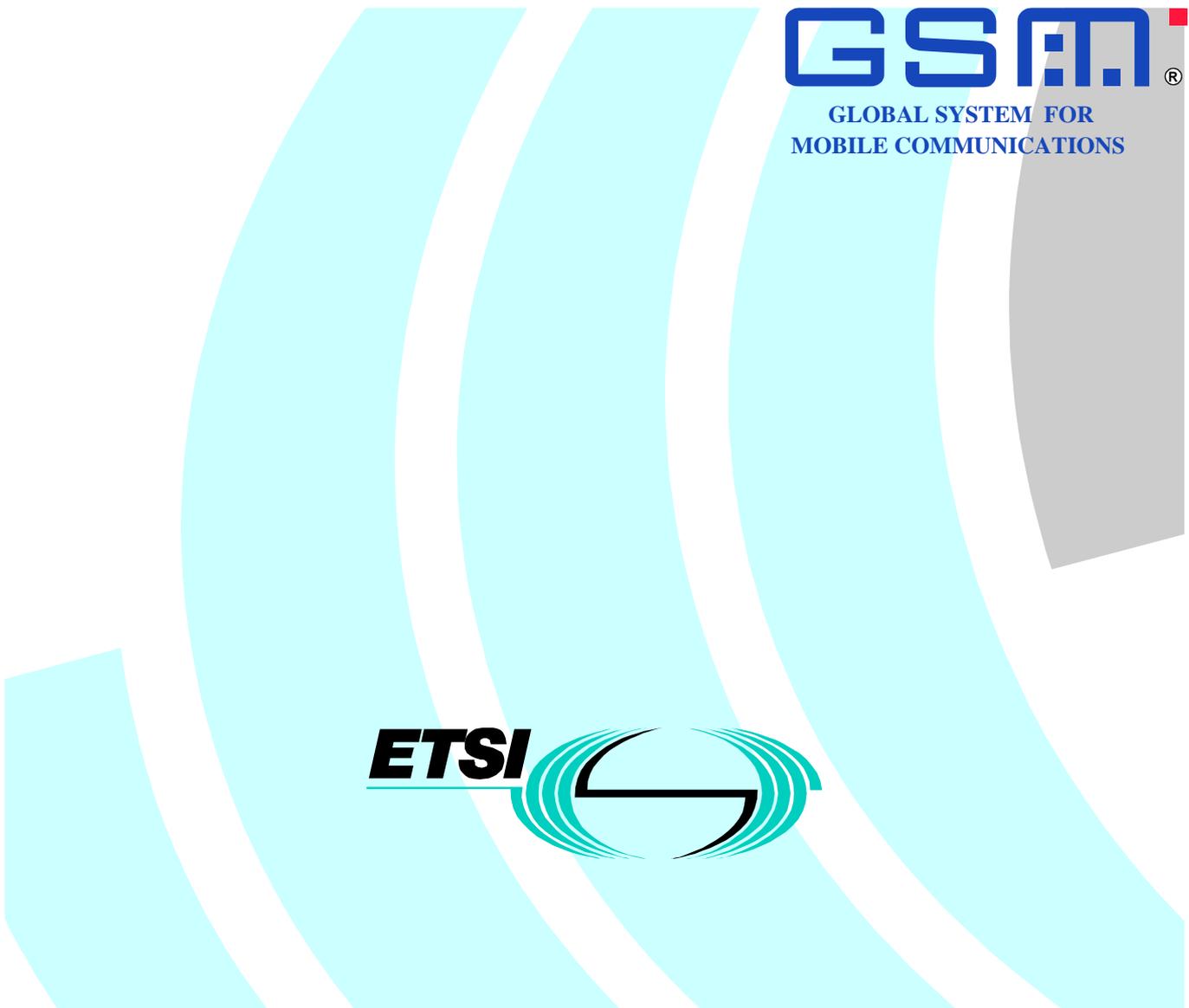


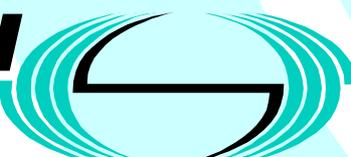
TS 101 369 V6.1.0 (1998-07)

Technical Specification

**Digital cellular telecommunications system (Phase 2+);
Terminal Equipment to Mobile Station (TE-MS)
multiplexer protocol
(GSM 07.10 version 6.1.0 Release 1997)**



GSM®
GLOBAL SYSTEM FOR
MOBILE COMMUNICATIONS

ETSI 

Reference

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Foreword

This Technical Specification (TS) has been produced by the Special Mobile Group (SMG) of the European Telecommunications Standards Institute (ETSI).

This specification specifies the Terminal Equipment to Mobile Station (TE-MS) multiplexer protocol within the digital cellular telecommunications system.

The contents of this TS is subject to continuing work within SMG and may change following formal SMG approval. Should SMG modify the contents of this TS, it will be re-released by SMG with an identifying change of release date and an increase in version number as follows:

Version 6.x.y

where:

- 6 indicates GSM Phase 2+ Release 1997;
- x the second digit is incremented for all other types of changes, i.e. technical enhancements, corrections, updates, etc.;
- y the third digit is incremented when editorial only changes have been incorporated in the specification.

Introduction

The 07.10 multiplexer protocol operates between an MS and a TE and allows a number of simultaneous sessions over a normal serial asynchronous interface. Each session consists of a stream of bytes transferring various kinds of data; for instance, voice, fax, data, SMS, CBS, phonebook maintenance, battery status, GPRS, USSD etc. This permits, for example, SMS and CBS to be transferred to a TE when a data connection is in progress. Many other combinations are possible including digital voice. It is, for instance, possible to transfer digital voice in combination with SMS. The multiplexer allows a complete system to be partitioned in a flexible way between a MS and TE.

The design of the multiplexer is flexible and independent of MS/TE platforms, and allows existing applications to work without any modifications.

The multiplexer is designed, with special care for battery-powered devices, to include very important functionality such as power saving control and priorities. It is also specially designed to require minimum processing power and memory consumption.

The multiplexer is defined as a single mode with different options based on the ISO HDLC standard (ISO/IEC 13239:1997) although the basic option is not in accordance with HDLC.

In the basic option, the multiplexer does not make use of any transparency mechanism or error recovery method. The advanced option uses the ISO HDLC standard transparency mechanism and gives the multiplexer an easy re-synchronisation method and the ability to operate over links which already use DC1/DC3 (XON/XOFF) flow control. The advanced option also may include error-recovery for links subject to errors.

In its basic option, the multiplexer is intended for use in situations where the link between MS and TE is of a very good quality and where the HDLC transparency mechanism (byte stuffing) can not be implemented in the MS. If an MS supports the HDLC transparency mechanism, it shall be used by the multiplexer. The ISO HDLC transparency mechanism must be used if loss of synchronisation may occur caused by, for example, data over-runs or under-runs. The error-recovery option should be used in situations where the link is subject to errors.

The multiplexer is based on a control channel. On this channel, management information is exchanged, such as parameter negotiation, power saving control information, testing, flow control, close down etc.

The multiplexer is optional, but when supported, it is activated with the 07.07 AT+CMUX command.

1 Scope

The scope of this document is to define a multiplexing protocol between a mobile station and a terminal. The multiplexing protocol can be used to send any data, for instance voice, SMS, USSD, fax etc.

This document describes the protocol, but not the commands or data transported with it.

2 References

References may be made to:

- a) specific versions of publications (identified by date of publication, edition number, version number, etc.), in which case, subsequent revisions to the referenced document do not apply; or
- b) all versions up to and including the identified version (identified by "up to and including" before the version identity); or
- c) all versions subsequent to and including the identified version (identified by "onwards" following the version identity); or
- d) publications without mention of a specific version, in which case the latest version applies.

A non-specific reference to an ETS shall also be taken to refer to later versions published as an EN with the same number.

- [1] GSM 01.04: "Digital cellular telecommunications system (Phase 2+); Abbreviations and acronyms".
- [2] ISO/IEC 13239:1997: "Information technology -- Telecommunications and information exchange between systems -- High-level data link control (HDLC) procedures".
-

3 Definitions and abbreviations

3.1 Abbreviations

For the purposes of the present document, the following abbreviations apply:

ABM	Asynchronous Balanced Mode
ERM	Error-Recovery Mode
DLC	Data Link Connection
FCS	Frame Check Sequence
SABM	Set Asynchronous Balanced Mode
UAU	numbered Acknowledgement
DM	Disconnected Mode
UIH	Unnumbered Information with header Check
UI	Unnumbered Information
PSC	Power Saving Control
MSC	Modem Status Command

Additional GSM related abbreviations can be found in GSM 01.04 [1].

4 Overview of Multiplexing System

The multiplexer provides mechanisms for conveying streams of data between TE and MS over a single start-stop framed, serial link. Figure 1 shows the arrangement of the various protocol levels and functions. The multiplexer layer

provides multiplexing of data arranged in octet streams with no other framing; if the structure of the data has to be conveyed, a convergence layer may be necessary. This Specification defines some convergence layers, others may be added later.

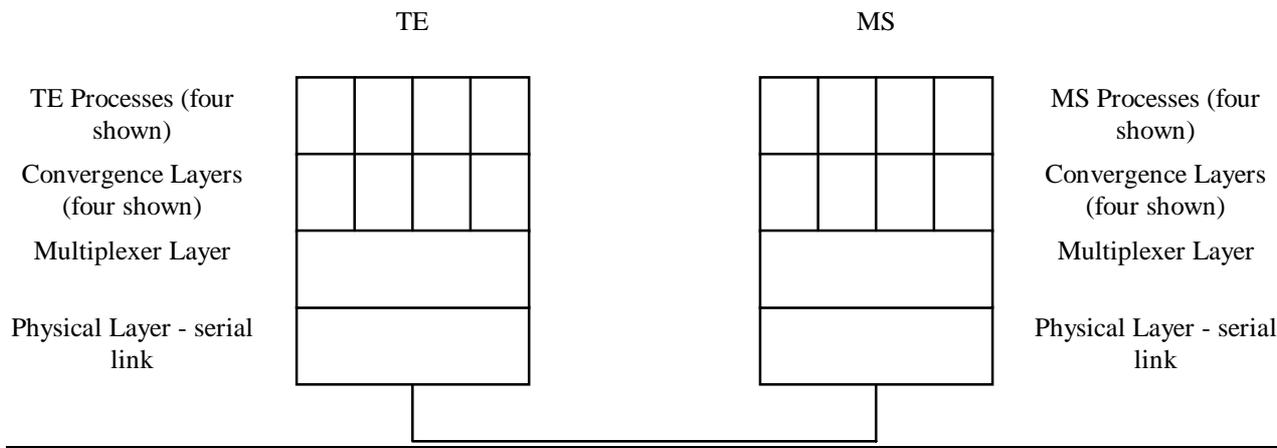


Figure 1: Protocol Stacks

The multiplexer provides a virtual connection between a process in the TE and a similar process in the MS. For example, a PC application supporting SMS functions could be connected to the SMS handler in the MS via a multiplexer channel.

This Specification uses start-stop transmission with eight-bit characters. Communication between the two multiplexing entities takes place using frames constructed as defined below.

Each channel between TE and MS is called a Data Link Connection (DLC) and is established separately and sequentially.

Each DLC may have individual flow control procedures for buffer management purposes and the aggregate link also has overall flow control mechanisms.

DLCs have two modes of operation; Error-Recovery Mode (ERM) and non-error-recovery mode (non-ERM), the choice of mode is made when a DLC is established. DLCs using error recovery mode may exist on the same link as DLCs using non-error recovery mode. If the error-recovery mode (ERM) is to be used at least on one DLC, then the multiplexer must be configured with the ISO HDLC transparency mechanism. The use of error recovery mode is optional. Non-error recovery mode uses the UI frame or UIH frame to carry user data; error recovery mode uses the I frame.

The multiplexer has three operating options, basic, advanced without error recovery and advanced with error recovery. The characteristics of the options are:

Basic:

- Length indicator used instead of the HDLC transparency mechanism.
- Different flag octet from that used by HDLC.
- Can not be used on links which use XON/XOFF flow control.
- May have longer recovery procedure from loss of synchronisation.

Advanced without error recovery:

- Asynchronous HDLC procedures in accordance with ISO/IEC 13239.
- Can be used on links which use XON/XOFF flow control.
- Recovers quickly from loss of synchronisation.

Advanced with error recovery:

- Uses HDLC error-recovery procedures.

5 Non Error Recovery mode Options

This clause describes the non-error-recovery options (basic and advanced) of the multiplexer. The main are given below:

- A simple set of procedures with no error recovery mechanism, for use on reliable connections.
- Data transparency is provided by the HDLC mechanism (advanced option only).
- A multiplexer control channel which conveys management and control information between the MS and TE.
- A mechanism that permits either MS or TE to enter power-saving modes without compromising the integrity of the multiplexer.
- A comprehensive set of convergence layers which enables many types of data to be carried while preserving the structure of the original data.

The use of the transparency mechanism must be set up at the beginning of the multiplexing session. It is a characteristic for the entire multiplexing session.

The simple set of procedures uses UIH frames to transmit information; these frames are easy to process because their structure permits the HDLC Frame Check Sequence (FCS) to be pre-calculated rather than being constructed on a character-by character basis. The procedures used are very straightforward and it is not necessary to implement the usual HDLC state machines.

UI frames or UIH frames may be used for those channels where the timely delivery of the information is more important than its reliability because erroneous frames will be discarded. UI frames would be used in those cases where it is important that the data delivered is accurate.

5.1 Service Interface Definition

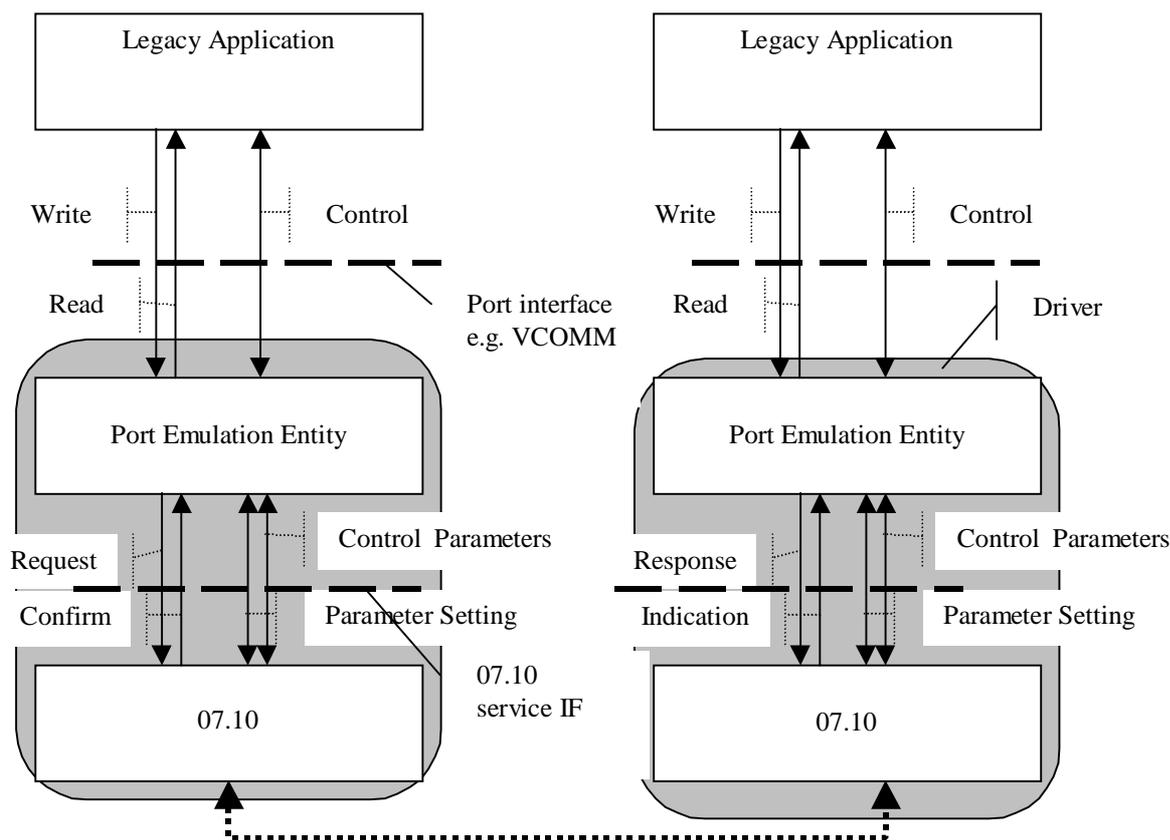
This clause describes the services provided by the TS 07.10 data link layer to the upper layer. The interface is specified in terms of primitives and parameters.

NOTE: this clause is only for information, detailed description of the parameters is found in the following subclauses.

5.1.1 Service Definition Model

The 07.10 specification is intended to define a protocol that can be used to emulate a serial port. In most systems the 07.10 will be a part of a port driver which includes a port emulation entity that must support existing communication APIs. The communication APIs vary from operating system to operating system and from device to device. This document does not specify how 07.10 is used by a port driver to emulate an existing API but instead focus on a set of services that can be used by all port drivers. Port drivers are not required to use all the services of 07.10.

The figure below shows a model of how 07.10 fits into a typical system.



The legacy application utilises a conventional serial port communication interface. The port emulation entity maps a system specific communication interface to 07.10 services. The 07.10 provides several transparent data stream channels and a control channel. The port interface is the application programmers interface for communication. It varies from system to system and one example is Virtual comm ports in windows.

5.1.2 Start up services

These services are used to start the TS 07.10 multiplexer operation over a serial channel. The following services are provided:

TS0710_START.request (*mode, system_parameters*)

TS0710_START.indication (*mode, system_parameters*)

TS0710_START.response (*mode, system_parameters, accept*)

TS0710_START.confirm (*mode, system_parameters, accept*)

Description: The *request* primitive is used to request that the multiplexer mode to be turned on in the desired mode and system parameters. The *indication* primitive transfers the request to start multiplexer operation along with the desired mode and system parameters to the upper layer of the target device. If the target device accepts the request by issuing an affirmative *response* primitive, the suggested mode and system parameters will become valid. The *confirm* primitive is returned to the upper layer of the requesting device. A successful establishment of the multiplexer mode is indicated by the *accept* parameter being set to "true". If the *accept* parameter is set to "false" the returned values for the other parameters are those suggested by the responding device.

Parameters:

mode = [Basic | HDLC - UIH frames | HDLC - UI frames | HDLC - frames]. (Note that the frame type for HDLC mode refers to the multiplexer control channel. For subsequently opened DLCs this parameter can be negotiated.

system_parameters = Port speed [9,6 | 19,2 | 38,4 | 57,6 | 115,2 | 230,4 kBit/s],
 Maximum Frame Size [1 – 128 in Basic mode,
 1 – 512 in HDLC modes
 default: 31 for the basic
 option and 64 for the
 advanced option]
 Acknowledgement Timer [0,01s-2,55s,
 default: 0,1s]
 Maximum number of retransmissions [0 – 100,
 default : 3]
 Response timer for the multiplexor control
 channel [0,01s-2,55s, default: 0,3s]
 Wake up response timer [1s – 255s, default 10s]
 Window size for error recovery mode [1 – 7,
 default : 2]

accept = [true | false]

Support of the mode parameter is optional. If the mode parameter is omitted, Basic mode is implied. Note that some of the above system parameters can be redefined for the individual DLCs, see below under DLC establishment services.

5.1.3 DLC establishment services

The DLC establishment services are used to open DLC's on the multiplexer channel. The following services are provided:

TS_0710_DLC_ESTABLISHMENT.request(DLCI, system_parameters)

TS_0710_DLC_ESTABLISHMENT.indication(DLCI, system_parameters)

TS_0710_DLC_ESTABLISHMENT.response(DLCI, system_parameters, accept)

TS_0710_DLC_ESTABLISHMENT.confirm(DLCI, system_parameters, accept)

Description: The transmitting device uses the *request* primitive to initiate the establishment of a new DLC with a desired set of system parameters on the multiplexer channel. The *indication* primitive is passed to the upper layer by the TS 0710 layer of the receiving device on reception of the DLC establishment request. The receiving device uses the *response* primitive to either accept or reject the proposed DLCI with its system parameters. On rejection, it is possible to suggest a modified set of system parameters. The *confirm* primitive is passed to the upper layer of the transmitting device on reception of the response from the receiving device.

Parameters:

DLCI = 1-63 (DLCI number)

System parameters = Type of frame [UIH | UI | I, default: UIH],
 Convergence layer [1 - 4, default: 1]
 Priority [0-63]
 Acknowledgement Timer [0,01s-2,55s,
 default: 0,1s]
 Maximum Frame Size [1 – 32768,
 default: 31 for the basic option and
 64 for the advanced option]
 Maximum number of retransmissions [0 – 255,
 default : 3]
 Window size for error recovery mode [1 – 7,
 default : 2]

Accept = [true | false]

All entries in the system parameters parameter are optional. The entries not implemented assume the default values.

5.1.4 Data services

The data services provided are:

TS_0710_DATA.request(DLCI, User_data)

TS_0710_DATA.indication(DLCI, User_data)

Description: The transmitting unit initiates transmission of data using the frame type specified for the chosen DLCI by means of the request primitive. The transmitted data is delivered to the upper layer of the receiving by the *indication* primitive. No confirmation primitive exists even for the error recovery mode. In this mode TS 0710 will take care of all mechanisms involved in the error checking and thus deliver data error free.

Parameters:

DLCI = [1 – 63] DLC over which the data is to be transmitted.

User_data = Data to be transferred organised in accordance with the convergence layer of the DLC

5.1.5 Power Control services

In some application it might be desirable for either the DTE or the DCE to enter a power saving mode with a minimum of communication activities taking place. Services that support this functionality are the Sleep services and the Wakeup services

5.1.5.1 Sleep services

TS_0710_SLEEP.request

TS_0710_SLEEP.indication

TS_0710_SLEEP.confirm

Description: The *request* primitive is used to advice the receiving device that the transmitter wishes to enter a low power state. The TS 0710 layer of the receiving unit sends an *indication* primitive to the upper layer in order to inform that the transmitting unit has entered the power saving state. The TS 0710 layer will automatically transmit an acknowledge message to the transmitting device, thus no *response* primitive is required. The *confirm* primitive is sent to the upper layer of the transmitting device when the low power request has been received, and indicates that the TS 0710 layer has entered the low power mode. Note that the Receiving device is not required to enter a low power mode, but it will be considered to have done so by the TS 07.10 layer.

5.1.5.2 Wakeup services

TS_0710_WAKEUP.indication

TS_0710_WAKEUP.response

Description: The *indication* primitive is sent to the upper layer when the TS 0710 layer of the receiving unit receives a request to wake up from the power saving state. When the receiving device is ready to resume operation on the multiplexer channel this is indicated to the TS 0710 layer in the receiving unit by means of the *response* primitive. Sins the wakeup routine is initiated by the transmitting device attempting to communicate, neither *request* nor *confirm* primitives are provided for the wakeup service. The transmitting device instead uses the Data services described below.

5.1.6 DLC Release services

The DLC release services are used to disconnect a DLC. The following services are provided:

TS_0710_DLC_RELEASE.request(DLCI)

TS_0710_DLC_RELEASE.indication(DLCI)

Description: The *request* primitive is used by the upper layer in the transmitting device to initiate close down of the selected DLC in TS 0710. The TS 0710 layer of the receiving device uses the *indication* primitive to inform the upper layer that the DLC has been closed down.

Parameters:

DLCI = [1 – 63] Number of the DLC to be released.

5.1.7 Close down services

The Close down services are used to terminate multiplexer operation on the serial channel and resume AT mode. The services provided are:

TS_0710_CLOSE.request

TS_0710_CLOSE.indication

Description: When the request primitive is passed to the TS 0710 layer of the transmitting device close down of the multiplexer mode is initiated and a close down command is sent to the receiving device. On reception of the close down command the TS 0710 layer of the receiving device sends the indication primitive to the upper layer and the multiplexer mode is terminated.

5.1.8 Control Services

5.1.8.1 07.10 Services

5.1.8.1.1 DLC parameter negotiation

These services are used to negotiate and set parameters for a specific DLC. The following services are provided:

TS0710_PARNEG.request (*DLC, DLC parameters*)

TS0710_PARNEG.indication (*DLC, DLC_parameters*)

TS0710_PARNEG.response (*DLC, DLC_parameters, accept*)

- TS0710_PARNEG.confirm (*DLC, DLC_parameters, accept*)

Description: The *request* primitive is used to request that the remote 07.10 entity changes a specific DLC connection parameters. An indication is sent to the remote port emulation entity. The remote emulation entity replies with a response which is forwarded as an confirmation to the originating port emulating entity.

DLC_parameters = frame type [UIH | UI | I ,
 default: UIH]
 Convergence Layer Type [Type 1 | Type 2 | Type 3 | Type 4,
 default: Type 1]
 Priority [1-63,
 default: according to table in subclause 5.6]
 Acknowledgement timer [10 ms - 25.5 sec,
 default: 100 ms]
 Maximum Frame Size [1 – 32768,
 default: 31 for the basic option and
 64 for the advanced option]
 Maximum number of retransmissions [0 – 100,
 default : 3]
 Response timer for the multiplexor control
 channel [0,01s-2,55s, default: 0,3s]
 Wake up response timer [1s – 255s, default 10s]
 Window size for error recovery mode [1 – 7,
 default : 2]

accept = [true | false]

5.1.8.1.2 DLC Service Negotiation service

These services are used to negotiate and set a specific service on a DLC. The following services are provided:

TS0710_PORTNEG.request (*DLC, Service_parameters*)

TS0710_PORTNEG.indication (*DLC, Service_parameters*)

TS0710_PORTNEG.response (*DLC, Service parameters, accept*)

TS0710_PORTNEG.confirm (*DLC, Service_parameters, accept*)

Description: The *request* primitive is used to request a specific service on a DLC. The indication is sent to the other port emulation. The remote port emulation entity replies with a response containing accepted or possible services. The originating port emulation entity receives a confirm on the request with either an accept or a possible service list.

service_parameters = *Service* [data | voice 64kbit/s A-law PCM | reserved 1 | reserved 2],
 voice codec [GSM 06.21 | 64kbit/s u-law PCM | coded ADPCM 32kbit/s | coded half rate | 128 kbit/s PCM | reserved]

5.1.8.1.3 Test service

These services are used to test the communication link between two 07.10 entities. The following services are provided:

TS0710_TEST.request (*Test data*)

TS0710_TEST.confirm (*Test data*)

Description: The *request* primitive is used to request a test of the communication link. The data is sent to the remote entity, which loops it back. The confirmation is sent to the originating port emulation entity containing the looped data.

Test Data = Data to be transferred as a test pattern, organised in accordance with the convergence layer of the 07.10 control channel.

5.1.8.1.4 Flow control services

The flow control services provided are:

TS_0710_FLOW.request(DLCI,State)

TS_0710_FLOW.indication(DLCI, State)

Description:

The request primitive with *State = disable* disables the issuing of TS_0710_DATA.indications by the 07.10 entity. The request primitive with *State = enable* enables the issuing of TS_0710_DATA.indications by the 07.10 entity. These requests may or may not result in the remote 07.10 entity issuing a TS_0710_FLOW.indication to the remote service user, depending on the states of the buffers in the 07.10 entities.

The indication primitive with *State = disable* disables the issuing of TS_0710_DATA.requests by the service user. The indication primitive with *State = enable* enables the issuing of TS_0710_DATA.requests by the service user. These indications may or may not have resulted from the receipt by the remote 07.10 entity of a TS_0710_FLOW.request from the remote service user. They may have been issued by the local 07.10 entity as a result of its buffer state.

The initial state of the 07.10 entity is with data flow enabled.

Parameters:

DLCI = [1 – 63] DLC over which the data is to be transmitted.

State = *enabled* (data may be transferred), *disabled* (data may not be transferred)

5.1.8.2 Port Emulation Services

5.1.8.2.1 Remote DLC parameter negotiation service

These services are used to negotiate and set of parameters for a remote communication port. The following services are provided:

TS0710_PORTNEG.request (*DLC, Port_parameters*)

TS0710_PORTNEG.indication (*DLC, Port_parameters*)

TS0710_PORTNEG.response (*DLC, Port parameters, accept*)

TS0710_PORTNEG.confirm (*DLC, Port_parameters, accept*)

Description: The *request* primitive is used to request that the remote port changes its parameters. The indication is sent to the other port emulation entity. The remote port emulation entity replies with a response. A confirm is sent to the originating port entity.

port_parameters = Port speed [2,4 | 4,8 | 7,2 | 9,6 | 19,2 | 38,4 | 57,6 | 115,2 |
230,4 kBit/s],
Data bits [5 | 6 | 7 | 8,
default: 8 bits |
Stop bits [1 | 1,5,
default: 1 bit |
Parity [no parity | parity,
default: no parity |
Parity Type [odd | even | mark | space]

accept = [true | false]

5.1.8.2.2 DLC Control Parameter service

The DLC Control Parameter service is used to convey control parameters between Port Emulation Entities. Default values should be assumed if no control parameter has been designated since the DLC has been made. This service is to control a specific DLC. It includes such as flow control, Modem signals, Break. The following services are provided:

TS0710_CONTROL.request (*DLC, Control_parameters*)

TS0710_CONTROL.indication (*DLC, Control_parameters*)

TS0710_CONTROL.response (*DLC, Control parameters*)

TS0710_CONTROL.confirm (*DLC, Control_parameters*)

Description: The *request* primitive is used to convey control information to the remote port. The indication is sent to the other port emulation entity. The remote port emulation entity replies with a response which is sent to the originating 07.10 entity. A confirm is sent back to the port emulation entity.

system_parameters = Modem Signal [DTR/DSR | RTS/CTS | RI | DCD],
Break Signal [0—3 s in steps of 200 ms,
default 0ms],
Buffers [do not discard buffers, discard buffer
default: do not discard buffers],
Break signal sequence [as soon as possible | in sequence,
default: in sequence]

5.1.8.2.3 DLC Line status indication service

These services are used to indicate a DLC line status to a remote port emulation entity.. The following services are provided:

TS0710_PORTNEG.request (*DLC, Line Status parameter*)

TS0710_PORTNEG.indication (DLC, *Line Status parameter*)

Description: The *request* primitive is used to send the line status to the remote device. The indication is sent to the other port emulation entity. The remote port emulation does not reply.

Line status parameter = Port speed [no errors, overrun error, parity error, framing error]

5.2 Frame Structure

All information transmitted between the TE and MS is conveyed in frames.

5.2.1 Frame Fields

The frame structure is composed of an opening and a closing flag, an Address field, a Control field, an Information field and FCS field. A length indication field is present in each frame if no transparency mechanism is used for the multiplexing session.

5.2.1.1 Flag Sequence Field

Each frame begins and ends with a flag sequence octet which is defined as a constant bit pattern.

5.2.1.2 Address Field

The address field consists of a single octet. It contains the Data Link Connection Identifier (DLCI), the C/R bit and the address field extension bit as shown in Figure 2.

Bit No.	1	2	3	4	5	6	7	8
	EA	C/R	D		L	C	I	

Figure 2: Format of Address Field

The DLCI is used to identify an individual user information stream as well as to identify connections between TE and MS. Multiple DLCIs shall be supported but the number is implementation-specific. The DLCIs are dynamically assigned. The values used for specific DLCIs are given in subclause 5.6.

The C/R (command/response) bit identifies the frame as either a command or a response. In conformance with HDLC rules, a command frame contains the address of the data link connection entity to which it is transmitted while a response frame contains the address of the data link connection entity transmitting the frame. For a given DLC, the DLCI value of the address field remains the same but the C/R bit changes, as shown in Table 1.

Table 1: Command/response bit usage

Command/response	Direction		C/R value	
Command	Initiator	————>	Responder	1
	Responder	————>	Initiator	0
Response	Initiator	————>	Responder	0
	Responder	————>	Initiator	1

See subclause 5.4.3.1 for more details about C/R bit.

According to the rules of ISO/IEC 13239:1997, the range of the address field may be extended by use of the EA bit. When the EA bit is set to 1 in an octet, it signifies that this octet is the last octet of the address field. When the EA bit is set to 0, it signifies that another octet of the address field follows. In this Specification there is only one address octet so the EA bit is always set to 1. Note that future amendments to this Specification may extend the address field and use the EA bit.

5.2.1.3 Control Field

The content of the control field defines the type of frame. The control fields of the frames used in this Specification are described in Table 2.

Table 2: Coding of Control Field

Frame Type	1	2	3	4	5	6	7	8	Notes
SABM (Set Asynchronous Balanced Mode)	1	1	1	1	P/F	1	0	0	
UA (Unnumbered Acknowledgement)	1	1	0	0	P/F	1	1	0	
DM (Disconnected Mode)	1	1	1	1	P/F	0	0	0	
DISC (Disconnect)	1	1	0	0	P/F	0	1	0	
UIH (Unnumbered Information with Header check)	1	1	1	1	P/F	1	1	1	
UI (Unnumbered Information)	1	1	0	0	P/F	0	0	0	Optional

In Table 2, P/F is the Poll/Final bit. The functions of these bits are described later.

5.2.1.4 Information Field

The information field is the payload of the frame and carries the user data and any convergence layer information. The field is octet structured. The information field is only present in I frames, UI frames and UIH frames.

5.2.1.5 Length Indicator

This field is present only in case when basic option is activated.

It has the following format:

Bit	1	2	3	4	5	6	7	8
	E/A	L1	L2	L3	L4	L5	L6	L7

Figure 3: Length field, first byte

The L1 to L7 bits indicates the length of the following data field. The default length is 31 bytes.

According to the rule of ISO/IEC 13239:1997, the range of the length field may be extended by use of the EA bit. When the EA bit is set to 1 in an octet, it signifies that this octet is the last octet of the length field. When the EA bit is set to 0, it signifies that a second octet of the length field follows. The total length of the length field is in that case 15bits, L1-L15.

The second octet of the length field (only present when the EA field in the first byte is set to 1) format:

Bit	1	2	3	4	5	6	7	8
	L8	L9	L10	L11	L12	L13	L14	L15

Figure 4: Length field, second byte

5.2.1.6 Frame Checking Sequence Field (FCS)

The FCS shall be the ones complement of the sum (modulo 2) of

- a) the remainder of

$$x^k (x^7 + x^6 + x^5 + x^4 + x^3 + x^2 + x^1 + 1)$$

divided (modulo 2) by the generator polynomial

$$x^8 + x^2 + x + 1,$$

where k is the number of bits in the frame existing between, but not including, the final bit of the opening flag and the first bit of the FCS, excluding start and stop elements (start/stop transmission), and bits (synchronous transmission) and octets (start/stop transmission) inserted for transparency, and

b) the remainder of the division (modulo 2) by the generator polynomial

$$x^8 + x^2 + x + 1$$

of the product of x^8 by the content of the frame existing between, but not including, the final bit of the opening flag and the first bit of the FCS, excluding start and stop elements (start/stop transmission), and bits (synchronous transmission) and octets (start/stop transmission) inserted for transparency.

As a typical implementation, at the transmitter, the initial content of the register of the device computing the remainder of the division is preset to all ones and is then modified by division by the generator polynomial (as described above) of the address, control and information fields; the ones complement of the resulting remainder is transmitted as the 8-bit FCS.

At the receiver, the initial content of the register of the device computing the remainder is preset to all ones. The final remainder after multiplication by x^8 and then division (modulo 2) by the generator polynomial

$$x^8 + x^2 + x + 1$$

of the serial incoming protected bits and the FCS, will be 1111 0011 (x^7 through x^0 , respectively) in the absence of transmission errors.

In the case of the UIH frame the FCS is calculated on the contents of the address and control fields only. This means that the I-field is not protected but does permit pre-calculation of the FCS for the repertoire of DLCIs that are to be used. The FCS is calculated in the normal manner for all other frames in Table 2.

5.2.2 Format Conventions

All transmitted characters will be sent using one start bit, eight data bits, no parity bit and one stop bit.

In the field descriptions, bit 1 is transmitted first.

Addresses, commands, responses and sequence numbers shall be transmitted low-order bit first (for example, the first bit of the sequence number that is transmitted shall have the weight 2^0).

The FCS shall be transmitted to the line commencing with the coefficient of the highest term.

NOTE: The use of these conventions in this Specification means that octet values are often expressed in the reverse bit order from conventions used in many other standards. The conventions are used here because of the importance of the correct order of bit transmission; care should be taken during implementation.

5.2.3 Frame Validity

An invalid frame in the frame format is one which meets any one (or more) of the following conditions:

- is not properly bounded by two flags;
- does not have at least three octets between flags after removal of characters inserted for transparency;
- indicates presence of a transmission error in that the FCS check fails;
- contains an address field with more than one octet.

Invalid frames shall be discarded without notification to the sender. Actions taken by the multiplexer to indicate reception of an invalid frame to the MS or TE are left to implementors. However, an indication that a frame with an FCS error has been received may be of use when supporting DLCs for voice/audio.

As an optional procedure in response to an invalid frame in error recovery mode, a receiver may transmit an REJ frame.

5.2.4 Frame Abort

Aborting a frame is not supported.

5.2.5 Inter-frame Fill

The time between frames shall be filled by sending continuous stop-polarity except in the case of the wake-up procedure (see subclause 5.4.7). The receiver shall also operate correctly if the time between frames is filled with flag characters. If a receiver receives more than three consecutive flags it shall begin to transmit continuous flags at the first available time (see subclause 5.4.7)

5.2.6 Basic Option

In this case, opening flag and closing flags may appear in the Information field of the frame. The flags cannot be used to determine beginning and end of a frame. A length indication for the frame must be given instead. The frame structure is then as follows:

Flag	Address	Control	Length Indicator	Information	FCS	Flag
0111 1101	1 octet	1 octet	1or2 octets	Unspecified length but integral number of octets	1 octet	0111 1101

Figure 5: Frame Structure for Basic option

5.2.6.1 Constraint

The closing flag may also be the opening flag of the following frame.

The flag value is different from the one used when the advanced option is activated.

Operation on link using DC1/XON and DC3/XOFF control characters defined in ISO/IEC 646 is not supported.

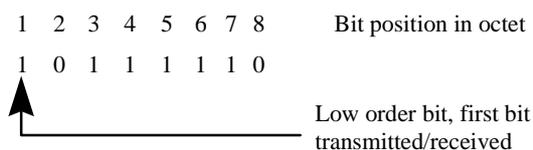
5.2.7 Advanced Option

If the advanced option is activated at the beginning of the multiplexing session, then it is used for all frames. This mechanism is based on a control octet transparency. It is based on a unique appearance of the opening and the closing flag in each frame. These flags will never appear in the information field of the frame. This mechanism allows a very quick synchronisation if a loss of synchronisation has occurred on the TE-MS link.

5.2.7.1 Control-octet transparency

The following transparency mechanism shall be applied to each frame from address field to FCS field inclusive.

The control escape octet is a transparency identifier that identifies an octet occurring within a frame to which the following transparency procedure is applied. The encoding of the control escape octet is:



The transmitter shall examine the frame between the opening and closing flag sequences including the address, control, and FCS fields and, following completion of the FCS calculation, shall:

- Upon the occurrence of the flag or a control escape octet, complement the 6th bit of the octet, and
- Insert a control escape octet immediately preceding the octet resulting from the above prior to transmission.

The receiver shall examine the frame between the two flag octets and shall, upon receipt of a control escape octet and prior to FCS calculation:

- Discard the control escape octet, and
- Restore the immediately following octet by complementing its 6th bit.

Other octet values may optionally be included in the transparency procedure by the transmitter. Such inclusion shall be subject to prior system/application agreement.

5.2.7.2 Start/stop transmission - extended transparency

The transmitter may apply the above transparency procedure to other octets in addition to the flag and control escape octets. At present, the only other octets are flow-control characters. The procedure is described in subclause 5.2.6.3.

5.2.7.3 Flow-control transparency

The flow-control transparency option provides transparency processing for the DC1/XON and DC3/XOFF control characters defined in ISO/IEC 646 (i.e., 1000100x and 1100100x, respectively, where x may be either 0 or 1). This has the effect of assuring that the octet stream does not contain values which could be interpreted by intermediate equipment as flow control characters (regardless of parity).

5.2.7.4 Frame Structure

The frame structure is shown in Figure 6. Note that this structure does not include information added for synchronisation (i.e. Start and stop bits) or transparency purposes. The order of transmission is from left to right.

In case the Transparency mechanism is activated, the frame structure is as follows:

Flag	Address	Control	Information	FCS	Flag
0111 1110	1 octet	1 octet	Unspecified length but integral number of octets	1 octet	0111 1110

Figure 6: Frame Structure for Advanced option

NOTE: The closing flag may also be the opening flag of the following frame.

5.3 Frame Types

5.3.1 Set Asynchronous Balanced Mode (SABM) command

The SABM command shall be used to place the addressed station in the Asynchronous Balanced Mode (ABM) where all control fields shall be one octet in length. The station shall confirm acceptance of the SABM command by transmission of a UA response at the first opportunity. Upon acceptance of this command, the DLC send and receive state variables shall be set to zero.

5.3.2 Unnumbered Acknowledgement (UA) response

The UA response shall be used by the station to acknowledge the receipt and acceptance of SABM and DISC commands.

5.3.3 Disconnected Mode (DM) response

The DM response shall be used to report a status where the station is logically disconnected from the data link. When in disconnected mode not commands are accepted until the disconnected mode is terminated by the receipt of a SABM command. If a DISC command is received while in disconnected mode a DM response should be sent.

5.3.4 Disconnect (DISC) command

The DISC command shall be used to terminate an operational or initialization mode previously set by a command. It shall be used to inform one station that the other station is suspending operation and that the station should assume a logically disconnected mode. Prior to actioning the command, the receiving station shall confirm the acceptance of the DISC command by the transmission of a UA response.

5.3.5 Unnumbered information with header check (UIH) command and response

The UIH command/response shall be used to send information without affecting the V(S) or V(R) variables at either station. UIH is used where the integrity of the information being transferred is of lesser importance than its delivery to the correct DLCI. For the UIH frame, the FCS shall be calculated over only the address and control fields.

Reception of the UIH command/response is not sequence number verified by the data link procedures; therefore, the UIH frame may be lost if a data link exception occurs during transmission of the protected portion of the command, or duplicated if an exception condition occurs during any reply to the command. There is no specified response to the UIH command/response.

5.3.6 Unnumbered Information (UI) command and response

The UI command/response shall be used to send information without affecting the V(S) or V(R) variables at either station.. Reception of the UIH command/response is not sequence number verified by the data link procedures; therefore, the UIH frame may be lost if a data link exception occurs during transmission of the protected portion of the command, or duplicated if an exception condition occurs during any reply to the command. There is no specified response to the UI command/response.

For the UI frame, the FCS shall be calculated over all fields (Address, Control, Length Indicator, Information).

Support of UI frames is optional.

5.4 Procedures and States

5.4.1 DLC Establishment

In most cases the establishment of a DLC will be initiated by the TE, however, the protocol is balanced and the initiation may come from the MS. The action taken by the higher layers of the TE upon the initiation of the establishment of a DLC from the MS is outside the scope of this specification.

The station wishing to establish a DLC transmits a SABM frame with the P-bit set to 1. The address field contains the DLCI value associated with the desired connection. If the responding station is ready to establish the connection it will reply with a UA frame with the F-bit set to 1. If the responding station is not ready or unwilling to establish the particular DLC it will reply with a DM frame with the F-bit set to 1.

Once a DLC has been established the stations are both said to be in a connected mode, for the particular DLC, and transfer of information may commence.

If no UA or DM response has been received after T1 the initiating station may retransmit the SABM. This action may be repeated until a response is obtained or action is taken by a higher layer.

If no negotiation procedure is used, DLC parameters are the default one.

5.4.2 DLC Release

The release of a DLC may be initiated by either station by the transmission of a DISC frame with the P-bit set to one. Confirmation of the DLC release is signalled by the other station sending a UA frame with the F-bit set to 1. Once the DLC has been released the stations enter disconnected mode for that particular DLC.

If the station receiving the DISC command is already in a disconnected mode it will send a DM response.

If no UA or DM response has been received after T1 the initiating station may retransmit the DISC. This action may be repeated until a response is obtained or action is taken by a higher layer.

5.4.3 Information Transfer

5.4.3.1 Information Data

Information is conveyed using UI or UIH frames. Support of UIH frames is mandatory and support of UI frames is optional. UI frames are used when it is important to know that data received is correct. An example of the use of UI frames is in carrying IP (Internet Protocol) traffic where error recovery procedures are performed, if necessary, by a higher layer. The use of UIH frames is appropriate if the link is not subject to errors. UI or UIH frames may also be used for data in situations where the delays inherent in error-recovery procedures are unacceptable, such as transmission of voice data.

The transmitter takes information from the convergence layer for the particular DLC and places it in the I-field of the transmitted frame. Once a UI or UIH frame has been correctly received, the contents of its I-field is passed to the convergence layer.

The frames sent by the initiating station have the C/R bit set to 1 and those sent by the responding station have the C/R bit set to 0. Both stations set the P-bit to 0.

The maximum length of the information field in UI or UIH frames shall be parameter N1 (see subclause 5.7.2).

5.4.3.2 Priority

Each data stream has a priority associated with it. The priority is a number in the range 0-63 with lower numbers having higher priority. The TE assigns a priority to each DLC and informs the MS of the priority by means of the multiplexer control channel (see subclause 5.4.6.3.1). In the absence of a message assigning priorities DLCs shall be given the priority 1. The transmitter is in control of which frames are transmitted and how they are constructed and it is not intended to specify precisely how this task is performed. If data of higher priority than that currently being transmitted is waiting the transmitter has several options available:

- a) complete the transmission of the current frame, or
- b) terminate the assembly of the current frame by sending the current FCS and terminating flag (only for Advanced option),

and start sending the frame of higher-priority data.

Handling of DLC with equal priorities should not favour one over the others. The DLC with the highest priority shall not block any of the lower priorities DLC. Interleaving of higher priority and lower priority frames is necessary in order to avoid permanent blocking of lower priority channels. Optimization of this interleaving for a specific implementation may have a significant impact on the application in use and therefore implementators are encouraged to consider this carefully.

5.4.4 Frame Variables

The poll (P) bit set to 1 shall be used by a station to solicit (poll) a response or sequence of responses from the other station.

The final (F) bit set to 1 shall be used by a station to indicate the response frame transmitted as the result of a soliciting (poll) command.

The poll/final (P/F) bit shall serve a function in both command frames and response frames. (In command frames, the P/F bit is referred to as the P bit. In response frames, it is referred to as the F bit.)

5.4.4.1 Functions of the poll bit

The P bit set to 1 shall be used to solicit a response frame with the F bit set to 1 from the other station at the earliest opportunity.

On a particular DLCI, only one frame with a P bit set to 1 shall be outstanding in a given direction at a given time. Before a station issues another frame with the P bit set to 1, it shall have received a response frame from the other station with the F bit set to 1. If no valid response frame is obtained within a system-defined time-out period, the retransmission of a command with the P bit set to 1 for error recovery purposes shall be permitted.

5.4.4.2 Functions of the final bit

A response frame with the F bit set to 1 shall be used by a station to acknowledge the receipt of a command frame with the P bit set to 1. The response shall be made at the earliest opportunity.

The station may transmit response frames with the F bit set to 0 at any opportunity on an asynchronous basis.

If a station receives a command with the P bit set to 1, transmission of a response with the F bit set to 1 shall take precedence over transmission of other commands, with the exception of the mode setting commands (SABM or DISC).

5.4.5 Time-out considerations

In order to detect a no-reply or lost-reply condition, each station shall provide a response time-out function (T1). The expiry of the time-out function shall be used to initiate appropriate error recovery procedures.

The duration of the time-out function in the two stations shall be unequal in order to resolve contention situations.

The time-out function shall be started whenever a station has transmitted a frame for which a reply is required. When the expected reply is received, the time-out function shall be stopped. If, during the interval that the time-out function is running, other frames are sent for which acknowledgements are required, the time-out function may have to be restarted.

If the response time-out function runs out, a command with the P bit set to 1 may be (re)transmitted, and the response time-out function restarted.

5.4.6 Multiplexer Control Channel

At the initiation of communication between the TE and MS a control channel is set up with DLCI 0 using the procedures of subclause 5.8.1. This channel is used to convey information between the two multiplexers. The control channel may use either error recovery mode or non-error recovery mode procedures as defined by the +CMUX command (GSM 07.07). If error recovery mode procedures are available they should be used.

5.4.6.1 Message format

All messages sent between the multiplexers conform to the following type, length, value format:



Each box in the diagram represents a field of minimum size one octet. The type and length octets have extension bits so those fields may contain more than one octet.

The first type field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	T1	T2	T3	T4	T5	T6

Subsequent type field octets have the following format:

Bit	1	2	3	4	5	6	7	8
	EA	T7	T8	T9	T10	T11	T12	T13

The EA bit is an extension bit. The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

The C/R bit indicates whether the message is a command or a response.

The T bits indicate the type coding. Each command has a unique pattern of bits. This means that a single-octet type field can encode 63 different message types. Only single octet message types are defined in this specification.

The first length field octet has the following structure:

Bit	1	2	3	4	5	6	7	8
	EA	L1	L2	L3	L4	L5	L6	L7

Subsequent length field octets have the same structure.

The EA bit is an extension bit. The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

The L bits define the number of value octets that follow. In the case of a single-octet length field L1 is the LSB and L7 is the MSB; this permits messages with up to 127 value octets to be constructed.

The contents of the value octets are defined for each message type in subclause 5.4.6.3.

Multiple messages may be included in the same frame (as long as the maximum frame size is not exceeded). Messages may not be split over more than one frame.

5.4.6.2 Operating procedures

Messages always exist in pairs; a command message and a corresponding response message. If the C/R bit is set to 1 the message is a command, if it is set to 0 the message is a response. A response message has the same T bits as the command that provoked it.

If a command does not produce a response within a time T2 the command may be sent again up to N2 times. If no response is received on the N2 transmissions, the multiplexer control channel should be considered faulty and an alarm raised. Resolution of the error situation is implementation dependent.

5.4.6.3 Message Type and Actions

5.4.6.3.1 DLC parameter negotiation (PN)

This procedure is optional. If this command is not supported, default values are applied to each DLC.

Before a DLC is set up using the mechanism in subclause 5.4.1, the TE and MS must agree on the parameters to be used for that DLC. These parameters are determined by parameter negotiation.

The parameter negotiation uses the following type field octet:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	0	0	1

The length field octet contains the value 8 and there follow eight value octets. The value octets contain the information in Table 3.

Table 3: Parameter Negotiation

Value Octet	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
1	D1	D2	D3	D4	D5	D6	0	0
2	I1	I2	I3	I4	CL1	CL2	CL3	CL4
3	P1	P2	P3	P4	P5	P6	0	0
4	T1	T2	T3	T4	T5	T6	T7	T8
5	N1	N2	N3	N4	N5	N6	N7	N8
6	N9	N10	N11	N12	N13	N14	N15	N16
7	NA1	NA2	NA3	NA4	NA5	NA6	NA7	NA8
8	K1	K2	K3	0	0	0	0	0

The various fields are coded as follows:

The D-bits define the DLCI that the other information refers to; Bit D1 is the least significant.

The I-bits define the type of frames used for carrying information in the particular DLC - See Table 4.

Table 4: Meaning of I-bits

Meaning	I1	I2	I3	I4
Use UIH frames	0	0	0	0
Use UI frames	1	0	0	0
Use I frames (note)	0	1	0	0

NOTE: Refere to clause 6

Other values are reserved. Default value is 0000.

In the absence of negotiation the frame type used (for DLCI>0) is the same as used by the multiplexer control channel.

The CL-bits define the type of convergence layer to be used on the particular DLCI - see Table 5.

Table 5: Meaning of CL-bits

Meaning	CL1	CL2	CL3	CL4
Type 1	0	0	0	0
Type 2	1	0	0	0
Type 3	0	1	0	0
Type 4	1	1	0	0

Other values are reserved. Default value is 0000

The P-bits define the priority to be assigned to the particular DLC. The range of values is 0 to 63 with 0 being the lowest priority. P1 is the least significant bit. Default value for P-bits are given by the DLCI values. See subclause 5.6.

The T-bits define the value of the acknowledgement timer (T1) - see subclause 5.7.1. The units are hundredths of a second and T1 is the least significant bit.

The N-bits define the maximum frame size (N1) - see subclause 5.7.2. The parameter is a sixteen-bit number with N1 as the least significant bit.

The NA-bits define the maximum number of retransmissions (N2) - see subclause 5.7.3. The parameter is an eight-bit number with NA1 as the least significant bit.

The K-bits define the window size for error recovery mode (k) - see subclause 5.7.4. The parameter is a three-bit number with K1 as the least significant bit.

The TE transmits a parameter negotiation command to the MS with the fields set to the values that the TE intends to use for the particular DLCI. The MS replies with a parameter negotiation response with its proposed set of values. The following rules must be observed by the MS in constructing its response:

- The DLCI value may not be changed.
- The use of I frames or UI frames is optional so an MS may respond with a UIH choice if it does not implement UI frames or I frames.
- The MS may not change the convergence layer proposed by the TE.
- The MS may not change the priority proposed by the TE.
- The T1 value is the one that the TE will use and is not negotiable; the MS will insert its own T1 value. It is advisable that different T1s are used in each direction.

- The MS may propose a smaller value for maximum frame size (N1) if it has insufficient memory to handle the size proposed.
- The N2 value is the one that the TE will use and is not negotiable; the MS will insert its own N2 value.
- The MS may propose a smaller value for window size (k) if it has insufficient memory to handle the size proposed.

If the TE considers the response from the MS to be acceptable the TE will start to establish the DLC in accordance with the procedures of subclause 5.3.1. If the response is not acceptable the TE may initiate another parameter negotiation command with revised parameters or pass the failure information to a higher layer.

If an incoming call arrives at the MS from the network for which no DLC has been set up, the MS may initiate the parameter negotiation procedure and set up a DLC. This situation should not occur in practice since a TE will generally set up DLCs for all the functions it shares with the MS after the capabilities exchange. The indication of an incoming call will be through an 07.07 or 07.05 result code.

5.4.6.3.2 Power Saving Control (PSC)

(see also subclause 5.4.7)

The power saving control messages use the following type field octet:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	0	1	0

The length byte contains the value 0 and there are no value octets.

If a station wishes to enter a low-power state it transmits a power saving control command; the other station replies with a power saving control response.

If a station wishes to request that the other station enter a low-power state it sends a power saving control command; the other station replies with a power saving control response. The responding station may enter a low-power state but need not do so.

5.4.6.3.3 Multiplexer close down (CLD)

(see also subclause 5.8.2)

The multiplexer close down command is used to reset the link into normal AT command mode without multiplexing.

The multiplexer close down messages use the following type field octet:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	0	1	1

The length byte contains the value 0 and there are no value octets.

5.4.6.3.4 Test Command (Test)

The test command is used to test the connection between MS and the TE. The length byte describes the number of values bytes, which are used as a verification pattern. The opposite entity shall respond with exactly the same value bytes.

The type field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	0	0

5.4.6.3.5 Flow Control On Command (FCon)

The flow control command is used to handle the aggregate flow. When either entity is able to receive new information it transmits this command.

The length byte contains the value 0 and there are no value octets

The type field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	0	1

5.4.6.3.6 Flow Control Off Command (FCoff)

The flow control command is used to handle the aggregate flow. When either entity is not able to receive information it transmits the FCoff command. The opposite entity is not allowed to transmit frames except on the control channel (DLC=0).

The length byte contains the value 0 and there are no value octets

The type field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	1	0

5.4.6.3.7 Modem Status Command (MSC)

It is desired to convey virtual V.24 control signals to a data stream, this is done by sending the MSC command. The MSC command has one mandatory control signal byte and an optional break signal byte. This command is only relevant when the basic option is chosen.

This command shall be sent prior to any user data after a creation of a DLC.

Command	Length	DLCI	V.24 signals	Break Signals (optional)
---------	--------	------	--------------	--------------------------

The length byte contains the value 2 or 3 and there are 2 or 3 value octets.

Both the DTE and DCE uses this command to notify each other of the status of their own V.24 control signals. The length of the Modem Status Command is either 4 or 5 bytes depending on the break signal.

The command field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	1	1

The C/R bit is used to indicate if it is a Modem Status Command or Modem Status Response.

Every time the signals change, the DTE or DCE sends this command to indicate the current status of each signal. When a DTE or DCE receives a Modem Command it always sends a Response back. The mappings of the V.24 signals to the bits in the control signal octet for the receiver and sender are given in tables 6 and 7, respectively.

In a Modem Status Command it is the status of the sender's own V.24 signals that shall be sent, but in a Response it is copy of the V.24 signals that are received from the Command frame that shall be returned.

The DLCI field identifies the specific DLC to which the command applies. Bit 2 is always set to 1 and the EA bit is set according to the description in subclause 5.2.1.2.

Bit No.	1	2	3	4	5	6	7	8
	EA	1	D		L	C	I	

Figure 7: Format of Address Field

The length field is followed by the control signals field which contains a representation of the state of the signals in accordance with Figure 8. The use of the extension bit allows other octets to be added to cater for other circumstances. At present, an optional second octet is defined for handling the transmission of break signals.

Bit No	1	2	3	4	5	6	7	8
Signal	EA	reserved 0	RTC	RTR	reserved 0	reserved 0	IC	DV

Figure 8: Format of control signal octet

Description of the control signal byte:

Bit 1. The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

Bit 2. Reserved for future use. Set to zero by the sender, ignored by the receiver.

Bit 3. Ready To Communicate (RTC). The bit is set to 1 when the device is ready to communicate.

Bit 4. Ready To Receive (RTR). The bit is set to 1 when the device is ready to receive data.

Bit 5. Reserved for future use. Set to zero by the sender, ignored by the receiver.

Bit 6. Reserved for future use. Set to zero by the sender, ignored by the receiver.

Bit 7. Incoming call indicator (IC). The bit is set to 1 to indicate an incoming call.

Bit 8. Data Valid (DV). The bit is set to 1 to indicate that valid data is being sent.

The control byte is mapped to V.24 signals according to the tables below:

Table 6: Mapping from the control signal octet by a receiving entity

Control Signal Byte bit number, name	DTE receiving		DCE receiving	
	signal	V.24 circuit	signal	V.24 circuit
3, RTC	DSR	107	DTR	108/2
4, RTR	CTS	106	RFR (note)	133
7, IC	RI	125	-ignored	-
8, DV	DCD	109	-ignored	-

NOTE. Circuit 133, RFR (Ready for Receiving) is commonly assigned to the connector pin that is alternatively used for circuit 105, RTS. It is sometimes referred to by that name.

Table 7: Mapping to the control signal octet by a sending entity

Control Signal Byte bit number, name	DTE sending		DCE sending	
	signal	V.24 circuit	signal	V.24 circuit
3, RTC	DTR	108/2	DSR	107
4, RTR	RFR (note)	133	CTS	106
7, IC	always 0-	-	RI	125
8, DV	always 1-	-	DCD	109

NOTE. Circuit 133, RFR (Ready for Receiving) is commonly assigned to the connector pin that is alternatively used for circuit 105, RTS. It is sometimes referred to by that name.

If a station is unable to transmit frames because of flow control but wishes to stop accepting further frames itself, it may still send frames containing no user data (i.e. Only the control signal octet and, optionally, the break signal octet) in order to signal flow control.

The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

Bit No	1	2	3	4	5	6	7	8
Signal	EA	B1	B2	B3	L1	L2	L3	L4

Figure 9: Format of Break signal octet (Optional)

The break signal octet carries information about a break signal detected in the data stream for the DLC. The meanings of the bits are shown in Table 8.

Table 8: Break signal octet meanings

Bit	Value	Meaning
B1	1	Octet encodes a break signal
	0	Octet does not encode a break signal
B2	0	reserved: set to 0 by sender, ignored by receiver
B3	0	reserved: set to 0 by sender, ignored by receiver
L1-L4	4-bit value	Length of break in units of 200ms

L1 is the least significant bit and L4 is the most significant bit of the break length.

When a station receives a break octet it shall process the information and pass it on in an appropriate way. This is outside the scope of this Specification.

5.4.6.3.8 Non Supported Command Response (NSC)

This response is sent whenever a command type is not supported by the receiving entity.

The length byte contains the value 1 and there is one value octets.

The type field octet has the following format:

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	1	0	0	0

The value octet contains the Command Type of the non supported command.

5.4.6.3.9 Remote Port Negotiation Command (RPN)

Note: This command is reserved for future use. The description below is only included into this specification to show the type of functionality that this command will cover.

This command is optional.

This command is used for set the remote port communication settings.

All devices must assure that the communication settings are correctly set, prior sending data. There are default values assigned on all parameters, if no negotiation is performed, the default value is chosen.

During a connection, a device must send the RPN whenever the communication settings are changed. The same applies for the Port Line Status.

The Remote Port Negotiation Command use the following type field octet:

Table 9: Type field octet

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	1	0

The length byte contains the value 1 or 3 and there are one or three value octets.

Table 10: DLCI octet

Bit No.	1	2	3	4	5	6	7	8
	EA	C/R	D		L	C	I	

The C/R bit is not used and always set to 0, the EA bit is according to the description in subclause 5.2.1.2.

Table 11: Port Value Octets

Value Octet	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
1	B1	B2	B3	B4	B5	B6	B7	B8
2	D1	D2	S	P	PT1	PT2	res	res

A device transmits a remote port negotiation command to the other device with the fields set to the desired values. When the remote port negotiation command is received, the responding station replies according to the following rules:

The DLCI value may not be changed.

The receiver may select a subset of the Port Value Octet bits proposed by the sender, but not a superset. It is the receiver's selection that is the valid one. If the receiver does not support any of the proposed values, it replies with the Port Value Octet bits all set to zero.

If no value bytes are included in the command, it is interpreted as a request, and the receiver shall respond with all possible Port Values.

If the sender considers the response to be acceptable, that is, the bits match, the sender will start to use the DLC according to the Port Value Octets. If the response is not acceptable the sender may initiate another remote port negotiation command with revised parameters until a final agreement is reached or pass the failure information to a higher layer.

The B1-B8 indicates the baudrate, see table below:

Table 12: Meaning of B-bits

Meaning	B1	B2	B3	B4	B5	B6	B7	B8
2400 bps	0	0	0	0	0	0	0	0
4800 bps	1	0	0	0	0	0	0	0
7200 bps	0	1	0	0	0	0	0	0
9600 bps	1	1	0	0	0	0	0	0
19200 bps	0	0	1	0	0	0	0	0
38400 bps	1	0	1	0	0	0	0	0
57600 bps	0	1	1	0	0	0	0	0
115200 bps	1	1	1	0	0	0	0	0
230 400 bps	0	0	0	1	0	0	0	0

All other values of the B-bits are reserved.

The default value is 1100 0000 (9600).

The D1-D2 indicates the number of data bits:

D1, D2

00 5 bits

01 6 bits

10 7 bits

11 8 bits - default

The S bit indicate number of stop bits: S=0: 1 stop bit, S=1: 1,5 stop bits. Default value = 0 (1 stop bit)

The P bit indicate the parity. P=0: no parity, P=1: parity. Default value = 0 (no parity)

The PT1 - PT2 indicates the parity type:

PT1,PT2

00 odd parity

01 even parity

10 mark parity

11 space parity

All reserved values are set to 0 (zero) by the sender and ignored by the receiver.

5.4.6.3.10 Remote Line Status Command(RLS)

Note: This command is reserved for future use. The description below is only included into this specification to show the type of functionality that this command will cover.

This command is optional.

This command is used for indicate remote port line status.

During a connection, a device must send the RLS whenever the Remote Port Line Status are changed.

The Remote Line Status command use the following type field octet:

Table 13: Type field octet

Bit	1	2	3	4	5	6	7	8
	EA	C/R	0	0	0	1	1	1

The length byte contains the value 2 and there are two value octets.

Table 14: DLCI octet

Bit No.	1	2	3	4	5	6	7	8
	EA	C/R	D		L	C	I	

The C/R bit is not used and always set to 0, the EA bit is according to the description in subclause 5.2.1.2.

Table 15: Remote Line Status Octets

Value Octet	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
1	L1	L2	L3	L4	res	res	res	res

A device transmits a remote line status command to the other device with the fields set to the desired value. When the remote line status command is received, the remote device must respond with a Remote Line Status Response containing the values that it received.

The L1-L4 bits indicates the Line Status. If L1 is set to 0, no error have occurred. L1 = 1 indicates the following errors:

L2-L4:

- 100 Overrun Error - Received character overwrote an unread character
- 010 Parity Error - Received character's parity was incorrect
- 001 Framing Error - a character did not terminate with a stop bit

The res bits are set to zero for the sender and ignored by the reciever.

5.4.6.3.11 Service Negotiation Command (SNC)

This command is used to query and set a specific service on a specific DLC. It is for instance used to set specific digital voice types.

In some situations it is not very suitable to mix AT commands and raw data on the same DLC. For those situations, special DLCs can be established and converted to carry a specific data type. Examples of situation where this is especially useful is for voice transportation, where the AT commands controlling the connection (for instance for multiparty) are transported on one DLC and voice data carried by another DLC. This mechanism can be seen as an alternative to sending escape sequences with AT commands in the data flow. If this command is not used, the DLC is by default set to normal AT command mode. If this command is used, the DLC indicated in the DLCI octet, is converted to carry the specific data type. The originator if this command may also query the specific service on each DLCI.

The service negotiation messages use the following format:

Table 16: Service Negotiation Command format

Byte No.	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>
	Type field code	Length	DLCI	Service Value octet (optional)	Voice Codec Value octet (optional)

The type field octet:

Table 17: Type field octet

Bit	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>	<u>8</u>
	EA	C/R	0	0	0	1	0	1

The length byte contains the value 1 or 3 and there are one or three value octets.

Table 18: DLCI octet

Bit No.	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>	<u>8</u>
	EA	C/R	D		L	C	I	

The C/R bit is always set to 0 and the EA bit is according to the description in subclause 5.2.1.2.

Table 19: Service Value Octets

Value Octet	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
1	EA	S1	S2	S3	S4	S5	S6	S7

The EA bit is according to the description in subclause 5.2.1.2.

Table 20: Voice Codec Value Octets

Value Octet	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
1	EA	V1	V2	V3	V4	V5	V6	V7

The EA bit is according to the description in subclause 5.2.1.2

Table 21: Service Value Bits

Value Bit	Service
S1	Data
S2	Voice
S3	Reserved
S4	Reserved
S5	Reserved
S6	Reserved
S7	Reserved

Table 22: Voice Codec Value Bits

Value Bit	Service
V1	Voice (coded – GSM 06.21)
V2	Voice (coded - PCM 64 kbit/s U-law)
V3	Voice (coded ADPCM 32kbit/s) ITU-T G.726
V4	Voice (coded halfrate)
V5	Voice (coded - PCM 64kbit/s A-law)
V6	Voice (coded PCM 128kbit/s)
V7	Reserved

The sender transmits a service negotiation command with the fields set to the values for all possible services it may use for the particular DLC. The receiver replies with a service negotiation response with its selected set of values. The following rules must be observed by the receiver in constructing its response:

The DLCI value may not be changed.

The receiver may select a subset of the services proposed by the sender, but not a superset. It is the receiver's selection that is the valid one. If the receiver does not support any of the proposed services, it replies with the service byte set to zero.

The Voice Codec Value Octet is always present even though data service is chosen. In this case, the Voice Codec Value Octet V1-V7 bits are set to zero,

A zero value means standard AT command mode.

If no value bytes are included in the command, it is interpreted as a request, and the receiver shall respond with all possible services.

If the sender considers the response to be acceptable, that is, the service bits match, the sender will start to use the DLC according to the services. If the response is not acceptable the sender may initiate another parameter negotiation command with revised parameters until a final agreement is reached or pass the failure information to a higher layer.

If no service negotiation has been performed on the DLCs, it operates in standard AT mode. In this case, an incoming call is indicated on that DLC.

The sender shall set a reserved bit to value 0. The receiver shall ignore a reserved bit.

5.4.7 Power Control and Wake-up Mechanisms

It is very important in many types of MS and some TE that the power consumed by the equipment is minimised. This aim is often achieved by entering various power-saving states under conditions of inactivity, for example. The

multiplexer system must be able to close down cleanly if either TE or MS wish to enter a low-power state. This is achieved by the use of the multiplexer control channel.

If either TE or MS wishes to enter a low-power state a power saving control command message is sent to the other station on the multiplexer control channel. The station receiving the message will complete the transmission of any frames in progress, report a busy or power-down condition to higher layers, freeze all timers and transmit the power saving control response message. When the station that initiated the power saving control message receives the acknowledgement it is then free to enter the reduced-power state.

Either station may send a power saving control command requesting that the other station enters a low power state. The responding station must acknowledge this command with a power saving control response message but need not obey the command to enter a low-power state. If no response is received the commanding station may repeat the command but must first use the wake-up procedure.

Either station may initiate a wake-up from the reduced power state by the transmission of the wake-up signal which consists of continuous flag characters. When the other station receives the flag characters it will wake-up (if necessary) and start sending flag characters. When the first station receives these flag characters it will stop sending flags and start transmitting the first frame. When the second station detects a valid frame it stops sending flags. The stations unfreeze their timers and continue operation as before.

If no response (continuous flags) is received to the wake-up procedure within time T3, an alarm should be raised to the higher layers and transmission of flags stops.

5.5 Convergence Layers

Convergence layers are defined to permit data which has implied structure to be conveyed through the multiplexer without losing the structure or other parameters which are associated with the data stream. Common uses of convergence layers are to carry the state of V.24 control signals through a DLC or to ensure that the boundaries of a coded voice frame are preserved.

Convergence layers apply to data whether it is carried by error recovery mode or non-error recovery mode procedures.

The use of particular convergence layers is implicitly linked to the DLCIs used but may be negotiated away from these defaults by the use of the multiplexer control channel.

5.5.1 Type 1 - Unstructured Octet Stream

Data which consists of an unstructured sequence of octets, for example, 64 kbit/s unencoded voice or normal asynchronous data without V.24 control signals, is inserted directly into the I-field. In this case, it could be said that the convergence layer is null.

Type 1 is the default convergence layer for each DLC.

5.5.2 Type 2 - Unstructured Octet Stream with flow control, break signal handling and transmission of V.24 signal states

If it is desired to convey virtual V.24 control signals associated with a data stream the first octet of each I-field contains a representation of the state of the signals in accordance with Figure 10. The use of the extension bit allows other octets to be added to cater for other circumstances. At present, an optional second octet is defined for handling the transmission of break signals.

The mappings of the V.24 signals to the bits in the control signal octet for the receiver and sender are given in tables 23 and 24, respectively.

Bit No	1	2	3	4	5	6	7	8
Signal	EA	FC	RTC	RTR	reserv ed 0	reserv ed 0	IC	DV

Figure 10: Format of control signal octet

Description of the control signal byte:

Bit 1. The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

Bit 2. DLC (frame) Flow Control (FC). In non-ERM, it is set to 1 when the device is unable to accept frames. In ERM, it is always set to 0 by the sender and ignored by the receiver.

Bit 3. Ready To Communicate (RTC). The bit is set to 1 when the device is ready to communicate.

Bit 4. Ready To Receive (RTR). The bit is set to 1 when the device is ready to receive data.

Bit 5. Reserved for future use. Set to zero by the sender, ignored by the receiver.

Bit 6. Reserved for future use. Set to zero by the sender, ignored by the receiver.

Bit 7. Incoming call indicator (IC). The bit is set to 1 to indicate an incoming call.

Bit 8. Data valid (DV). The bit is set to 1 to indicate that valid data is being sent.

The control byte is mapped to V.24 signals according to the tables below:

Table 23: Mapping from the control signal octet by a receiving entity

Control Signal Byte bit number, name	DTE receiving		DCE receiving	
	signal	V.24 circuit	signal	V.24 circuit
2, FC	DLC flow control	-	DLC flow control	-
3, RTC	DSR	107	DTR	108/2
4, RTR	CTS	106	RFR (note)	133
7, IC	RI	125	ignored	-
8, DV	DCD	109	ignored	-

NOTE. Circuit 133, RFR (Ready for Receiving) is commonly assigned to the connector pin that is alternatively used for circuit 105, RTS. It is sometimes referred to by that name.

Table 24: Mapping to the control signal octet by a sending entity

Control Signal Byte bit number, name	DTE sending		DCE sending	
	signal	V.24 circuit	signal	V.24 circuit
2, FC	frame flow control	-	frame flow control	-
3, RTC	DTR	108/2	DSR	107
4, RTR	RFR (note)	133	CTS	106
7, IC	always 0	-	RI	125
8, DV	always 1	-	DCD	109

NOTE. Circuit 133, RFR (Ready for Receiving) is commonly assigned to the connector pin that is alternatively used for circuit 105, RTS. It is sometimes referred to by that name.

In non-error recovery mode, the FC bit provides frame flow control for the DLC. If a station is unable to accept further frames, for example, because of buffer management issues, it shall set FC to 1. When the station is again able to receive

frames it shall set FC to 0. If a station receives a frame with FC set to 1 it shall cease transmitting frames until it receives a frame with FC set to 0.

If a station is unable to transmit frames because of flow control but wishes to stop accepting further frames itself, or to signal a change in the control signals or a break condition it may still send frames containing no user data (i.e. containing only the control signal octet and, optionally, the break signal octet).

In error recovery mode the FC bit is not used and shall be set to 0 by the sender and ignored by the receiver. If a station has been prevented from sending I frames, for example, by receiving a RNR frame, it may still send a UI or UIH frame containing no user data if it wishes to signal a change in the control signals or a break condition.

The EA bit is set to 1 in the last octet of the sequence; in other octets EA is set to 0. If only one octet is transmitted EA is set to 1.

Bit No	1	2	3	4	5	6	7	8
Signal	EA	B1	B2	B3	L1	L2	L3	L4

Figure 11: Format of Break signal octet

The break signal octet carries information about a break signal detected in the data stream for the DLC. The meanings of the bits are shown in Table 25

Table 25: Break signal octet meanings

Bit	Value	Meaning
B1	1	Octet encodes a break signal
	0	Octet does not encode a break signal
B2	1	Discard data in buffers
	0	Do not discard data in buffers
B3	1	Transmit break signal onwards as soon as possible
	0	Transmit break signal onwards in sequence
L1-L4	4-bit value	Length of break in units of 200ms

L1 is the least significant bit and L4 is the most significant bit of the break length.

When a station receives a break octet it shall process the information and pass it on in an appropriate way. This is outside the scope of this Specification.

The remaining octets of the I-field contain data for that DLC.

5.5.3 Type 3 - Uninterruptible Framed Data

An example of uninterruptible framed data is coded voice data made up of a sequence of voice frames. It is important that coded voice frames reach the voice decoder with the frame structure intact and with the shortest possible delay. The simplest way of ensuring this is to map one complete voice frame into one I-field. This frame shall not be shortened during transmission even if data of higher priority is waiting.

At the transmitter each frame of data is inserted into the I field of an I frame, UI frame or UIH frame. The data shall not be spread over more than one frame and data from other frames must not be included in the I field. The receiver handles the data as a complete frame and passes it on as a complete frame.

Coded voice data should be transmitted using UI frames or UIH frames because the delays associated with re-transmissions are usually unacceptable.

5.5.4 Type 4 - Interruptible Framed Data

This type of convergence layer is used might be used to convey data which has an implied structure but where the delay is not as important as Type 3. The structured data may be segmented across several frames and re-assembled at the other station. PPP-framed IP data is an example of the type of data that could be carried over a Type 4 convergence layer.

The first octet of every Type 4 frame is a control octet and is defined in Figure 12.

Bit No	1	2	3	4	5	6	7	8
Signal	EA	-	-	-	-	-	B	F

Figure 12: Format of Type 4 octet

The EA bit is for future expansion if more than one octet is needed. It is set to 1 in the case described here.

The B and F bits are used to indicate whether the frame is the first frame in a sequence, a middle frame or the last frame. The meanings of the bits are as shown in Table 26.

Table 26: Meaning of B and F bits

B	F	Meaning
1	0	First frame of a sequence
0	0	Middle frame of a sequence
0	1	Last frame of a sequence
1	1	Data is contained entirely within one frame

NOTE 1: PPP-framed IP data can be carried using a Type 1 convergence layer if other framing structures, such as a layer 2 protocol, have already been included in the data stream.

NOTE 2: If a frame is coded as being the last frame or that all the data is contained within one frame, that frame may then not be shortened because shortening would make the meaning of the header incorrect. It may be advisable to construct the last frame of a sequence such that it contains no data and avoid the use of the 11 code if frame shortening is desired.

5.6 DLCI Values

All DLCs use a type 1 convergence layer by default; the use of other layers may be negotiated using the multiplexer control channel.

Table 27: DLCI Assignments

Usage	DLCI number (decimal)	Priority
Multiplexer control channel	0	0
AT commands (07.07 and 07.05)	1-7	7
AT commands (07.07 and 07.05)	8-15	15
AT commands (07.07 and 07.05)	16-23	23
AT commands (07.07 and 07.05)	24-31	31
AT commands (07.07 and 07.05)	32-39	39
AT commands (07.07 and 07.05)	40-47	47
AT commands (07.07 and 07.05)	48-55	55
AT commands (07.07 and 07.05)	56-62	63
Reserved	63	

DLCI value 63 is reserved and must not be allocated for ETSI purposes because of the special meaning in HDLC.

DLCI value 0 is reserved for the control channel.

5.7 System Parameters

The following system parameters are defined for the multiplexer. T1, N1, N2 and k may be negotiated by use of the multiplexer control channel or the default values given here should be used. T2 and T3 are set with the AT+CMUX command.

5.7.1 Acknowledgement Timer (T1)

The acknowledgement timer governs the amount of time that a station will wait for an acknowledgement before resorting to other action (e.g. transmitting a frame). The two stations may operate with different values of T1.

The units are hundredths of a second. Times of up to 25.5 seconds may be used.

The default value is 100 ms and the minimum is 10 ms.

5.7.2 Maximum Frame Size (N1)

N1 defines the maximum number of octets that may be contained in an information field. It does not include octets added for transparency purposes.

The default value is 64 octets when the advanced option activated and 31 octets when it is not activated. The range is 1 to 32768 octets.

NOTE: The maximum frame size should be chosen carefully particularly if a Type 2 convergence layer is being used. The frame must be large enough to contain a complete protocol frame.

5.7.3 Maximum number of retransmissions (N2)

N2 defines the maximum number of times that a station re-attempt a procedure requiring a response. The two stations may operate with a different value of N2.

The default value is 3 and the range is 0-255.

5.7.4 Window Size (k)

The window size parameter (k) defines the maximum number of I frames that a DLC can have outstanding (i.e. unacknowledged). Identical values need not be used for each direction. The window size may not be larger than 7.

This parameter is only applicable when Error Recovery Option is activated. See clause 6.

The default value is 2 and the range is 1-7

5.7.5 Response Timer for multiplexer control channel (T2)

The T2 timer is the amount of time the multiplexer control channel waits before retransmitting a command.

T2 must be greater than T1. The units are hundredths of a second. Times of up to 25.5 seconds may be used.

The default value is 300 ms and minimum 20 ms.

5.7.6 Response Timer for wake-up procedure(T3)

The T3 timer is the amount of time the transmitting station of a power wake-up command waits before raising an alarm when no response is received. The units are seconds. Times of up to 255 seconds may be used.

The default value is 10 s and minimum 1 s.

5.8 Start-up and close-down of multiplexer

5.8.1 Start-up procedure

Multiplexer operation is started by the use of the +CMUX command (see GSM 07.07). This command instructs the multiplexer to start up the multiplexer control channel (see subclause 5.8.1) using either error recovery mode or non-error recovery mode. The TE multiplexer initiates the establishment of the multiplexer control channel by sending a SABM frame on DLCI 0 using the procedures of subclause 5.4.1.

Once the multiplexer channel is established other DLCs may be established using the procedures of subclause 5.4.1. The multiplexers may negotiate the parameters associated with each DLC prior to establishment of a DLC or may use the defaults.

5.8.2 Close-down procedure

Initiation of the close-down will come from higher layers in either the TE or MS and is outside the scope of this specification. Once the command to close down is received the multiplexer will close down each DLC in turn using the procedures of subclause 5.4.2. When all DLCs (except the multiplexer control channel - DLCI 0) are closed down (disconnected mode) the multiplexer that initiated close-down procedure will send a close-down message on the multiplexer control channel. When this message is acknowledged both stations will revert to the non-multiplexed mode. If no response is received to the close-down command within time T2, the initiating station may retransmit it but must close down if no response message is received in time T3.

After closing of the multiplexer protocol, the MS and TE should revert to normal AT mode.

6 Error Recovery Mode Option

When the Advanced option is selected an error recovery mechanism may be used for better security. The error-recovery mode is optional and is intended for those cases where the quality of the TE-MS link can not be guaranteed and/or when the integrity of the data to be transmitted is critical. Some DLCs may use error recovery mode and some use non-error recovery mode on the same link.

error recovery mode uses I frames to carry the data; the procedures used are defined below.

New frames types and procedures are added.

6.1 Frame Types

Table 28: Coding of Control Field

Frame Type	1	2	3	4	5	6	7	8
I (Information)	0	N(S)			P/F	N(R)		
RR (Receive Ready)	1	0	0	0	P/F	N(R)		
RNR (Receive Not Ready)	1	0	1	0	P/F	N(R)		
REJ (Reject)	1	0	0	1	P/F	N(R)		

N(R) and N(S) are receive and send sequence numbers, respectively. They are described later in this document.

6.1.1 Information transfer, I, command and response

The function of the information, I, command and response shall be to transfer sequentially numbered frames, each containing an information field, across a data link.

The encoding of the I command/response control field shall be as shown in table 28.

The I frame control field shall contain two sequence numbers:

- N(S), send sequence number, which shall indicate the sequence number associated with the I frame; and
- N(R), receive sequence number, which shall indicate the sequence number (as of the time of transmission) of the next expected I frame to be received, and consequently shall indicate that the I frames numbered up to N(R) - 1 inclusive have been received correctly.

6.1.2 Receive ready, RR, command and response

The receive ready, RR, frame shall be used by a station to

- a) indicate that it is ready to receive an I frame; and
- b) acknowledge previously received I frames numbered up to $N(R) - 1$ inclusive.

When transmitted, the RR frame shall indicate the clearance of any busy condition that was initiated by the earlier transmission of an RNR frame by the same data station. See subclause 6.2.2.5.1.

6.1.3 Receive not ready, RNR, command and response

The receive not ready, RNR, frame shall be used by a station to indicate a busy condition; i.e., temporary inability to accept subsequent I frames. I frames numbered up to $N(R) - 1$ inclusive shall be considered as acknowledged. The I frame numbered $N(R)$ and any subsequent I frames received, if any, shall not be considered as acknowledged; the acceptance status of these frames shall be indicated in subsequent exchanges

6.1.4 Reject, REJ, command and response

The reject, REJ, frame shall be used by a station to request retransmission of I frames starting with the frame numbered $N(R)$. I frames numbered $N(R) - 1$ and below shall be considered as acknowledged. Additional I frames awaiting initial transmission may be transmitted following the retransmitted I frame(s).

With respect to each direction of transmission on the data link, only one REJ exception condition from a given station to another station shall be established at any given time. A REJ frame shall not be transmitted until an earlier REJ exception condition has been cleared as indicated in 6.3.3.5.2.2.

The REJ exception condition shall be cleared (reset) upon the receipt of an I frame with an $N(S)$ equal to the $N(R)$ of the REJ frame.

6.2 Procedure and State

6.2.1 Frame state variables and sequence numbers

6.2.1.1 General

Each station shall maintain an independent send state variable $V(S)$ for the frames it transmits and an independent receive state variable $V(R)$ for the I frames it sends to and receives from another station.

6.2.1.2 Send state variable $V(S)$

The send state variable denotes the sequence number of the next in-sequence I frame to be transmitted. The send state variable can take the value 0 to 7 inclusive. The value of the send state variable shall be incremented by one with each successive I frame transmission, but shall not exceed $N(R)$ of the last received frame by more than 7.

6.2.1.3 Send sequence number $N(S)$

Only I frames shall contain $N(S)$, the send sequence number of transmitted frames. Prior to transmission of an I frame, $N(S)$ shall be set equal to the value of the send state variable.

6.2.1.4 Receive state variable $V(R)$

The receive state variable denotes the sequence number of the next I frame expected to be received. The receive state variable can take the value 0 to 7 inclusive. The value of the receive state variable shall be incremented by one on receipt of an error-free I frame whose send sequence number $N(S)$ equals the receive state variable.

6.2.1.5 Receive sequence number $N(R)$

All frames which contain $N(R)$ (see Table 28) shall indicate the $N(S)$ sequence number of the next expected I frame. Prior to transmission of a frame containing $N(R)$, the $N(R)$ shall be set equal to the current value of the receive state

variable. The $N(R)$ indicates that the station transmitting the $N(R)$ has correctly received all I frames numbered up to $N(R) - 1$ inclusive.

6.2.1.6 Use of the P/F bit to assist in error recovery

As the P and F bits set to 1 are always exchanged as a pair (for every P bit there shall be one F bit, and another P bit shall not be issued until the previous P bit has been matched with an F bit, and, similarly, another F bit shall not be issued until another P bit is received), the $N(R)$ contained in a received frame with a P bit or F bit set to 1 can be used to detect that I frame retransmission is required. This capability provides early detection of I frames not received by the remote data station and indicates the frame sequence number where retransmission shall begin. This capability is referred to as checkpointing. The $N(R)$ of a correctly received frame shall acknowledge previously transmitted I frames to $N(R) - 1$ inclusive.

The $N(R)$ of a received I, RR or RNR response frame which has the F bit set to 1 shall cause the receiving station to initiate appropriate error recovery if the $N(R)$ does not acknowledge at least all I frames transmitted by the receiving station previous to, and concurrent with, the last frame which was transmitted by the receiving station with the P bit set to 1.

6.2.2 Exchange of information (I) frames

6.2.2.1 Sending I frames

The control field format shall be as defined in subclause 6.1 for an I frame, with $N(S)$ set to the value of the send state variable $V(S)$ and with $N(R)$ set to the value of the receive state variable $V(R)$. Following data link set-up, both $V(S)$ and $V(R)$ shall be set to zero. The maximum length of the information field in I frames shall be parameter $N1$ (see subclause 5.7.2). The default value of $N1$ is 256 octets; other values may be negotiated by use of the multiplexer control channel.

If a station is ready to send an I frame numbered $N(S)$, where $N(S)$ is equal to the last received acknowledgement plus 7, the station shall not send the I frame but shall follow the procedures described in subclause 5.4.5.

The decision whether to send an I frame as a command or as a response, i.e., to use the C/R bit to indicate a P or an F bit, respectively, shall depend on the need to acknowledge a received P bit set to 1 by transmitting a response with the F bit set to 1.

6.2.2.2 Receiving I frames

After a station receives correctly an I frame [i.e., $N(S)$ equals the value of the receive state variable $V(R)$] that it can accept, the station shall increment its receive state variable $V(R)$, and, at its next opportunity to send, take one of the following actions:

- if information is available for transmission and the other station is ready to receive, it shall act as described in subclause 6.2.2.1 and acknowledge the received I frame(s) by setting $N(R)$ in the control field of the next transmitted I frame to the value of $V(R)$; or
- if information is not available for transmission, but the station is ready to receive I frames, the station shall send an RR frame and acknowledge the received I frame(s) by setting $N(R)$ to the value of $V(R)$; or
- if the station is not ready to receive further I frames, the station may send an RNR frame and acknowledge the received I frame(s) by setting the $N(R)$ to the value of $V(R)$.

If the station is unable to accept the correctly received I frame(s), $V(R)$ shall not be incremented. The station may send an RNR frame with the $N(R)$ set to the value of $V(R)$.

The I or supervisory frame transmitted will be either a command or a response depending on whether a P bit set to 1 or an F bit set to 1 transmission, respectively, is required. If the transmission of a P bit or F bit set to 1 is not required, the acknowledgement frames may be either commands or responses.

6.2.2.3 Reception of incorrect frames

If a frame is received with an incorrect FCS, it shall be discarded.

If an I frame is received with a correct FCS but with an incorrect N(S), the receiving station shall ignore the N(S) field and discard the information field in that frame. This shall continue until the expected I frame is received correctly. The receiving station shall, however, use the P/F and N(R) indications in the discarded I frames. The station shall then acknowledge the expected I frame, when received correctly, as described in subclause 5.4.4.2.

The P/F recovery (checkpointing) shall cause the retransmission of the I frames received incorrectly, as described in subclause 6.2.1.6.

6.2.2.4 Station receiving acknowledgements

A station receiving an I, RR, or RNR frame with a valid $N(R) = x$ shall treat as acknowledged all previously transmitted I frames up to and including the I frame transmitted with N(S) equal to $x - 1$.

6.2.2.5 Exception conditions and recovery

The following procedures are available to effect recovery following the detection/occurrence of an exception condition at the data link layer. The exception conditions described are those situations which may occur as the result of transmission errors, data station malfunction or operational situations.

6.2.2.5.1 Busy

The busy condition shall result when a station is temporarily unable to receive, or unable to continue to receive, I frames due to internal constraints; for example, receive buffering limitations. In this case, an RNR frame shall be transmitted with the N(R) number of the next I frame that is expected. Traffic awaiting transmission may be transmitted from the busy data station prior to, or following, the RNR frame. The continued existence of a busy condition shall be reported by retransmission of an RNR frame at each P/F frame exchange.

A data station receiving an RNR frame, when in the process of transmitting, shall stop transmitting I frames at the earliest possible time. The station shall wait for a duration of T2 before resuming transmission.

Indication that a busy condition has cleared and that I frames will now be acceptable shall be reported by the transmission of an RR, REJ, SABM, or UA frame with or without the P/F bit set to 1. Clearance of a busy condition at a station shall also be indicated by the transmission of an I frame with the F bit set to 1.

6.2.2.5.2 N(S) sequence error

An N(S) sequence error exception condition shall occur in the receiver when an I frame that is received error free (no FCS error) contains an N(S) that is not equal to the receive state variable at the receiver. The receiver shall not acknowledge (i.e., not increment its receive state variable) the frame causing the sequence error or any I frames which may follow until an I frame with the correct N(S) is received.

A station which receives one or more I frames having sequence errors, but which are otherwise error free, shall accept the control information contained in the N(R) field and the P/F bit to perform data link control functions; for example, to receive acknowledgement of previously transmitted I frames, or to cause a station to respond (P bit set to 1). Therefore, the retransmitted I frame may contain an N(R) field and/or P/F bit information that are updated and different from those contained in the originally transmitted I frame.

Following the occurrence of a sequence error, the following means are available for initiating the retransmission of lost I frames or those with errors.

6.2.2.5.3 Poll/final (P/F) bit (checkpoint) recovery

When a data station receives a frame with the P/F bit set to 1, it shall initiate retransmission of unacknowledged I frames previously transmitted with sequence numbers that are less than the V(S), send state variable, value that was current at the time of transmission of the last frame with the P/F bit, respectively, set to 1. Retransmission shall start with the oldest numbered unacknowledged I frame. I frames shall be retransmitted sequentially. New I frames may be transmitted if they become available. Such retransmission of I frames as a result of an exchange of P/F bits set to 1 is known as checkpoint retransmission.

Checkpoint retransmission shall not be initiated under the following conditions:

If a REJ command with the P bit set to 0 or 1, or a REJ response with the F bit set to 0, has been received and actioned while a P bit set to 1 was unanswered, checkpoint retransmission shall be inhibited on the next frame received with the F bit set to 1, if it would cause retransmission of the same particular I frame; i.e., same N(R) in same numbering cycle.

If a P/F bit set to 1 is received in an unnumbered format frame (SABM, UA, DISC, DM, UI or UIH), checkpoint retransmission shall be inhibited.

If, after sending a frame with the P/F bit set to 1, a data station receives an acknowledgement to that frame before receiving the corresponding frame with the P/F bit set to 1, checkpoint retransmission on the frame with the P/F bit set to 1 shall be inhibited.

If any frame with the P bit set to 1 is received, checkpoint retransmission shall be inhibited.

6.2.2.5.4 REJ recovery

The REJ command/response shall be used primarily to initiate an exception recovery (retransmission), following the detection of a sequence error, earlier than is possible by checkpoint (P/F bit) recovery; for example, if a REJ frame is immediately transmitted upon detection of a sequence error, then there is no requirement to wait for a frame with the P/F bit set to 1 in order to update V(R).

With respect to each direction of transmission on the data link, only one "sent REJ" exception condition from one station to another data station shall be established at a time. A "sent REJ" exception condition shall be cleared when the requested I frame is received or when the response/command time-out function runs out. When the data station perceives by time-out that the requested I frame has not been received, because either the requested I frame or the REJ frame was in error or lost, the REJ frame may be repeated.

A station receiving a REJ frame shall initiate sequential transmission (or retransmission) of I frames starting with the I frame indicated by the N(R) contained in the REJ frame. New I frames may be transmitted subsequently if they become available.

If retransmission beginning with a particular frame occurs due to checkpointing (see subclause 6.2.2.5.3), and a REJ frame is received which would also start retransmission with the same particular I frame [as identified by the N(R) in the REJ frame], the retransmission resulting from the REJ frame shall be inhibited.

6.2.2.5.5 SABM Command

When this command is actioned, the responsibility for all unacknowledged I frames assigned to data link control reverts to a higher layer. Whether the content of the information field of such unacknowledged I frames is reassigned to data link control for transmission or not is decided at a higher layer.

6.2.2.5.6 DISC Command

When this command is actioned, the responsibility for all unacknowledged I frames assigned to data link control reverts to a higher layer. Whether the content of the information field of such unacknowledged I frames is reassigned to data link control for transmission or not is decided at a higher layer.

Annex A (informative): Advice to TE software implementers

The multiplexing protocol allows a number of virtual channels to be established between a TE and an MT. The TE is normally responsible for establishing and clearing down each virtual channel, although the MT may autonomously clear the entire multiplexing session.

Each channel will start life as an instance of GSM 07.07, and will allow the normal AT command procedures for both GSM 07.07 and GSM 07.05. Any changes made to the AT register settings will be valid within the virtual channel only. If registers are saved to non-volatile memory then the changes will apply to the defaults for the AT registers and will affect new channels from that point on. Such changes will only affect other active channels if they are reset with ATZ. Changes to the phonebook or to SMS messages will, of course, be on a global basis.

The software in the TE sitting above the multiplexing protocol is recommended to establish a virtual channel and leave it "idle" for the reception of incoming calls according to responses as defined in GSM 07.07. When an incoming call arrives the software may then cause an appropriate application to become active in order to receive the incoming call. The previously "idle" channel will then be occupied with this call and so the TE software is recommended to establish an additional channel to take over from the previously-idle channel in preparation for other incoming calls or indications.

Because the ISO HDLC transparency mechanism must be used if it is supported by the MS, the TE shall always try to configure the multiplexer with this transparency mechanism. If it is not supported by the MS, the TE shall configure the multiplexer in the basic option.

Annex B (informative): Document change history

SMG#	TDoc	SPEC	VERS	NEW_VERS	CR	REV	PHASE	CAT	WORKITEM	SUBJECT
s26	98-293	07.10	6.0.0	6.1.0	A001		R97	F	MS-TE multiplexing protocol	07.10 primitive description
s26	98-293	07.10	6.0.0	6.1.0	A002		R97	F	MS-TE multiplexing protocol	Editorial corrections in length indication and priority table
s26	98-293	07.10	6.0.0	6.1.0	A003		R97	F	MS-TE multiplexing protocol	Modem Control Signals
s26	98-293	07.10	6.0.0	6.1.0	A004		R97	F	MS-TE multiplexing protocol	Service Negotiation Command
s26	98-293	07.10	6.0.0	6.1.0	A005		R97	F	MS-TE multiplexing protocol	Port Parameter Command

History

Document history		
V6.1.0	July 1998	Publication