UWB equipment under test shall be the -10 dB bandwidth of the intended UWB signal under normal operational conditions as defined in clause 4.3.1.

A single UWB device can have more than one operating bandwidth. All UWB related emissions shall be measured in the identified operating bandwidth of the UWB device under test. The required mitigation techniques are only valid in the operating bandwidth.

The RX conformance test considers the dynamic range and the resilience of the receiver against interference signals in the operating bandwidth and on some clearly identified frequencies inside and outside the operating bandwidth(s), see clause 4.4.4.

Test site and general arrangements for compliance measurements are defined in clauses 6.1.1 and 6.1.2.

4.3 Transmitter Conformance Requirements

4.3.1 Operating Bandwidth

4.3.1.1 Applicability

This requirement shall apply to all kind of GPR/WPR.

4.3.1.2 Definition

The operating bandwidth(s) of GPR/WPR is/are the -10 dB bandwidth(s) of the undesired emissions radiated into the air by the equipment.

**NOTE:** This definition is in accordance with the -10 dB bandwidth as defined in Annex 1 of Recommendation ITU-R SM.1755 [i.7].

4.3.1.3 Limits

Any operating bandwidth of all the DUT shall lie within the permitted frequency range of operation of the device (see table 1) and shall be > 50 MHz.

4.3.1.4 Conformance

The conformance test suite for operating bandwidth shall be as defined in clause 6.2.2.

4.3.2 Maximum value of mean power spectral density

There is no regulatory limit for the UWB maximum mean power spectral density in the main lobe of the GPR/WPR antenna (towards ground or wall) due to the nature of the GPR/WPR applications (see scope of the present document). The relevant mean power spectral density emissions (according to ECC/DEC/(06)08 [i.2]) of the GPR/WPR device is considered in clause 4.3.4 (undesired emission limit) and annex C (calculation of the mean power density).

4.3.3 Maximum value of peak power

There is no regulatory limit for the UWB maximum peak power in the main lobe of the GPR/WPR antenna (towards ground or wall) due to the nature of the GPR/WPR applications (see scope of the present document). The relevant peak power emissions (according to ECC/DEC/(06)08 [i.2]) of the GPR/WPR device is tested under clause 4.3.4 (undesired emissions limit).

4.3.4 All undesired emissions

4.3.4.1 Applicability

This requirement shall apply to all kind of GPR/WPR.
4.3.4.2 Definition

Term "undesired emissions" see clause 3.1.
See also clause 4.3.5 for the other emissions.

4.3.4.3 Limits

The effective radiated power of any emission from GPR/WPR shall not exceed the values given in table 2.

Table 2: Power limits of radiated emissions
(based on ECC/DEC/(06)08 [i.2], Annex 1)

<table>
<thead>
<tr>
<th>Frequency range (MHz)</th>
<th>Peak power limit values for emission</th>
</tr>
</thead>
<tbody>
<tr>
<td>30 to 230</td>
<td>-44.5 dBm/120 kHz (e.r.p.)</td>
</tr>
<tr>
<td>&gt; 230 to 1 000</td>
<td>-37.5 dBm/120 kHz (e.r.p.)</td>
</tr>
<tr>
<td>&gt; 1 000 to 18 000</td>
<td>-30 dBm/MHz (e.i.r.p.)</td>
</tr>
</tbody>
</table>

The maximum mean e.i.r.p. spectral density which is based on the peak values measured according to clause 6.2.5, shall be calculated as set out in annex C and shall not exceed the values in table C.1.

4.3.4.4 Conformance

The conformance test suite shall be as defined in clause 6.2.6.

4.3.5 Other Emissions

This requirement does not apply for GPR/WPR. The total undesired emissions from a GPR/WPR already include direct non UWB based (TX/RX) emissions from the housing/structure/electronics; therefore this clause does not apply because covered by the measurement of all undesired emissions in clause 4.3.4 (see ECC/DEC/(06)08 [i.2]).

4.3.6 Transmitter unwanted emissions

Transmitter unwanted emissions are specified as Out-Of-Band (OOB) and spurious emissions. For GPR/WPR these emissions are covered by the spectrum mask as defined in clause 4.3.4 and annex C and is tested under clause 4.3.4 (undesired emissions limit).

4.4 Receiver Conformance Requirements

4.4.1 General

For a detailed description for GPR/WPR receiver requirements, see annex D.

4.4.2 Receiver spurious emissions

Receiver spurious emissions are measured as part of the emissions resulting from the operation of GPR/WPR imaging systems, see clause 4.3.4.

4.4.3 Receiver dynamic range (sensitivity) for GPR/WPR

4.4.3.1 Applicability

This requirement shall apply to all kind of GPR/WPR.
4.4.3.2 Definition

Receiver dynamic range is defined in ETSI EG 203 336 [i.6] as the range of input signal levels over which a receiver functions at a specified performance level.

For GPR/WPR this performance criterion is set upon the difference $D_1$ between the maximum signal $M$ for the RX in the linear region of operation and the noise level $N$.

$$D_1[\text{dB}] = M[\text{dB}] - N[\text{dB}]$$

(1)

NOTE: More details on this RX-requirement are given in clause D.1.

4.4.3.3 Limits

$$D_1 \geq 40 \text{ dB}$$

(2)

4.4.3.4 Conformance

The conformance tests for Receiver dynamic range shall be as defined in clause 6.3.2.

4.4.4 Receiver blocking for GPR/WPR

4.4.4.1 Applicability

This requirement shall apply to all kind of GPR/WPR.

4.4.4.2 Description

For GPR/WPR, receiver blocking is defined as the measure of the capability of the receiver to receive a wanted signal without exceeding a given degradation due to the presence of an unwanted input signal at any frequency within the operating bandwidth; it evaluates the capability of the GPR/WPR to operate as intended in coexistence with interferers. This parameter is also defined as "Interferer signal handling" in ETSI TS 103 361 [2].

Operation as intended is evaluated using a performance criterion. For GPR/WPR this performance criterion is set upon the difference $D_2$ between the maximum signal $M$ for the RX in the linear region of operation and output signal $I$ in presence of the interferer.

$$D_2[\text{dB}] = M[\text{dB}] - I[\text{dB}]$$

(3)

NOTE: More details on this RX-requirement are given in clause D.1.

4.4.4.3 Limits

$$D_2 \geq 20 \text{ dB}$$

(4)

4.4.4.4 Conformance

The conformance tests for GPR/WPR receiver blocking shall be as defined in clause 6.3.2.

4.5 Other Requirements and Mitigation techniques

4.5.1 Deactivation mechanism

4.5.1.1 Applicability

This requirement shall apply to all kind of GPR/WPR.
4.5.1.2 Description

GPR/WPR applications are not intended for communications purposes. Their intended usage excludes radiation into the free space and this should be avoided due to a proper mechanism that deactivates the equipment when normal use is interrupted.

4.5.1.3 Limits

The deactivation mechanism requirements are defined in annex B.

4.5.1.4 Conformance

The conformance tests for the deactivation mechanism shall be as defined in clause 6.4.

5 Testing for compliance with technical requirements

5.1 Environmental conditions for testing

Tests defined in the present document shall be carried out at representative points within the boundary limits of the declared operational environmental profile.

Where technical performance varies subject to environmental conditions, tests shall be carried out under a sufficient variety of environmental conditions (within the boundary limits of the declared operational environmental profile) to give confidence of compliance for the affected technical requirements.

5.2 General conditions for testing

Clause 5.4 of ETSI EN 303 883 [1] provides information on test conditions, power supply and ambient temperature. ETSI TS 103 051 [i.3] provides additional information on measurement uncertainty.

6 Conformance test suites

6.1 Test setup

6.1.1 Setup description for small GPR/WPR

An semi-anechoic chamber with a conductive ground plane is the test site to be used for radiated testing of small GPR/WPR.
Figure 2: Calibrated setup for small GPR/WPR

In this case the DUT shall be placed at a height of 80 cm on a non-conducting support with the emitter directed downwards. A layer of ferrite tile should be placed directly on the floor and above the turntable.

A stack of broadband, flat RF absorbers up to 80 cm in height shall be placed directly below the DUT.

The stack of absorbers shall guarantee an absorption greater than 20 dB for normal incident energy above 500 MHz; the layer of ferrite tile shall guarantee an absorption greater than 20 dB for normal incident energy below 500 MHz.

If flat RF absorbers are not available, pyramidal or wedge-shaped RF absorbers may be used; in this case, some sections of absorber may be inverted and placed over other absorbers to form a solid block.

Care shall be taken not to place any RF absorber between the end of the turntable and the measurement antenna, as this would prevent energy not directed downwards from reflecting from the ground plane. The placement of the absorber shall not be disturbed when the device is rotated. This arrangement prevents energy directed downwards from consideration in the measurement.

The measurement antenna is placed three metres away from the boresight (vertical centre axis) of the DUT; it should be mounted on a support capable of allowing the antenna to be used in either horizontal or vertical polarization. Moreover the support should additionally allow the height of antenna centre above the ground to be varied from 1 metre to 4 metres.

For both the horizontal and vertical polarization of the test antenna, measurements in azimuth and elevation shall be taken for each frequency of interest to ensure that the maximum emission value has been recorded.

6.1.2 Setup description for large GPR/WPR

An open area test site is to be used for radiated testing of large GPR/WPR.

Large GPR/WPR shall be tested in an open area Test site over a dry sand pit. Characteristics of the sand to be used for filling up the pit are listed in annex E.

Emission of GPR/WPR is to be directed towards the sand pit. The sand pit shall be 50 cm deep and minimum 50 cm larger than the DUT (see figure 3). The DUT shall be placed in the middle of the sand pit. A thin plastic sheet or other suitable barrier all around the pit will preserve sand condition.
The open area test site comprises the sand pit and an antenna mast of variable height above a ground plane, which in the ideal case, is perfectly conducting and of infinite extent. In practice, whilst good conductivity can be achieved, the ground plane size has to be limited.

The ground plane shall extend up to the edges of the sand pit (see figure 3).

During the measurement, the DUT shall be placed on the testbed of sand with its antenna pointing directly into the sand and the test antenna is placed three metres away from the boresight (vertical centre axis) of the DUT.

For measurement below 960 MHz, the test antenna is placed three metres away from the boresight (vertical centre axis) of the DUT; it should be mounted on a support capable of allowing the antenna to be used in either horizontal or vertical polarization. Moreover the support should additionally allow the height of antenna centre above the ground to be varied from 1 metre to 4 metres to ensure that the maximum emission is recorded. Measurement shall be repeated for both the test antenna polarizations, by rotating the DUT from 0° to 360° with 45° step increment.

For measurement above 960 MHz, the test antenna is placed three metres away from the boresight (vertical centre axis) of the DUT; it should be mounted on a support capable of allowing the antenna to be used in either horizontal or vertical polarization. Moreover the support should additionally allow the height of antenna centre above the ground to be varied from 1 metre to 4 metres to ensure that the maximum emission is recorded. Measurement shall be repeated for both the test antenna polarizations, by rotating the DUT from 0° to 360° with 45° step increment.
For measurement above 960 MHz, the test antenna is placed three metres away from the boresight (vertical centre axis) of the DUT; it should be mounted on a support capable of allowing the antenna to be used in either horizontal or vertical polarization. The test antenna is pointed in the direction of the DUT to ensure that the maximum emission is recorded. Measurement shall be repeated by rotating the DUT from 0° to 360° degrees with 45° step increment.

6.2 Conformance methods of measurement for transmitter

6.2.1 General

The DUT shall be measured for:

- the operating bandwidth(s);
- the undesired emissions.

6.2.2 Operating Bandwidth(s)

The DUT shall be tested with the setup described in clause 6.1.1 or 6.1.2 depending on DUT dimensions.

Measurement shall be repeated for both test antenna polarizations, and by rotating the DUT from 0° to 360° degrees with 45° step increment. Test antenna's height shall be varied from 1 metre to 4 metres to ensure that the maximum peak of the emission is recorded.

The dimensions of the DUT and the setup used shall be recorded in the test report.

In both measurements for the lower and upper frequency bound \( f_L \) and \( f_H \), there shall be no point in the emission below \( f_L \) and above \( f_H \) where the level increases above the level recorded at \( f_L \) and \( f_H \). This ensures that peaks and valleys occurring near \( f_C \) are not used prematurely as the upper and lower bounds of the emission.

The peak of the radiated emission shall be determined by a peak power measurement, that indicates the maximum of the emission, \( f_C \).

The peak power of the emission shall be measured by:

- Set the spectrum analyser detector to positive peak.

- Centre the span on the peak of the emission and set the span to a value large enough to display the full emissions spectrum.

- Set the RBW to no less than 1 MHz and the VBW to no less than the RBW.

- A VBW of three times the RBW is preferred to eliminate video averaging.

The DUT shall be tested by directly coupling the normal operational transmitted signal, via a free-line-of-sight towards the measuring test antenna in a manner to ensure the test antenna receives a sufficient signal.

For the lower frequency bound \( f_L \), the emission shall be searched from a frequency lower than the peak that has, by inspection, a much lower PSD than the peak PSD -10 dB and increasing in frequency towards the peak until the PSD indicates a level of 10 dB less than at the peak of the radiated emission.

The process shall be repeated for the upper frequency bound \( f_H \), beginning at a frequency higher than the peak that has, by inspection, a much lower PSD than the peak PSD -10 dB.

The results for \( f_L, f_H \), the operating bandwidth and \( f_C \) shall be reported in the test report.

6.2.3 Mean power spectral density measurements

The mean power spectral density (according to ECC/DEC/(06)08 [i.2]) of the GPR/WPR device is considered under clause 6.2.5 (undesired emissions).
6.2.4 Peak power measurements

The peak power (according to ECC/DEC/(06)08 [i.2]) of the GPR/WPR device is considered under clause 6.2.5 (undesired emissions).

6.2.5 All undesired emissions measurement

The DUT shall be tested with the setup described in clause 6.1.1 or 6.1.2 depending on DUT dimensions.

Measurement shall be repeated for both test antenna polarizations, and by rotating the DUT from 0° to 360° degrees with 45° step increment. Test antenna’s height shall be varied from 1 metre to 4 metres to ensure that the maximum emission is recorded. The dimensions of the DUT and the setup used shall be recorded in the test report.

It may be necessary for specific DUTs to perform this measurement by inserting a low noise amplifier in the measuring arrangement to ensure sufficient signal level.

In all measurements the normal operational signal shall be used.

For measurements below 1 GHz, a quasi-peak detector according to CENELEC EN 55016-1-1 [3], clause 4 shall be used. For measurements above 1 GHz, a peak detector shall be used.

Using a spectrum analyser the following settings shall be applied:

a) Set the RBW below 1 GHz to 120 kHz and above 1 GHz to 1 MHz and the VBW to be at least equal or greater than the RBW.

b) Record over the frequency range \( f_L \) to \( f_H \) (see clause 6.2.2) the maximum level \( P_m \) received by the test antenna in the direction of the maximum emission of the DUT.

c) Calculate and record the peak power according the equation (5).

\[
\text{Power}_{\text{peak}} = P_m - G_R + L_C + L_{\text{Atten}} - G_{\text{Amp}} + 20 \log \left( \frac{4 \pi D}{\lambda} \right) \quad (5)
\]

where:

- \( P_m \): measured power.
- \( G_R \): gain of the receive (measurement) antenna, in dBi.
- \( L_C \): signal loss in the measurement cable, in dB.
- \( L_{\text{Atten}} \): value of external attenuation (if used), in dB.
- \( G_{\text{Amp}} \): value of external amplification (if used), in dB.
- \( D \): measurement distance, in metres, taken from the centre of the DUT to the antenna reference point at the position in its height scan where the maximum signal was detected.
- \( \lambda \): wavelength computed on the centre frequency of radiated DUT signal.

d) The maximum observed values for the peak power and the maximum mean e.i.r.p. spectral density computed according to annex C shall be recorded in the test report.

In order to obtain the required sensitivity a narrower bandwidth may be necessary, this shall be stated in the test report form.

The measurement shall be repeated in the frequency bands 1 164 MHz to 1 215 MHz and 1 559 MHz to 1 610 MHz measured in a 1 kHz resolution bandwidth. Using a spectrum analyser the following is applicable:

a) Search for the highest narrowband emission/spectral line and record the frequency.

b) Set the RBW to 1 kHz and the VBW to 3 kHz.

c) Set the centre frequency of the SA to the frequency recorded in a).
d) Measure and record the level of the emission recorded in step a).

The measuring receiver configuration shall use a low noise preamplifier and a dipole antenna (for frequencies below 1 GHz) or horn antenna (for frequencies above 1 GHz). Details are given in ETSI EN 303 883 [1]. For the emission measurements, a combination of bicones and log periodic dipole array antennas (commonly termed “log periodics”) could also be used to cover the entire 30 MHz to 1 000 MHz band.

If the test site is disturbed by radiation coming from outside the site, measurements may be performed with reduced distance between the transmitter and the test antenna and limits consequently increased.

Proper pre-select filtering can be incorporated to protect the measurement system low-noise pre-amplifier from overload. In addition, persistent ambient signals can be detected to remove the ambient signal contributions present in the measured spectra. This requires post-processing of the measurement data utilizing a computer and data analysis software.

6.2.6 Other emissions

This requirement does not apply to any DUT because it is covered by the measurement of all undesired emissions in clause 6.2.5.

6.2.7 Transmitter unwanted emissions

For GPR/WPR these emissions are covered by the measurement of all undesired emissions in clause 6.2.5.

6.3 Conformance methods of measurement for receiver

6.3.1 Receiver spurious emissions

Receiver spurious emissions are measured as part of the emissions by GPR/WPR, see clause 6.2.5.

6.3.2 Receiver dynamic range (sensitivity) and blocking

6.3.2.0 General

The receiver dynamic range and blocking conformance shall be tested in the test scenario described in clause 6.3.2.1.

The interferer test frequency range, interferers and interferer power levels, test scenario, performance criterion and level of performance shall be recorded in the test report.

6.3.2.1 Test scenario

The DUT shall be tested with the setup described in clause 6.1.1 or 6.1.2 depending on the dimension of the DUT. Figure 5 or figure 6 are visualizing these two scenarios for the receiver tests.
6.3.2.2 Interferer test frequencies and interferer power levels

The interferer test frequency range shall be as defined in clause 9.1.2 of ETSI TS 103 361 [2], using the receiver operating frequency range as equal to the operating bandwidth (see clause 6.2.2 of the present document).
The selection of interferes shall be as given in ETSI TS 103 361 [2], clause 9.3 and table 7.

6.3.2.3 Measurement of the maximum signal M for the receiver

The maximum signal M for the receiver in the linear region of operation shall be determined from the signal produced when the DUT is suspended 5 cm above a plane metal. The size of the metal plate shall be at least the DUT footsize. During this measurement, the interferer shall be deactivated. At least 100 measurements shall be recorded and averaged; M is defined as the maximum absolute value in Volts occurring in the averaged result.

6.3.2.4 Measurement of the noise level N with the interferer deactivated

Using the setup described in figure 5 or figure 6 and with the interference source switched off, at least 100 measurements shall be recorded collected and averaged. The result for N is defined as the maximum absolute value in Volts occurring in the averaged signal from the half to the end of the time window.

6.3.2.5 Measurement of the received signal I with the interferer activated

Using the setup described in figure 5 or figure 6 and the interfering signal based on clause 6.3.2.2, at least 100 measurements shall be recorded collected and averaged. The result for I is defined as the maximum absolute value in Volts occurring in the averaged signal from the half to the end of the time window.

6.3.2.6 Calculation of D1

D1 is evaluated as the difference between the value M[dB] and N[dB], with:

\[ M[dB] = 20 \log(M[V]) = 10 \log(M[W]) \] (6)

\[ N[dB] = 20 \log(N[V]) = 10 \log(N[W]) \] (7)

6.3.2.7 Calculation of D2

D2 is evaluated as the difference between the value M[dB] and I[dB], with:

\[ I[dB] = 20 \log(I[V]) = 10 \log(I[W]) \] (8)

\[ M[dB] = 20 \log(M[V]) = 10 \log(M[W]) \] (9)

6.4 Other test suites

6.4.1 Deactivation mechanism

The DUT shall be tested with the setup described in clause 6.1.1 or 6.1.2 depending on DUT dimensions.

Any emission from the DUT shall cease within 10 seconds of the de-activation mechanism being switched off or released by the operator (ECC/DEC/(06)08 [i.2]).

NOTE: There are particular cases where the equipment is mounted in a vehicle for the collection of data where the de-activation time required is 60 seconds.

The result shall be recorded in the test report.
Annex A (informative):
Relationship between the present document and the essential requirements of Directive 2014/53/EU

The present document has been prepared under the Commission's standardisation request C(2015) 5376 final [i.5] to provide one voluntary means of conforming to the essential requirements of Directive 2014/53/EU on the harmonisation of the laws of the Member States relating to the making available on the market of radio equipment and repealing Directive 1999/5/EC [i.1].

Once the present document is cited in the Official Journal of the European Union under that Directive, compliance with the normative clauses of the present document given in table A.1 confers, within the limits of the scope of the present document, a presumption of conformity with the corresponding essential requirements of that Directive and associated EFTA regulations.

<table>
<thead>
<tr>
<th>Harmonised Standard ETSI EN 302 066</th>
<th>Requirement</th>
<th>Essential requirements of Directive</th>
<th>Clause(s) of the present document</th>
<th>Requirement Conditionality</th>
</tr>
</thead>
<tbody>
<tr>
<td>No</td>
<td>Description</td>
<td>3.2</td>
<td>4.3.1</td>
<td>U</td>
</tr>
<tr>
<td>1</td>
<td>Operating Bandwidth(s)</td>
<td>3.2</td>
<td>4.3.4</td>
<td>U</td>
</tr>
<tr>
<td>2</td>
<td>All undesired emissions</td>
<td>3.2</td>
<td>4.4.2</td>
<td>U</td>
</tr>
<tr>
<td>3</td>
<td>Receiver spurious emissions</td>
<td>3.2</td>
<td>4.4.3</td>
<td>U</td>
</tr>
<tr>
<td>4</td>
<td>Receiver dynamic range</td>
<td>3.2</td>
<td>4.4.4</td>
<td>U</td>
</tr>
<tr>
<td>5</td>
<td>Receiver blocking</td>
<td>3.2</td>
<td>4.5.1</td>
<td>U</td>
</tr>
<tr>
<td>6</td>
<td>Deactivation mechanism</td>
<td>3.2</td>
<td>4.5.1</td>
<td>U</td>
</tr>
</tbody>
</table>

Key to columns:

**Requirement:**

- **No**
  - A unique identifier for one row of the table which may be used to identify a requirement.
- **Description**
  - A textual reference to the requirement.

**Essential requirements of Directive**

Identification of article(s) defining the requirement in the Directive.

**Clause(s) of the present document**

Identification of clause(s) defining the requirement in the present document unless another document is referenced explicitly.

**Requirement Conditionality:**

- **U/C**
  - Indicates whether the requirement is unconditionally applicable (U) or is conditional upon the manufacturer's claimed functionality of the equipment (C).
- **Condition**
  - Explains the conditions when the requirement is or is not applicable for a requirement which is classified "conditional".

Presumption of conformity stays valid only as long as a reference to the present document is maintained in the list published in the Official Journal of the European Union. Users of the present document should consult frequently the latest list published in the Official Journal of the European Union.

Other Union legislation may be applicable to the product(s) falling within the scope of the present document.
Annex B (normative):
Deactivation mechanism

The deactivation mechanism of the equipment is a function which deactivates the equipment when normal use is interrupted.

The following requirements shall be fulfilled according to the provisions of ECC/DEC/(06)08 [i,2]:

- Manually operated GPR and WPR, which is intended to be used as handheld equipment, shall contain a manually operated non-locking switch (e.g. it may be a sensor for the presence of the operators hand or a movement sensor) which ensures that the equipment de-activates (i.e. the transmitter switches off) within 10 seconds of being released by the operator.

- In the case of remotely/computer controlled imaging equipment, the equipment shall be de-activated via the control system provided that de-activation takes place within 10 seconds of the control system being switched off or released by the operator.

- GPR and WPR equipment shall be designed to operate while in contact with, or in close proximity, or within one metre of, to the ground or the wall, and their emissions being directed into the ground or wall (e.g. measured by a proximity sensor or imposed by the mechanical design). Manufacturers shall provide instruction manuals for the equipment which include a description for its use and deployment (positioning) during operation.

- There are particular cases where the equipment is mounted in a vehicle for the collection of data where the de-activation time required is 60 seconds.
Annex C (normative):
Calculation of the Mean Power Density

C.0 General

Maximum mean power densities and peak power densities of any emission emanating from GPR/WPR imaging systems are defined below. For pragmatic reasons and for taking the mitigation factors into account, the mean power density shall be determined by formula (C.1) or (C.2) and the peak values shall be measured according to clause 6.2.5.

NOTE: GPR/WPRs operate across a wide range of spectrum where established radio services operate. These services have diverse bandwidths, some may be susceptible to peak signal levels and others to average signal levels. There are technical and practical issues, related to bandwidth, the effective loading of the GPR/WPRs radiation by earth materials and the limitations of instrumentation. Peak signal levels are measured according to clause 6.2.5 and average signal levels calculated based upon the duty cycle of the GPR/WPR.

a) The mean power density of any emission emanating from GPR/WPR imaging systems shall be kept to a minimum and not exceed the limits in table C.1.

Table C.1: Maximum mean e.i.r.p. of any emission emanating from GPR/WPR imaging systems (based on ECC/DEC/(06)08 [i.2], Annex 1)

<table>
<thead>
<tr>
<th>Frequency range (MHz)</th>
<th>Maximum mean e.i.r.p. density (dBm/MHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt; 230</td>
<td>-65</td>
</tr>
<tr>
<td>230 to 1 000</td>
<td>-60</td>
</tr>
<tr>
<td>1 000 to 1 600</td>
<td>-65 (see note)</td>
</tr>
<tr>
<td>1 600 to 3 400</td>
<td>-51,3</td>
</tr>
<tr>
<td>3 400 to 5 000</td>
<td>-41,3</td>
</tr>
<tr>
<td>5 000 to 6 000</td>
<td>-51,3</td>
</tr>
<tr>
<td>&gt; 6 000</td>
<td>-65</td>
</tr>
</tbody>
</table>

NOTE: In addition to the maximum mean e.i.r.p. density given above, a maximum mean e.i.r.p density of -75 dBm/kHz applies in the RNSS bands 1 164 MHz to 1 215 MHz and 1 559 MHz to 1 610 MHz in case of spectral lines in these bands. Peak power shall be measured according to clause 6.2.5 of the present document and mean power density shall be determined from formula (C.1) or (C.2) set out below.

b) The measured radiated peak power of any emission emanating from GPR/WPR imaging systems shall not exceed the limits as given in clause 4.3.4.3 (table 2), measured according to clause 6.2.5.

c) The time domain architecture of GPR/WPRs and patterns of use imply that there is wide variation in the total power emitted in any time period. For pulsed systems this includes the duration of pulses compared to the time between pulses, the time between bursts of pulses when the system is being moved to the next measurement position and other operational factors. This should be taken into account when considering the mean power that may be incident upon a vulnerable radio service. In order to accommodate all these factors a conversion factor shall be used to evaluate the mean power that should be compared to the limits in table C.1. This conversion factor has been established as a simple and practical way to assess mean power levels based on the measurement of peak power levels.

When determining mean power values, for pulsed systems, to be compared with the values in table C.1 the following formula shall be used:

\[ \text{Power}_{\text{mean}} = \text{Power}_{\text{peak}} + \text{conversion \_ factor} \quad \text{(C.1)} \]

with:

\[ \text{conversion \_ factor} = 10 \log(\text{PRF} \times \tau) \quad \text{(C.2)} \]
where:

\( \tau \) is the pulse width of the GPR/WPR transmitter measured at the 50 % amplitude points of the envelope at boresight with an UWB probe and a suitable oscilloscope. When performing this measurement, care should be taken that the pulse is properly gated, i.e. no reflectors should be allowed to influence the pulse while travelling from the GPR/WPR transmitter to the UWB probe. The UWB probe/antenna shall have a bandwidth wide enough to capture the UWB signal from the GPR/WPR properly.

PRF is the pulse repetition frequency.

For systems using step-frequency waveforms, the wideband signal is formed by transmitting a sequence of discrete frequencies each having a DwellTime (DT). The length of the total sequence is the ScanTime (ST). The Scan Time is identical to the Cycle Time in frequency hopping systems, and it is the interval between each time the transmitter is hopping back to the first frequency in the sequence.

For calculating the mean power value for a step-frequency system, the following formula shall be used:

\[
\text{Power}_{\text{mean}} = \text{Power}_{\text{peak}} + \text{conversion \_factor} \tag{C.3}
\]

with:

\[
\text{conversion \_factor} = 10 \log(\frac{\text{DT}}{\text{ST}}) \tag{C.4}
\]

where:

- DT is measured at the 50 % amplitude points of the envelope at boresight with an UWB probe and a spectrum analyser in zero-span mode at a frequency near the maximum of the radiated spectrum using 1 MHz resolution bandwidth. ST is measured in the same way using a spectrum analyser in zero-span mode and 1 MHz resolution bandwidth.

C.1 Measurement of \( \tau \), transmit pulse width

C.1.0 Introduction

There are two ways of measuring \( \tau \), time domain (see clause C.1.1) and frequency domain methods (see clause C.1.2).

C.1.1 Time domain

The GPR antenna is lifted off the ground and pointed directly towards the measurement antenna, see figure C.1. The distance between the DUT and receive antenna shall be greater than one wavelength (at the lowest frequency radiated). Care shall be taken so that there are no unwanted multipath reflections included in the time interval where the pulse width measurement is carried out. The non-dispersive antenna/UWB-probe shall have a fractional bandwidth wide enough to represent the UWB, signal (GPR/WPR typically have a fractional bandwidth greater than 100 %).

![Figure C.1: Test setup 1](image-url)
C.1.2 Frequency domain

The RF bandwidth of a single pulse modulated carrier is approximately equal to $1/\tau$. By measuring the occupied bandwidth an equivalent pulse width is calculated. There is no need to have a non-dispersive antenna or oscilloscope any more, the measurement is done with the same antenna and spectrum analyser as for the peak power measurement as per clause 6.2.2, but with the GPR and measurement antenna facing each other, see figure C.2.

To avoid multipath reflections distorting the measurement, this test shall be carried out in an open test area or in an anechoic room.

$$\tau = \frac{1}{(f_H - f_L)} \text{, -10 dB measurement points (see clause 6.2.2)} \quad (C.5)$$
Annex D (normative):
Receiver parameters for GPR/WPR

D.0 General

Ground- and Wall- Probing Radar imaging systems applications and are used in survey and detection applications. GPR/WPR systems are not intended for communications purposes, and the intended signal is not radiated into free space. Thus, "classical" parameters for a radiocommunications receiver as provided in ETSI EG 203 336 [i.6] are inappropriate to GPR/WPR because of the peculiar unique sensing (non-traditional communications and radar) use of this technology.

Specifically, GPR/WPR are imaging devices where detection is ultimately based on the minimum acceptable Signal to Noise Ratio (SNR\text{min}) to perform a detection; in other words, the minimum input signal at the receiver stage recalled in ETSI EG 203 336 [i.6], is the one that surpass the received noise by a specific amount, so that the relevant target becomes detectable by the operator.

This "detection threshold" is largely dependent on the operator's skill and experience, but is generally considered 3 dB minimum; thus a target would become detectable by the GPR/WPR user if its signal produced by such target exceeds the received noise level by at least 3dB. However, in the following this threshold is set to 0 dB (worst case).

It is also important noting that the received noise level is dependent on the gain of the receiver signal chain which could not be measureable in GPR/WPRs (e.g. in integral antenna devices); thus, an absolute specification for this parameter cannot be given. However, the difference between the maximum signal that the receiver signal detection circuitry can tolerate before clipping or distorting the signal and such received noise level, is not affected by that gain; further, this parameter also affects another important feature for the GPR/WPRs which is the maximum detection range (i.e. the maximum exploration range for the system).

Given the considerations above, it was concluded that the receiver dynamic range and the receiver blocking can be used as a measure of the capability of the receiver to receive a wanted signal without exceeding a given degradation due to the presence of an unwanted input signal.

D.1 Resilience of GPR/WPR receiver against interferences

D.1.0 Introduction

A GPR/WPR is designed to be moved for scanning and detecting targets that are embedded in a lossy dielectric media (e.g. the ground); this is obtained by measuring the electromagnetic field back-scattered by those targets. Because of the need of working even in presence of large signal absorption by the propagation medium and the desire to detect the smallest size of object possible, the resilience against any interfering signal is crucial to not reducing the exploration depth.

GPR/WPR performance is maximized by processes that will ultimately increase the desired signal and minimize all undesired signals; the most common undesired signals for a GPR/WPR are:

a) electronic noise generated in the receiver electronics;

b) signals generated in the transmitter system that are undesired and enter the receiver electronics by any path (also called "direct transmit/receive antenna leakage");

c) electromagnetic signals from external sources (radio transmissions, cell phones, etc.) that enter the receiver electronics via the receive antenna or some other path;

d) signals from extraneous features in the propagation medium that may mask the response of the desired target (often referred to as clutter noise).
Obviously, receiver resilience against the latter's cannot be evaluated and even specified; as explained in the following paragraphs, the performance criterion used for the receiver requirement for GPR/WPR (clauses 4.4.3 and 4.4.4) takes into consideration signals a), b) and c) above.

D.1.1 Maximum signal M for the RX in the linear region of operation

The maximum signal M for the receiver in the linear region of operation is defined as the maximum absolute value (in Volts) occurring in the signal received by the GPR/WPR when suspended 5 cm above a plane metal.

In this setup, with the interfering signal switched off, M overvalues the direct transmit/receive antenna leakage and represents the maximum signal the GPR/WPR can receive when operating. The graph in figure D.1 represents that received signal which is decaying with respect to time and hence distance from the GPR/WPR.

![Figure D.1: Example of GPR/WPR received and averaged signal - the maximum level is the reflection from the metallic plate](image)

D.1.2 Noise level N for the RX in the linear region of operation

The noise level N is defined as the maximum absolute value in Volts occurring in the averaged signal from the half to the end of the time window with the interferer deactivated. This constitutes the minimum signal that the GPR/WPR can receive in this setup.

D.1.3 Signal I recorded in presence of the interferer

The signal I is defined as the maximum absolute value in Volts occurring in the averaged signal from the half to the end of the time window with the interferer activated.

In this condition, the presence of the interferer may produce an increase of the noise received by the GPR/WPR which can hide reflections from weaker targets (figure D.2).
D.2 Performance criteria for GPR/WPR

Basing on concepts illustrated above, for GPR/WPR the receiver performance criteria are set upon the dynamic range $D_1$ and the difference $D_2$ between the maximum signal $M$ and output signal $I$ in presence of the interferer (see figure D.3).

As indicated above, $M$ is the maximum signal that the receiver senses, whereas $N$ is the noise floor below which detectable return signals are not discernible; in this sense, it can be concluded that the low input signal level at the receiver ("wanted signal") is the one that exceeds by some amount the noise floor; this, in fact, is the minimum signal the operator of a GPR/WPR can detect, no matter of the characteristics of the target detected by the GPR/WPR which is producing such signal.
According to that, the term dynamic range for a GPR/WPR is specified by the parameter D1 in clause 4.4.3.2; this requires the evaluation of the DUT maximum signal, M and the noise floor, N.

The parameter so defined in dB (D1= M-N) establishes a specified level of performance to be reached by the equipment (i.e. this can be interpreted as the "pre-determined level of performance" for a GPR/WPR in the specific test scenario), so that can be used to set a specification for the receiver sensitivity.

Performance of the GPR/WPR receiver in the presence of an external noise source is also assessed based on comparison with the parameter D1. The presence of a noise source will obviously impact the noise floor and change the value reducing the system sensitivity to weak signals. Setting a minimum required value for the parameter D2 is a meaningful method for assessing the resilience of GPR/WPR against interferences.

D.3 Justification for missing RX requirements from ETSI EG 203 336

ETSI EG 203 336 [i.6] uses the signal interferer handling concept from ETSI TS 103 361 [2], which has been developed for very broadband UWB applications (e.g. having more than 500 MHz bandwidth); these devices have a so called underlay regulation, with extremely low emission limits in the order of the EMC limits and even below.

The interferer signal handling concept requires a receiver test with the tree strongest expected interferer within the operating bandwidth; in the present document (ETSI EN 302 066) this test is described as "blocking". It is therefore assumed that a GPR/WPR complying with such strong inband interferer will automatically comply with signals with the same magnitude in adjacent bands; therefore receiver tests outside the operating band are deemed as unnecessary.

Given that, other parameters listed in ETSI EG 203 336 [i.6] are linked to the selected receiver performance criteria in this standard as explained here below:

- Sensitivity: the received noise is measured and used in the dynamic range clause.
- Adjacent channel selectivity: this parameter is included in the clause on GPR/WPR blocking.
- Co-channel rejection: this parameter is covered by the signal interferer handling concept used with the receiver blocking test.
- Spurious response rejection, Intermodulation and Reciprocal Mixing: these parameters are covered by the signal interferer handling concept used with the receiver blocking test.
- Desensitization this is covered by the signal interferer handling concept with the three strongest inband interferer used with the dynamic range test.
Annex E (normative):
Characteristics of the sand for the conformance test suites

E.1 General

The setup for testing the compliance of large GPR/WPR includes a pit filled with dry sand.

The purpose of this pit is to maximize the energy coupling into the subsurface, thus enabling the measurement of emissions that are radiated by GPR/WPR in all directions above the ground ("undesired emissions"). The specification of the sand for the pit is given in clause E.2.

The requirement of maximizing the energy coupling into the subsurface, imposes the use of a non-conductive, high impedance material directly under the GPR/WPR antenna; in fact, the use of an high conductivity, low impedance soil just below the antenna, will essentially 'short out the antenna', thus resulting in a wrong measurement of the undesired emissions.

For that reason, the pit in the test setup for large GPR/WPR is filled with dry, non-conductive sand that allows energy to transition to much lower impedance soil (wet and possibly high conductivity soil) that appears at greater depth.

In this sense, the dry sand play much the same role as tapered foam absorber used in test facilities. The goal for the absorber is to graduate the impedance with distance to minimize spurious reflections from the test facility structure.

E.2 Physical characteristics of the sand for the test setup

Sand to be used for filling up the pit in the test setup for large GPR/WPR shall have the following characteristics:

a) Name: silica sand

b) Origin: river sand or crushed stone sand

c) Chemical Composition: SiO$_2$ > 80 %

d) Classification: Coarse sand (i.e. passing through a sieve with clear openings of 3.175 mm)

e) Loss on ignition (LOI): < 2,2 %

NOTE: The Loss On Ignition parameter is obtained by measuring the weight change of a sample after it has been heated to high temperature causing some of its content to burn or to volatilise. In the case of silica sand, this parameter is related to the humidity content (as lower the parameter, as drier the sand). The verification procedure to assess the LOI of the sand is described in clause E.3.

E.3 Verification of the humidity content of the sand

In order to verify the dryness of the sand in the test setup for large GPR/WPR, the measurement of the Loss On Ignition (LOI) parameter is required.

Loss on ignition describes the process of measuring the weight change of a sample after it has been heated to high temperature causing some of its content (i.e. the water in this case) to burn or to volatilise.

A sample of the sand extracted from the test setup is placed in weighed container and weighed; weight loss is measured after heating the sample overnight at 100ºC to remove water.

When determining the Loss On Ignition (LOI) to be compared with the value in clause E.2, the following formula shall be used:

\[
\text{LOI} = 100 \times \frac{\text{weight before heating} - \text{weight after heating}}{\text{weight before heating}} \quad \text{(E.1)}
\]
Annex F (informative):
Bibliography

- ETSI EN 301 489-33 (V2.1.1) (02-2017): "ElectroMagnetic Compatibility (EMC) standard for radio equipment and services; Harmonised Standard covering the essential requirements of article 3.1b of the Directive 2014/53/EU; Part 33: Specific conditions for Ultra-WideBand (UWB) devices".


Annex G (informative):
Change History

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<tr>
<td>1.2.1</td>
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| 2.1.1   | Revision for compliance with Directive 2014/53/EU  
Out-sourcing of standard measurement procedures into a separate ETSI EN 303 883 (V1.1.1)  
New requirement on Interferer signal handling  
New annex B “Application form for testing” |
| 2.2.1   | Revision of requirement on receiver conformance |
### Document history

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