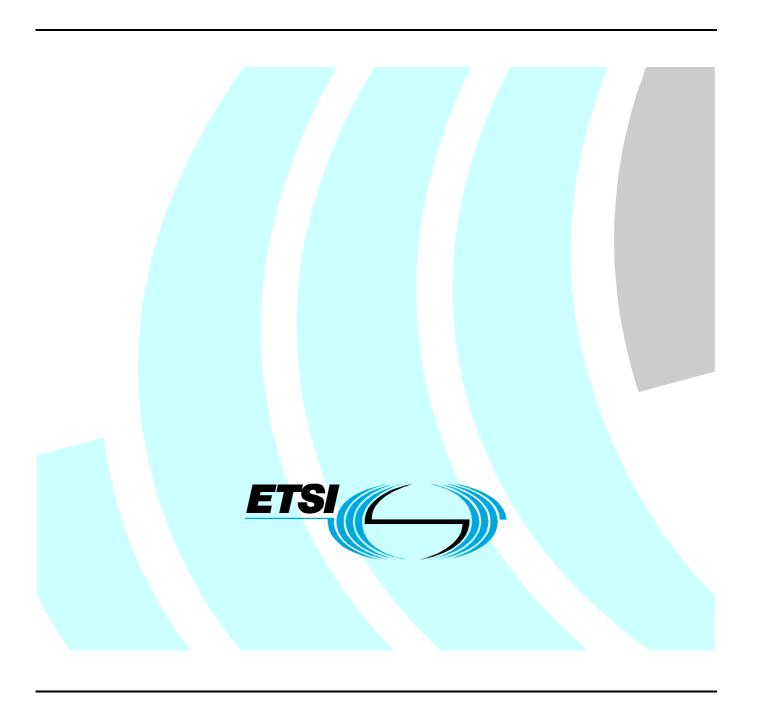
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Technical Specification

Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 6: Radio link control



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Foreword

This Technical Specification (TS) has been produced by ETSI Technical Committee Satellite Earth Stations and Systems (SES).

The present document is part 6 of a multi-part deliverable covering the BSM Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specifications, as identified below:

Part 1: "General description";
Part 2: "Frame structure";
Part 3: "Channel coding";
Part 4: "Modulation";
Part 5: "Radio transmission and reception";
Part 6: "Radio link control";
Part 7: "Synchronization".

1 Scope

The present document presents the requirements for synchronizing timing and frequency between the ST and the satellite network within the SES BSM Regenerative Satellite Mesh - A (RSM-A) air interface family.

2 References

Void.

3 Definitions and abbreviations

3.1 Definitions

For the purposes of the present document, the following terms and definitions apply:

Network Control Centre (NCC): centre that controls the access of the satellite terminal to an IP network and also provides element management functions and control of the address resolution and resource management functionality

satellite payload: part of the satellite that provides air interface functions

NOTE: The satellite payload operates as a packet switch that provides direct unicast and multicast

communication between STs at the link layer.

Satellite Terminal (ST): terminal installed in the user premises

terrestrial host: entity on which application level programs are running

NOTE: It may be connected directly to the Satellite Terminal or through one or more networks.

3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply:

DDID Downlink Destination ID

EIRP Effective Isotropic Radiated Power

IP Internet Protocol

LLA Latitude, Longitude and Altitude

Mbps Mega bits per second (millions of bits per second)

MIP Management Information Packet

 $\begin{array}{ll} \text{MMI} & \text{Man-Machine Interface} \\ \text{NCC} & \text{Network Control Centre} \\ PCE_{STD} & \text{Power Control Error Standard} \\ \end{array}$

PHY PHYsical PTP Point-to-Point RS Reed-Solomon

RSM Regenerative Satellite Mesh
SAP Service Access Point
SLC Satellite Link Control
ST Satellite Terminal

TDMA Time Division Multiple Access
TIP Transmission Information Packet

ULPC UpLink Power Control

UW Unique Word

4 General description of radio link control system

BSM RSM-A is a multi-spot beam, multicarrier, synchronous system where the timing and frequency on the satellite serve as the reference to synchronize the TDMA transmissions for the STs, and other network elements. The satellite includes a packet switch designed to provide single-hop, point to point packet routing between downlink cells.

The functions of the physical layer are different for the uplink and downlink. The major functions are illustrated in figure 4.

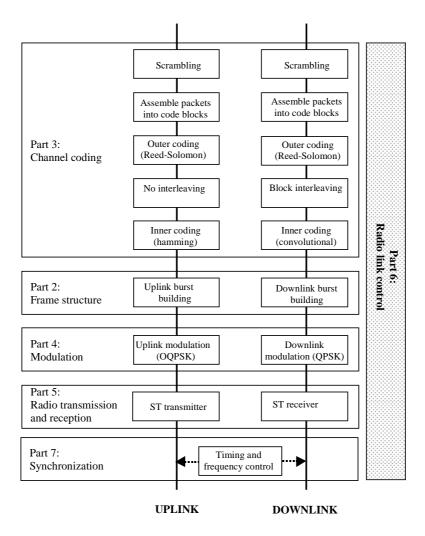


Figure 4: Physical layer functions

The present document describes the radio link control functions. This group of functions is highlighted in figure 4.

Clause 5 describes ST antenna pointing. Clause 6 describes cell and microcell selection. Clause 7 describes system information reception. Clause 8 describes power control. Clause 9 describes radio link failure. Clause 10 describes fallback mode of operation and transition requirements. Clause 11 describes radio link measurements. Clause 12 describes the control parameters required to perform radio link control.

Clause 5 and clause 6 describe the procedures used for installation of the ST. These procedures require knowledge of the ST location and also the location and cell parameters of the desired RSM-A satellite. This information may be obtained by any suitable combination of internal and external mechanisms, provided that the resulting accuracy complies with the requirements given in this specification. The calculations in the present document assume ST location in the form of the ST Latitude, Longitude and Altitude (LLA). The ST may have an integrated GPS receiver or may have a suitable Man-Machine Interface (MMI) such that the information may be entered into the ST by an installer. Alternatively, some GPS receivers can output in earth centred earth fixed (ECEF) Cartesian coordinates. Required accuracy of LLA is given in RSM-A; Air Interface; Physical layer specification, TS 102 188-7.

The details of the MMI are outside the scope of the present document.

5 ST antenna initial pointing

In order to determine the proper initial pointing of an ST antenna, the ST antenna elevation angle and azimuth angle shall be calculated from knowledge of the ST position and the location of the desired RSM-A satellite.

5.1 Calculating ST Antenna Elevation and Azimuth Angles

The inputs to this procedure are the Satellite location and the ST location information. These calculations assume the ST location information, the geodetic latitude and longitude (ST_LAT and ST_LONG), are known. The Geodetic coordinate system is the coordinate system which uses the Prime Meridian and the Equator as the reference planes to define the latitude and longitude. The geodetic latitude of a point is the angle from the equatorial plane to the vertical direction of a line normal to the reference ellipsoid. The geodetic longitude of a point is the angle between a reference plane and a plane passing through the point, both planes being perpendicular to the equatorial plane. The geodetic height at a point is the distance from the reference ellipsoid to the point in a direction normal to the ellipsoid. The geodetic height of the ST shall be required in the calculations performed in clause 6.

In order to determine the ST latitude, longitude and height, as required to perform the calculations in this clause and clause 6, the ST may have an integrated GPS receiver or may have a suitable Man-Machine Interface (MMI) such that the information may be entered into the ST by an installer. Alternatively, any other algorithm may be used to locate an ST provided that the timing requirements described in BSM RSM-A physical layer specification, TS 102 188-7 and cell selection requirements can be met.

The ST may calculate the ST antenna elevation and azimuth pointing angles or may use any other algorithm to locate an ST provided that the ST may be pointed accurately so as to meet the transmitter and receiver requirements in RSM-A physical layer specification, TS 102 188-5.

The ST may have a lookup table listing all the satellite locations or this may be information entered at the time of installation. Since there may be new BSM RSM-A systems in the future, an ST manufacturer should have a method whereby an ST might be located anywhere in the world and use any BSM RSM-A satellite which may be in view of that location.

The ST Elevation angle (ST_EL) and the ST azimuth angle (ST_AZ) are computed as follows:

$$\begin{aligned} \sin\left(\zeta\right) &= \cos\left(ST_LAT\right)\cos\left(\Delta Long\right) \\ y_e &= \sin\zeta - R_C/R_{geo} \\ x_e &= \cos\left(\zeta\right) \\ ST_EL &= \tan^{-1}\left(y_e/x_e\right) \\ y_a &= -\sin\left(\Delta Long\right) \\ x_a &= -\sin\left(ST_LAT\right)\cos\left(\Delta Long\right) \\ ST_AZ &= \tan^{-1}\left(y_a/x_a\right) \end{aligned}$$

where $R_C = a/K$ and where a is the radius of the earth. K is a latitude dependent constant given by:

$$K = (1 - F (2 - F) \sin^2 (ST_LAT))^{1/2}$$

The parameter R_{geo} is the geosynchronous orbit radius. The parameter F is the flattening defined by:

$$F = (a - b)/a$$

Where a is the semi-major earth axis (ellipsoid equatorial radius) and b is the semi-minor earth axis (ellipsoid polar radius).

and *\Delta\Long* is the angular difference between the satellite location and the geodetic longitude location of the ST.

$$\Delta Long = \Theta$$
-ST_LONG

where Θ is the orbital location in degrees longitude West and ST_LONG is the terminal location is degrees longitude West. Table A.1 lists the RSM-A satellite positions for North America.

Note that all trigonometric calculations should be in radians.

If the ST performs these calculations, the pointing angles shall be saved in non-volatile memory and output through a suitable MMI to the installer to use for initial antenna pointing.

6 Selection of Cell/Microcell and Beam Polarization

6.1 Conversion of geodetic LLA coordinates to antenna coordinates system

These calculations determine the slant path (distance from satellite to ST) and help determine the cell and microcell based on the ST position.

First transform the latitude and longitude to the Cartesian coordinate systems (Xp, Yp, Zp) as shown in figure 6.1. The coordinate system is shifted by the geosynchronous radius in order to place the origin at the centre of the Earth. The elements of vector (Xp, Yp, Zp) are computed as follows

Given the ST location in geodetic coordinates (Height, Latitude and Longitude) the following procedure will convert them to Cartesian coordinates (X, Y, Z).

The elements of the ST location (in Cartesian coordinates) are computed as follows:

$$X_{ST} = (R_C + height) \cos{(ST_LAT)} \cos{(\Delta Long)}$$
 $Y_{ST} = (R_C + height) \cos{(ST_LAT)} \sin{(\Delta Long)}$
 $Z_{ST} = (R_C (1-F)^2 + height) \sin{(ST_LAT)}$
 $X_p = X_{ST} - R_{geo}$
 $Y_p = Y_{ST}$, and
 $Z_p = Z_{ST}$

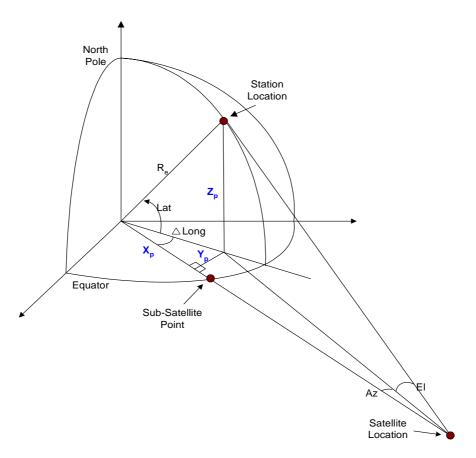


Figure 6.1: On-orbit geometry

The vector (Xp, Yp, Zp) is placed into a rotated coordinate system to take into account the boresight pointing of the antenna. This rotation is performed through the following linear equation:

$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = M \begin{bmatrix} X_p \\ Y_p \\ Z_p \end{bmatrix}$$

where M is a rotation matrix given by:

$$M = \begin{bmatrix} \cos(\theta_Y) & 0 & -\sin(\theta_Y) \\ 0 & 1 & 0 \\ \sin(\theta_Y) & 0 & \cos(\theta_Y) \end{bmatrix} \begin{bmatrix} \cos(\theta_X) & -\sin(\theta_X) & 0 \\ \sin(\theta_X) & \cos(\theta_X) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

 θ_X is the boresight azimuth angle and θ_Y is the boresight elevation angle defined in annex A. Finally, compute the azimuth and elevation angles.

$$Az = \tan^{-1} \left(\frac{-Y}{X} \right)$$

$$El = \tan^{-1} \left(\frac{Z}{\sqrt{X^2 + Y^2}} \right)$$

where Az and El are the ST angular coordinates relative to the satellite boresight.

6.2 Cell selection

At installation, after mapping the ST position into satellite antenna (Az, El) coordinates, the ST may use a look-up table to determine cell, and uplink polarization, microcell and downlink polarization, and downlink destination IDs to be used at that location. Example look-up tables are presented in annex A for some RSM-A systems. Because the coverage grids used are hexagonal in angle space, the cell (or microcell) centre closest to this point defines the cell (or microcell) location for the ST. Alternatively, this information may be entered into the terminal at the time of installation through a suitable MMI. An automatic algorithm for determining this information is described, but it is not required.

After antenna pointing and after acquiring the Beacon on LHCP, the ST may scan the downlink for TIP messages (see RSM-A, SMAC/SLC layer specification, TS 102 189-2). In order to do this the ST may filter on the destination sub addresses 0 to 127 instead of the downlink destination IDs. The ST should rank order the TIP messages by received relative power. The ST should remember the two strongest signals. In clear weather, these should be averaged over 5 successfully received TIP messages. The ST should then acquire the RHCP beacon (see RSM-A, Physical layer specification, TS 102 188-7) and perform this measurement on the RHCP downlink. The ST shall compare its satellite antenna (*Az, El*) coordinates to the cell centres and select the cell with the minimum squared angular distance. In the event of a tie, the ST should select the one which had the strongest relative received power.

6.3 Microcell selection

The ST should then select the microcell beam centre within the selected cell that is the closest to the ST location in the satellite angular space by calculating the squared angular distance.

From the satellite point of view figure 6.3 shows the microcell centre relative to a given cell centre. The offsets correspond to a hexagonal grid with spacing of $(0.189 \times \text{sqrt}(3) / 2)$ degrees between points and a 10,8934 degree clockwise rotation relative to the elevation-axis. These offsets are applied in angular coordinates to the centre of the cell.

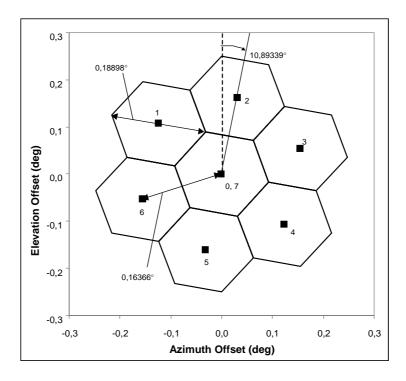


Figure 6.3: Microcell orientation relative to cell centre

A downlink microcell ID is represented using two indices corresponding to a cell ID (CID) (1 to 112) and the associated Microcell Local ID (MLID) (1 to 7). Microcell local ID 0 represents cellcast. The offsets are added to El_{CC} and Az_{CC} coordinates at the centre of the cell. The microcell centres are calculated using the following relationships:

$$Az_{MCC}(CID, MLID) = Az_{CC}(CID) + \Delta Az(MLID)$$

$$El_{MCC}(CID, MLID) = El_{CC}(CID) + \Delta El(MCID)$$

where: $Az_{CC}(CID)$ and $El_{CC}(CID)$ are the cell centre coordinates for the cell from table 6.3, and

 $\Delta Az(MLID)$ and $\Delta El(MCID)$ are the microcell offsets from table 6.3.

Table 6.3: Microcell centre offset from cell centre

Δ Azimuth Offset [degree] ΔAZ(MLID)	Δ Elevation Offset [degree] ΔEL(MCID)	Microcell Local ID MCID
0,000000	0,000000	0
-0,123718	0,107143	1
0,030929	0,160714	2
0,154647	0,053571	3
0,123718	-0,107143	4
-0,030929	-0,160714	5
-0,154647	-0,053571	6
0,000000	0,000000	7

6.4 Downlink Destination ID

The downlink destination ID is an eleven bit field. The msb indicates the polarization (pol) where pol = 0 indicates LHCP and pol = 1 indicates RHCP.

The downlink destination ID which the terminal shall use during installation is calculated from the following steps.

- 1) With knowledge of its location, an ST shall determine its CID and MLID within the cell from the method described in clauses 6.1 through 6.3.
- 2) The ST may determine the default polarization from a lookup table using the cell ID or the ST may use measurements of TIP message transmissions described in clause 6.2 to determine the downlink polarization.
- 3) The ST shall then determine the Downlink Destination ID (DDID) to use for PTP from the CID, MLID and the pol using the following formula:

$$DDID = 32 + 8 \times (CID-1) + (MLID) + pol \times 1024$$

4) The ST shall determine the DDID to use for cellcast from the CID and the pol using the following formula:

$$DDID = 32 + 8 \times (CID-1) + pol \times 1024$$

The ST shall use both of these DDIDs at installation.

In general, other DDIDs, which the ST shall learn from the commissioning process, may not have this relationship to CID or MLID.

An example of the downlink destination ID numbering method for null, shaped beam broadcast, beacon, cellcast, and PTP bursts are shown in tables A.3 and A.4.

7 System information reception

The ST should then filter on the DDID associated with the selected cell and microcell and receive the indirect Management Information Packet (MIP) message. The indirect MIP message (see RSM-A, SMAC/SLC, TS 102 189-2) contains the DDID the ST shall use for commissioning and configuration. This may be a shaped beam address or a cell address. The ST should convey all information it acquired by this procedure to the installer. The ST shall store all information in non-volatile memory.

The ST should read the uplink polarization in the TIP message (see RSM-A, SMAC/SLC, TS 102 189-2) broadcast in the selected cell.

The ST shall read the TIP message every superframe.

8 RF uplink power control

8.1 Burst probing power

Initial burst probing for timing synchronization is described in BSM RSM-A PHYS layer specification TS 102 188-7.

The ST shall use the nominal transmit power, P_o , calculated below:

$$P_o = (-172,55 + Path Loss - Directivity)$$
 dBWi, where

Path Loss is calculated by:

Path Loss = 20 Log10 (
$$4\pi*Uplink\ Frequency*Path\ Length/0,3$$
) dB

And Directivity is the satellite antenna directivity of the uplink beam calculated by:

Directivity =
$$4.5 * (1 - (\varphi/0.25)^2)$$

where

$$\varphi^2 = (Az - Az_{CC})^2 + (El - El_{CC})^2$$

where Az and El are the ST angular coordinates relative to the satellite boresight calculated in clause 6.1 and Az_{CC} and El_{CC} are the cell centre coordinates given in table A.2. Path Length is derived in BSM RSM-A PHY layer specification TS 102 188-7.

8.2 Power control maintenance

An ST shall be required to control output power within a target range so as to maintain as acceptable packet loss ratio and at the same time, limit interference to the rest of the system. The ST shall adjust the uplink power in order to maintain a target SNR at the satellite, based on the UPLC reports received from the satellite. The instantaneous SNR for each burst received at the satellite, is reported by the satellite to the ST in the ULPC status packet messages (see RSM-A, SMAC/SLC, TS 102 189-2). The standard deviation of power control error (PCE_{STD}) at time slot k over the last M transmissions, is defined as:

$$PCE_{STD}(k) = \frac{1}{M} \sqrt{\sum_{i=k-M+1}^{k} \left[\left(\frac{C}{N} \right) (i) - \left(\frac{C}{N} \right)_{T \text{ arg } et} \right]^{2}}$$

where (C/N)(i) is the i(th) measurement reported by the satellite of SNR, $(C/N)_{Target}$ is the target SNR.

At installation after the first 1000 transmissions and with M = 100, the PCE_{STD} shall be less than [1,5 dB].

In steady state, after 10,000 transmissions, the PCE_{STD} shall meet the requirements shown in table 8.2.1.

Table 8.2.1: Power control requirements

		Rate/Volume (note 1)	Contention (note 2)	
Normal		$PCE_{STD} < 0.7 dM (M = 1000)$	$PCE_{STD} < 1.2 dB (M = 100)$	
Faded PCE _{STD} < 1,0 dB (M = 1000) PCE _{STD} < 1,5 dB (M = 100)				
NOTE 1: Rate/Volume is defined as continuous transmission, at least one time slot per frame for every frame, over at least 3 different carrier designators during the measurement period.				
NOTE 2: Contention is defined as 100 transmissions with a gap of at least 9,6 s between each transmission over at least 3 carrier designators.				

Normal is defined as a period wherein at least 99 % of the time the random uplink fade is less than 2 dB. Faded is defined as a period wherein at least 99 % of the time the random uplink fade is greater than 2 dB but less than the maximum fade at which the uplink can be closed. Table 8.2.2 gives some examples of the relationship between the ST EIRP and the maximum fade for reference values of EIRP. See RSM-A, physical layer specification, TS 102 188-5, for more information.

Table 8.2.2: Maximum uplink fade

Carrier mode	Reference EIRP (dBW)	Maximum fade (dB)
128 Kbps	48	17,8
512 Kbps	48	11,2
2 Mbps	52,5	8,7

8.3 ULPC information

The ULPC status packet messages (see RSM-A SMAC/SLC, TS 102 189-2) contains information about the quality of the uplink signal as received by the satellite. The following clauses describe how the information in this message is used by the ST.

8.3.1 SNR

The STs calculate the SNR in dB using the SNR field from the ULPC status packet message (see RSM-A, SMAC/SLC, TS 102 189-2) using the following equation:

SNR in dB =
$$\frac{1}{4}$$
 SNR field + k_2

where

$$k_2 = -6.0$$
 for 128 Kbps,

 $k_2 = 0.0$ otherwise.

8.3.2 Block Decoder Metric

The ST shall interpret the 4-bit Block Decoder Metric as shown in table 8.4.

The satellite counts the number of bit errors detected by the inner block decoder (see RSM-A, Physical layer, TS 102 188-3) during the initial 244 bytes (one Reed-Solomon code block) of each time slot on each carrier. This error count is mapped to the 4-bit Block decoder Metric.

The bit error count corresponding to the target $E_c / (N_o + I_o)$ required to achieve the Packet Loss Ratio (PLR) in the table below is provided to the ST in the ULPC status message (see RSM-A, SMAC/SLC, TS 102 189-2).

Table 8.3.2: Packet Loss Ratio

Rate	PLR
128 Kbps	1,0 x 10 ⁻⁵
512 Kbps	1,0 x 10 ⁻⁵
2 Mbps	7,5 x 10 ⁻⁷
16 Mbps	2,5 x 10 ⁻⁷

The average number of bit errors detected, as a function of the input $E_c / (N_o + I_o)$ in the range of [-2, 8] dB shall be made available to the ST.

Binary Bit Value	Block Decoder Error C	ount (per Code Block)	Estimated
-	>= Lower bound	< Upper bound	Ec/(No+lo) (dB)
0000	0	2	6,2143
0001	2	3	5,7857
0010	3	5	5,3571
0011	5	9	4,9286
0100	9	14	4,5000
0101	14	20	4,0714
0110	20	28	3,6429
0111	28	39	3,2143
1000	39	50	2,7857
1001	50	63	2,3571
1010	63	78	1,9286
1011	78	95	1,5000
1100	95	112	1,0714
1101	112	129	0,6429
1110	129	488	0,2143
1111	RS Fa	ailure	N/A

8.3.3 Uplink noise measurement

The uplink noise measurement reported to the ST in the ULPC status packet message (see RSM-A, SMAC/SLC, TS 102 189-2) correlates with carrier bandwidth. The noise measurement represents an estimate of the standard deviation, σ_N , of the noise process during the frame dead time. This 8-bit value, Noise Estimate, can be used to obtain an estimate of the noise density at the reference point used for satellite SNR measurements using the following equation:

Noise Density $(dBm/Hz) = 20 \log_{10}$ (Noise Estimate) - 133,68 dB

9 Radio link failure

This clause describes the physical layer criteria by which an ST moves from Registered_Active State to Registered_No_Link state.

An ST shall move from the Registered_Active State to the Registered_No_Link state if it fails to receive TIP messages (see RSM-A, SMAC/SLC, TS 102 189-2) in five consecutive superframes.

10 Fallback mode

This clause describes the physical layer criteria by which the ST shall initiate fallback mode of operation. This clause also describes the physical layer criteria by which the ST shall recover from fallback mode.

An ST shall enter fallback mode after experiencing an uplink fade of at least X dB for 192 s.

15

For 512 Kbps:

$$X = (C/N)_{DL} - [5,3 + (P_{max} - 48,1) / 1,9]$$

For 2 Mbps:

$$X = (C/N)_{DL} - [5,3 + (P_{max} - 48,1 - 6) / 1,9]$$

Where $(C/N)_{DL}$ is the normal downlink C/N which is averaged over at least 24 hours and P_{max} is the ST maximum uplink EIRP.

An ST in fallback mode shall enter normal mode after experiencing an uplink fade that is less than Y dB for 192 s.

For 512 Kbps:

$$Y = (C/N)_{DL} - [2,3 + (P_{max} - 48,1) / 1,9]$$

For 2 Mbps:

$$Y = (C/N)_{DL} - [2,3 + (P_{max} - 48,1 - 6)/1,9]$$

11 Control Parameters

This clause gives the values of the physical layer control parameters used in the calculations shown in clause 6.

11.1 Parameters for installation and cell selection

These parameters shall be conveyed to the ST.

Parameter	Description	Unit	Range	Default	Resolution	#Bits
а	Semi-major axis = equatorial radius	m	-	6378137	1	-
b	Semi-minor axis = polar radius	m	-	6356752	1	-
F	Earth flattening		-	1/298,2572235		-
Rgeo	Geostationary orbit radius	m	-	42163203	1	-
					_	$5 \times 6 = 30$

Annex A (informative): Cell parameters

A.1 General Description

The Cell Parameter information is predefined for each of the available satellites. The information may be embedded in the ST (e.g. embedded look-up tables) or may be entered at the time of installation as described in clause 6. As an example of the information that is required, this annex gives the parameters which describe the North American RSM-A system.

NOTE: This information is informative and subject to regulatory agreements.

A.1.1 Antenna boresight angles for North American Satellites

Table A.1 shows the boresight angles for the three orbital locations, Θ .

Table A.1: Antenna boresight angles

Orbital slot (degrees west longitude), Θ	99	101	103
Boresight azimuth (degree), θ_X	-0,28	0.00	0.28
Boresight elevation (degree), θ_Y	+6,00	+6,00	+6,00

A.1.2 Cell definition, mapping, polarization, and unique word assignment

The cells that provide the required coverage lie on a triangular grid in elevation-over-azimuth angle coordinates. Each cell is composed of 7- microcells as illustrated in figure A.1, as viewed from the satellite in the coordinate.

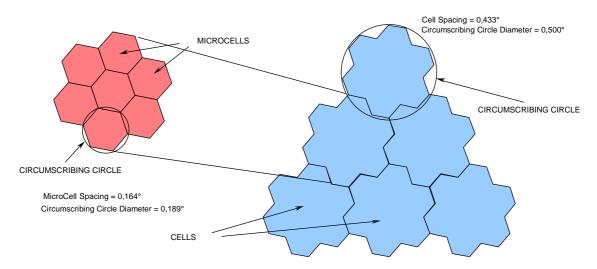


Figure A.1: Cell to seven microcells relationship

Cells can be circumscribed with $0,500^{\circ}$ diameter circles. The 7-microcells that make up each cell can each be circumscribed with a $0,189^{\circ}$ diameter circle.

Table A.2 lists the cell centres in antenna coordinates using the El over Az coordinate system. The spacing between cell centres is 0.433° (= $0.5 \times \text{sqrt}(3) / 2$). 112 cells are required to completely tile the coverage region.

Table A.2: Baseline cell centre location, uplink cell polarization, and unique word

Cell ID	Azimuth (degree)	Elevation (degree)	Uplink pol	7-cell UW select ID	(Cell ID	Azimuth (degree)	Elevation (degree)	Uplink pol	7-cell UW select ID
1	0,3830	1,7819	LHCP	1		57	1,8985	0,0930	RHCP	6
2	2,9810	1,7819	LHCP	7		58	2,3315	0,0930	LHCP	7
3	0,1665	1,4069	RHCP	5		59	2,7645	0,0930	RHCP	1
4	0,5995	1,4069	LHCP	6		60	3,1975	0,0930	LHCP	2
5	2,7645	1,4069	RHCP	4		61	2,6480	0,4680	LHCP	7
6	3,1975	1,4069	LHCP	5		62	2,2150	0,4680	RHCP	1
7	1,3490	1,0320	RHCP	6		63	1,7820	0,4680	LHCP	2
8	0,4830	1,0320	RHCP	1		64	1,3490	0,4680	RHCP	3
9	0,0500	1,0320	LHCP	2		65	0,9160	0,4680	LHCP	4
10	0,3830	1,0320	RHCP	3		66	0,4830	0,4680	RHCP	5
11	0,8160	1,0320	LHCP	4		67	0,0500	0,4680	LHCP	6
12	1,2490	1,0320	RHCP	5		68	0,3830	0,4680	RHCP	7
13	1,6820	1,03206	LHCP	6		69	0,8160	0,4680	LHCP	1
14	2,1150	1,0320	RHCP	7		70	1,2490	0,4680	RHCP	2
15	2,5480	1,0320	LHCP	1		71	1,6820	0,4680	LHCP	3
16	2,9810	1,0320	RHCP	2		72	2,1150	0,4680	RHCP	4
17	-2,4315	-0,657	LHCP	1		73	2,548	0,468	LHCP	5
18	-1,9985	-0,657	RHCP	2		74	2,981	0,468	RHCP	6
19	-1,5655	-0,657	LHCP	3		75	3,414	0,468	LHCP	7
20	-1,1325	-0,657	RHCP	4		76	-2,4315	0,843	LHCP	5
21	-0,6995	-0,657	LHCP	5		77	-1,9985	0,843	RHCP	6
22	-0,2665	-0,657	RHCP	6		78	-1,5655	0,843	LHCP	7
23	0,1665	-0,657	LHCP	7		79	-1,1325	0,843	RHCP	1
24	0,5995	-0,657	RHCP	1		80	-0,6995	0,843	LHCP	2
25	1,0325	-0,657	LHCP	2		81	-0,2665	0,843	RHCP	3
26	1,4655	-0,657	RHCP	3		82	0,1665	0,843	LHCP	4
27	1,8985	-0,657	LHCP	4		83	0,5995	0,843	RHCP	5
28	2,3315	-0,657	RHCP	5		84	1,0325	0,843	LHCP	6
29	2,7645	-0,657	LHCP	6		85	1,4655	0,843	RHCP	7
30	3,1975	-0,657	RHCP	7		86	1,8985	0,843	LHCP	1
31	-2,648	-0,037	RHCP	5		87	2,3315	0,843	RHCP	2
32	-2,046	-0,282	LHCP	6		88	2,7645	0,843	LHCP	3
33	-1,782	-0,282	RHCP	7		89	3,1975	0,843	RHCP	4
34	-1,762	-0,282	LHCP	1		90	3,6305	0,843	LHCP	5
35	· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·					-2,648			
	-0,916	-0,282	RHCP	2		91		1,218	RHCP	2
36 37	-0,483	-0,282	LHCP	3		92	-2,215	1,218	LHCP	3
	-0,05	-0,282	RHCP	4		93	-1,782	1,218	RHCP	4
38	0,383	-0,282	LHCP	5		94	-1,349	1,218	LHCP	5
39	0,816	-0,282	RHCP	6	\vdash	95	-0,916	1,218	RHCP	6
40	1,249	-0,282	LHCP	7		96	-0,483	1,218	LHCP	7
41	1,682	-0,282	RHCP	1	\vdash	97	-0,05	1,218	RHCP	1
42	2,115	-0,282	LHCP	2	\vdash	98	0,383	1,218	LHCP	2
43	2,548	-0,282	RHCP	3	\vdash	99	0,816	1,218	RHCP	3
44	2,981	-0,282	LHCP	4		100	1,249	1,218	LHCP	4
45	3,414	-0,282	RHCP	5		101	-1,1325	1,593	LHCP	3
46	-2,8645	0,093	LHCP	2	$\bot \bot$	102	-3,514	1,968	LHCP	2
47	-2,4315	0,093	RHCP	3		103	-3,081	1,968	RHCP	3
48	-1,9985	0,093	LHCP	4	lacksquare	104	-2,648	1,968	LHCP	4
49	-1,5655	0,093	RHCP	5	$\bot \bot$	105	-7,3115	-2,6799	RHCP	11
50	-1,1325	0,093	LHCP	6		106	0,304	-2,666	RHCP	7
51	-0,6995	0,093	RHCP	7		107	5,314	-2,954	RHCP	1
52	-0,2665	0,093	LHCP	1		108	5,44	-4,195	RHCP	2
53	0,1665	0,093	RHCP	2		109	4,527	-5,186	RHCP	3
54	0,5995	0,093	LHCP	3		110	7,205	-9,607	RHCP	4
55	1,0325	0,093	RHCP	4		111	4,01	-8,058	RHCP	5
56	1,4655	0,093	LHCP	5		112	5,368	-11,332	RHCP	6

A.1.3 Downlink destination ID

Table A.3: Downlink destination ID numbering

LHCP			RHCP			
DDID	Burst type	ULCID	DDID	Burst type	ULCID	
0	Null Burst	n/a	1024	Null Burst	n/a	
1	Shaped beam		1025	Shaped beam		
2	Calibration Burst		1026	Calibration Burst		
3	Reserved	N/a	1027	Reserved	N/a	
4	Reserved	N/a	1028	Reserved	N/a	
5	Reserved	N/a	1029	Reserved	N/a	
6	Beacon Burst 0	1 to 112	1030	Beacon Burst 0	1 to 112	
7	Beacon Burst 1	1 to 112	1031	Beacon Burst 1	1 to 112	
8	Beacon Burst 2	1 to 112	1032	Beacon Burst 2	1 to 112	
9	Beacon Burst 3	1 to 112	1033	Beacon Burst 3	1 to 112	
10	Beacon Burst 4	1 to 112	1034	Beacon Burst 4	1 to 112	
11	Beacon Burst 5	1 to 112	1035	Beacon Burst 5	1 to 112	
12	Beacon Burst 6	1 to 112	1036	Beacon Burst 6	1 to 112	
13	Beacon Burst 7	1 to 112	1037	Beacon Burst 7	1 to 112	
14	Beacon Burst 8	1 to 112	1038	Beacon Burst 8	1 to 112	
15	Beacon Burst 9	1 to 112	1039	Beacon Burst 9	1 to 112	
16	Beacon Burst 10	1 to 112	1040	Beacon Burst 10	1 to 112	
17	Beacon Burst 11	1 to 112	1041	Beacon Burst 11	1 to 112	
18	Beacon Burst 12	1 to 112	1042	Beacon Burst 12	1 to 112	
19	Beacon Burst 13	1 to 112	1043	Beacon Burst 13	1 to 112	
20	Beacon Burst 14	1 to 112	1044	Beacon Burst 14	1 to 112	
21	Beacon Burst 15	1 to 112	1045	Beacon Burst 15	1 to 112	
22	Shaped beam		1046	Shaped beam		
23	Shaped beam		1047	Shaped beam		
24	Shaped beam		1048	Shaped beam		
25	Shaped beam		1049	Shaped beam		
26	Shaped beam		1050	Shaped beam		
27	Shaped beam		1051	Shaped beam		
28	Shaped beam		1052	Shaped beam		
29	Shaped beam		1053	Shaped beam		
30	Shaped beam		1054	Shaped beam		
31	Reserved		1055	Reserved		
32	PTP or Cellcast	Note	1056	PTP or Cellcast	Note	
:	:	Note		:	Note	
927	PTP or Cellcast	Note	1950	PTP or Cellcast	Note	
928	PTP or Cellcast	N where 1 ≤ N	1951	PTP or Cellcast	N where 1 ≤ N	
		≤ 112			≤ 112	
		_ ' ' ' _			112	
1023	PTP or Cellcast	N where 1 ≤ N ≤ 112	2047	PTP or Cellcast	N where 1 ≤ N ≤ 112	

A.1.4 Downlink microcell polarization assignments

Table A.4 list the individual microcell centres by cell ID and their predefined polarization. An ST shall use this predefined polarization to receive microcell addressed packets during commissioning and operation.

Table A.4: Downlink polarization

Cell ID	polarization	ation Cell ID polarizati		
1	LHCP	57	LHCP	
2	LHCP	58	RHCP	
3	LHCP	59	LHCP	
4	RHCP	60	RHCP	
5	LHCP	61	LHCP	
6	RHCP	62	RHCP	
7	RHCP	63	LHCP	
8	RHCP	64	RHCP	
9	LHCP	65	LHCP	
10	RHCP	66	RHCP	
11	LHCP	67	LHCP	
12	RHCP	68	RHCP	
13	LHCP	69	LHCP	
14	RHCP	70	RHCP	
15	LHCP	71	LHCP	
16	RHCP	72	RHCP	
17	RHCP		LHCP	
18	LHCP	73 74	RHCP	
	RHCP		LHCP	
19	LHCP	75 76	RHCP	
20		76		
21	RHCP	77	LHCP	
22	LHCP	78	RHCP	
23	RHCP	79	LHCP	
24	LHCP	80	RHCP	
25	RHCP	81	LHCP	
26	LHCP	82	RHCP	
27	RHCP	83	LHCP	
28	LHCP	84	RHCP	
29	RHCP	85	LHCP	
30	LHCP	86	RHCP	
31	RHCP	87	LHCP	
32	LHCP	88	RHCP	
33	LHCP	89	LHCP	
34	LHCP	90	RHCP	
35	RHCP	91	RHCP	
36	LHCP	92	LHCP	
37	RHCP	93	RHCP	
38	LHCP	94	LHCP	
39	RHCP	95	RHCP	
40	LHCP	96	LHCP	
41	RHCP	97	RHCP	
42	LHCP	98	LHCP	
43	RHCP	99	RHCP	
44	LHCP	100	LHCP	
45	RHCP	101	RHCP	
46	RHCP	102	RHCP	
47	LHCP	103	LHCP	
48	RHCP	104	RHCP	
49	LHCP	105	LHCP	
50	RHCP	106	RHCP	
51	LHCP	107	LHCP	
52	RHCP	108	RHCP	
53	LHCP	109	LHCP	
54	RHCP	110	LHCP	
55	LHCP	111	RHCP	
56	RHCP	112	RHCP	
		·		

Annex B (informative): Bibliography

ETSI TR 101 984: "Satellite Earth Stations and Systems (SES); Broadband Satellite Multimedia; Services and Architectures".

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ETSI TS 102 188-2: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 2: Frame structure".

ETSITS 102 188-3: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 3: Channel coding".

ETSITS 102 188-4: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 4: Modulation".

ETSITS 102 188-5: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 5: Radio transmission and reception".

ETSITS 102 188-7: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; Physical layer specification; Part 7: Synchronization".

ETSITS 102 189-2: "Satellite Earth Stations and Systems (SES); Regenerative Satellite Mesh - A (RSM-A) air interface; MAC/SLC layer specification; Part 2: MAC layer".

History

Document history				
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